

Symmetry Breaking and Synchrony Breaking

Martin Golubitsky
Department of Mathematics
Mathematical Biosciences Institute
Ohio State

Why Study Patterns I

- Patterns are **surprising** and **pretty**

Mud Plains



Leopard Spots



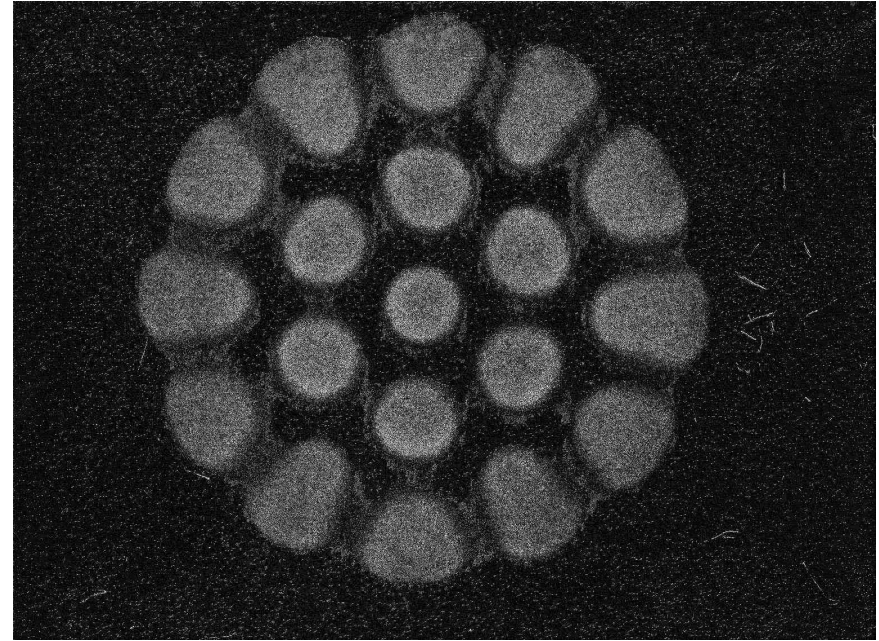
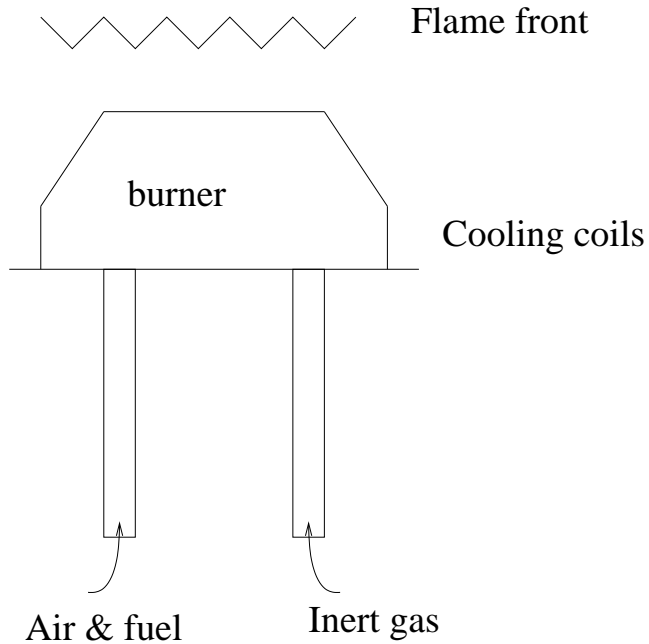
Sand Dunes in Namibian Desert



Zebra Stripes



Porous Plug Burner Flames (Gorman)



- **Dynamic patterns**
- A film in two parts
 - rotating patterns
 - standing patterns

Why Study Patterns II

- 1) Patterns are surprising and pretty
- 2) Science behind patterns

Columnar Joints on Staffa near Mull



Columns along Snake River

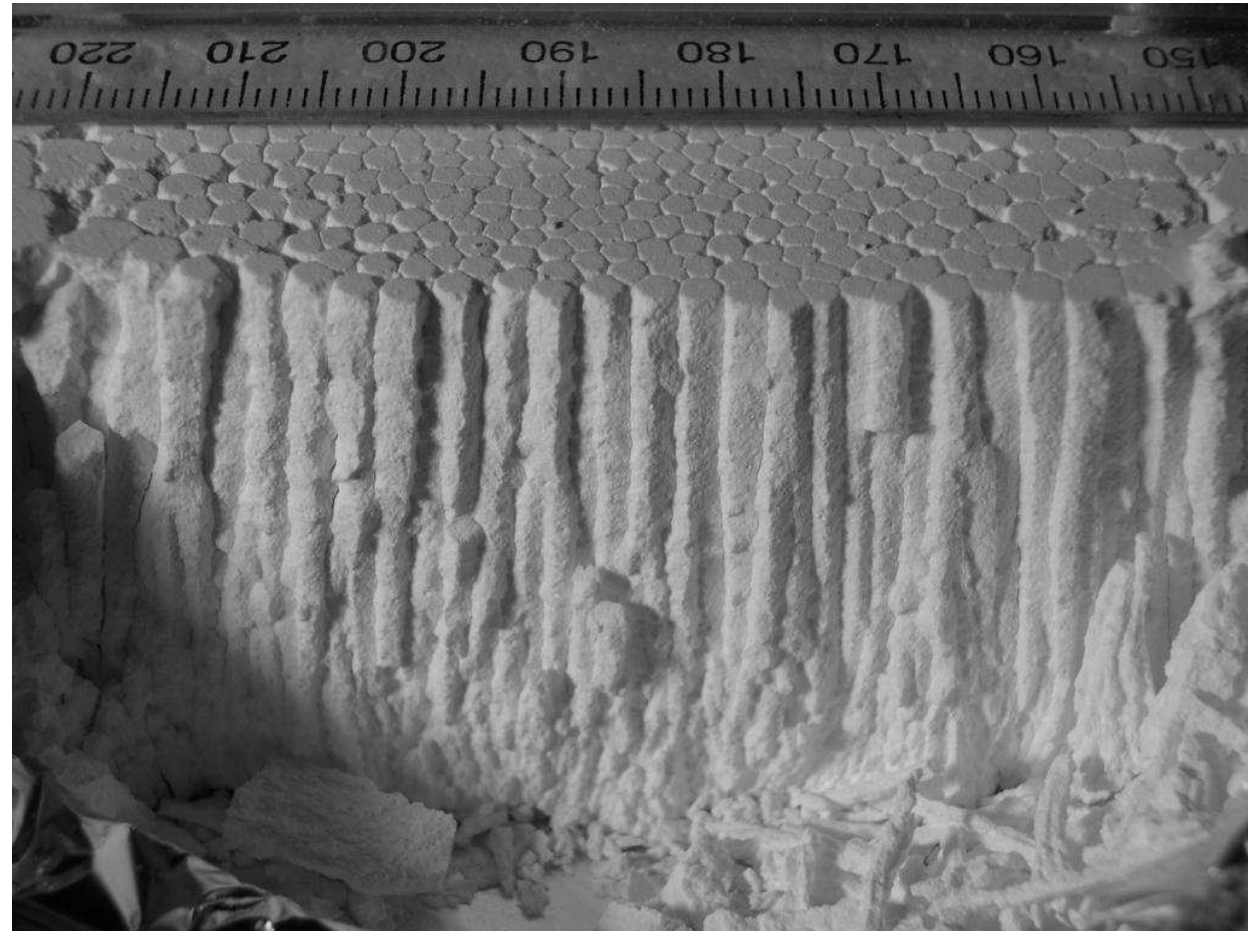
Snake River in Oregon



Irish Giants Causeway



Experiment on Corn Starch



Goehring and Morris, 2005

Why Study Patterns III

- 1) Patterns are surprising and pretty
- 2) Science behind patterns
- 3) **Change in patterns provide tests for models**

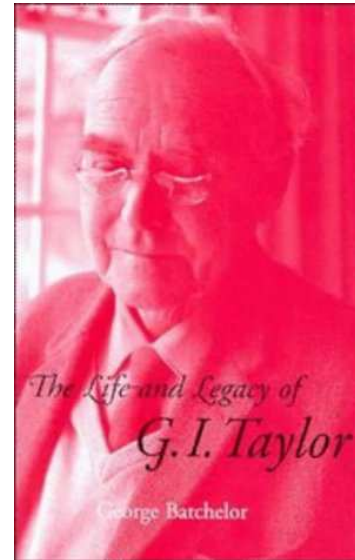
A Brief History of Navier-Stokes

Navier-Stokes equations for an incompressible fluid

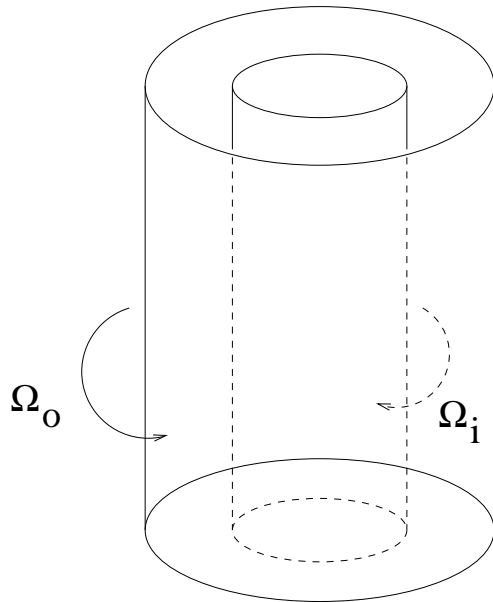
$$\begin{aligned}u_t &= \nu \nabla^2 u - (u \cdot \nabla)u - \frac{1}{\rho} \nabla p \\ 0 &= \nabla \cdot u\end{aligned}$$

u = velocity vector ρ = mass density
 p = pressure ν = kinematic viscosity

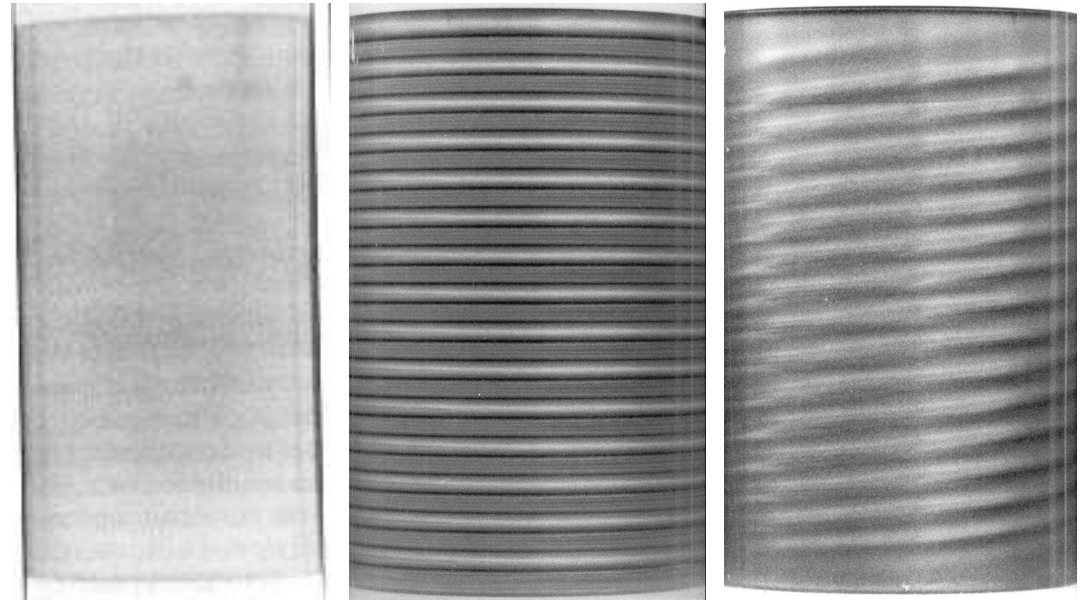
● Navier (1821); Stokes (1856); Taylor (1923)



The Couette Taylor Experiment



Andereck, Liu, and Swinney (1986)



Couette

Taylor

Spiral

time independent

time periodic

- Ω_i = speed of inner cylinder

- Ω_o = speed of outer cylinder

G.I. Taylor: Theory & Experiment (1923)

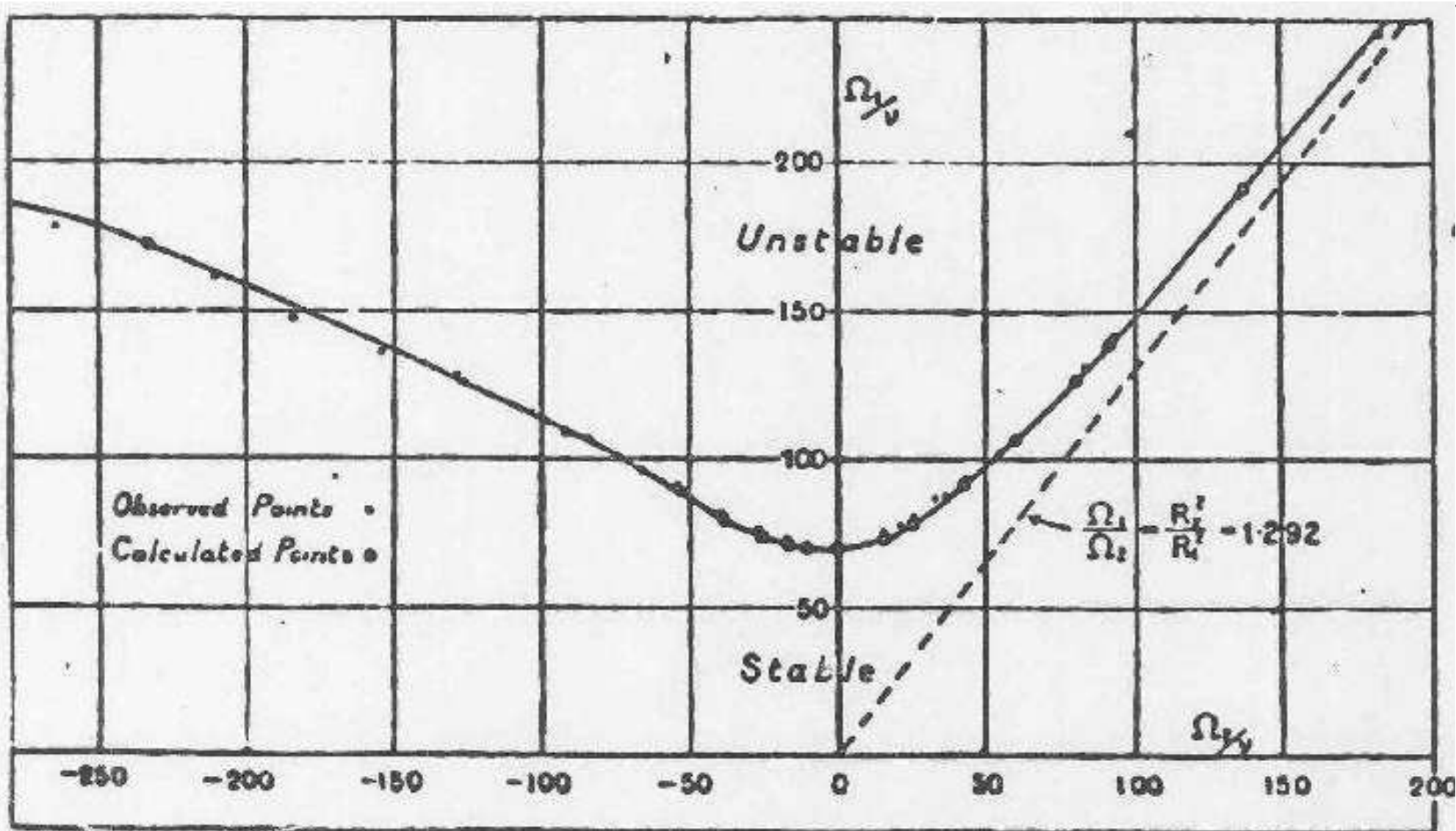


Fig. 18. Comparison between observed and calculated speeds at which instability first appears;

Why Study Patterns IV

- 1) Patterns are surprising and pretty
- 2) Science behind patterns
- 3) Change in patterns provide tests for models
- 4) **Model independence**

Mathematics provides menu of patterns

Planar Symmetry-Breaking

- **Euclidean symmetry**: translations, rotations, reflections
- **Symmetry-breaking** from translation invariant state in planar systems with **Euclidean symmetry** leads to
 - **Stripes**: invariant under translation in one direction
Sand dunes, zebra
 - **Spots**: states centered at lattice points
mud plains, leopard

Circle Symmetry-Breaking Oscillation

- There exist **two** types of **time-periodic** solutions near a circularly symmetric equilibrium
 - **Rotating waves:**
Time evolution is the same as spatial rotation
 - **Standing waves:**
Fixed lines of symmetry for all time
- Examples: Gorman's flame experiments
 - PDE systems on interval with periodic boundary conditions

Primer on Steady-State Bifurcation

- Solve $\dot{x} = f(x, \lambda) = 0$ where $f : \mathbf{R}^n \times \mathbf{R} \rightarrow \mathbf{R}^n$
- Local theory: Assume $f(0, 0) = 0$ – find solns near $(0, 0)$
- If $J = (d_x f)_{0,0}$ **nonsingular**, IFT implies unique soln $x(\lambda)$
- Bifurcation of steady states $\iff \ker J \neq \{0\}$

Equivariant Steady-State Bifurcation

Let $\gamma : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be linear

- γ is a symmetry iff $\gamma(\text{soln}) = \text{soln}$ iff $f(\gamma x, \lambda) = \gamma f(x, \lambda)$
- Chain rule $\implies J\gamma = \gamma J \implies \ker J$ is γ -invariant
- **Theorem:** Fix Γ . Generically $\ker J$ is an **absolutely irreducible** representation of Γ
i.e. only commuting matrices are **multiples of identity**
- Reduction implies that there is a unique steady-state bifurcation theory for each absolutely irreducible rep

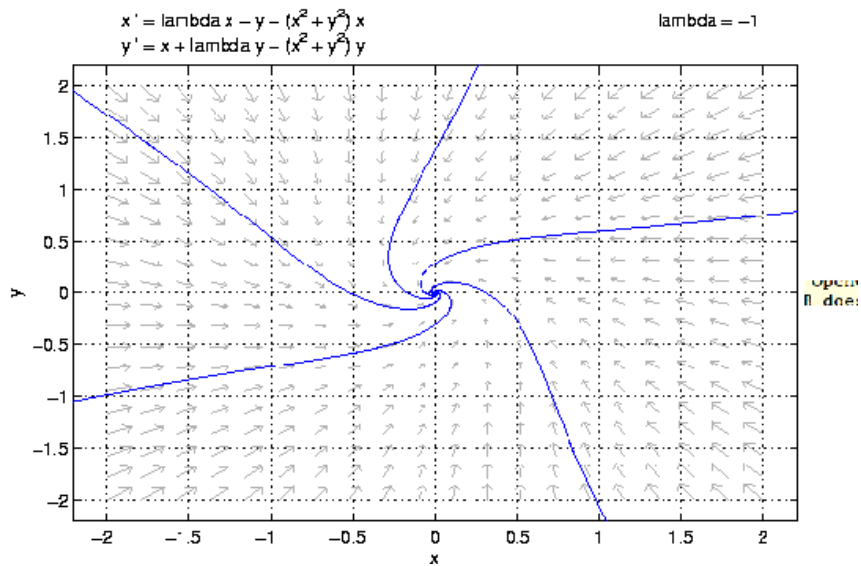
Primer on Hopf Bifurcation

$$\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} \lambda & 1 \\ -1 & \lambda \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} - (x^2 + y^2) \begin{bmatrix} x \\ y \end{bmatrix}$$

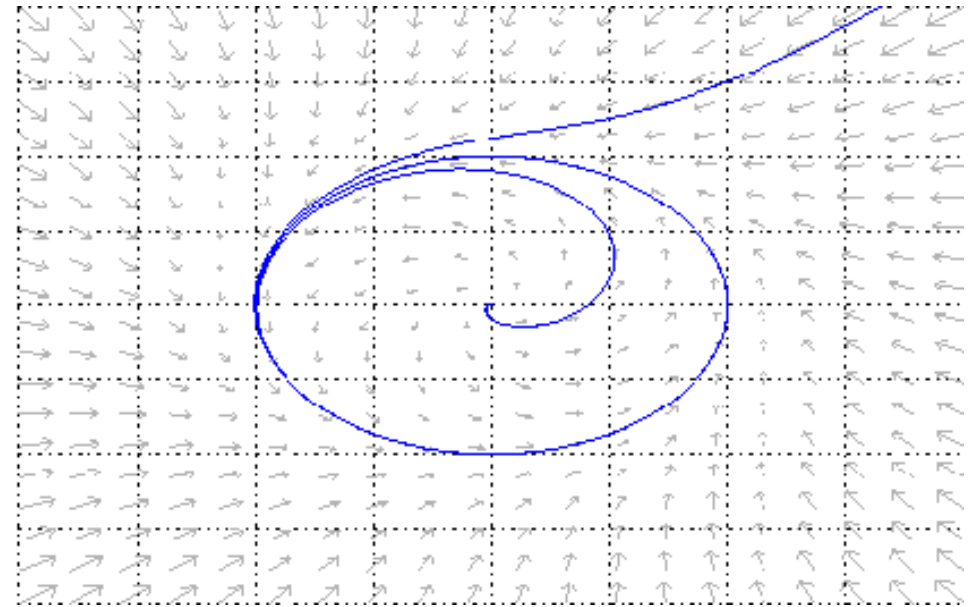
Origin is an equilibrium **for all values** of λ

Primer on Hopf Bifurcation

$$\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} \lambda & 1 \\ -1 & \lambda \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} - (x^2 + y^2) \begin{bmatrix} x \\ y \end{bmatrix}$$



$$\lambda = -1$$



$$\lambda = 1$$

Primer on Hopf Bifurcation

$$\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} \lambda & 1 \\ -1 & \lambda \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} - (x^2 + y^2) \begin{bmatrix} x \\ y \end{bmatrix}$$

- Origin goes from **spiral sink** to **spiral source** as $\lambda \nearrow 0$
- Let $r^2 = x^2 + y^2$. Then $\dot{r} = (\lambda - r^2)r$
 - 1) Unique branch of **periodic trajectories** (for $\lambda > 0$)
 - 2) **Amplitude growth** of periodic solution is $\lambda^{\frac{1}{2}}$

Primer on Hopf Bifurcation

$$\begin{bmatrix} \dot{x} \\ \dot{y} \end{bmatrix} = \begin{bmatrix} \lambda & 1 \\ -1 & \lambda \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} - (x^2 + y^2) \begin{bmatrix} x \\ y \end{bmatrix}$$

- Origin goes from **spiral sink** to **spiral source** as $\lambda \nearrow 0$
- Let $r^2 = x^2 + y^2$. Then $\dot{r} = (\lambda - r^2)r$
 - 1) Unique branch of **periodic trajectories** (for $\lambda > 0$)
 - 2) **Amplitude growth** of periodic solution is $\lambda^{\frac{1}{2}}$

Hopf Theorem: Generically (1) and (2) hold when **pair of eigenvalues of Jacobian** on imaginary axis

Primer on Equivariant Hopf Bifurcation

- Hopf bifurcation $\iff J$ has eigenvalues $\pm\omega i$
- Suppose

$$\mathbf{R}^n = V_1 \oplus \cdots \oplus V_\ell$$

where V_j are **distinct** absolutely irreducible

Then

- $J : V_j \rightarrow V_j$ is a **real** multiple of I_{V_j}
- all eigenvalues of J are **real**
- Hopf bifurcation is **not** possible.

Primer on Equivariant Hopf Bifurcation

- Hopf bifurcation $\iff J$ has eigenvalues $\pm\omega i$
- Representation on E^c is Γ -simple iff either
 - $E^c = V \oplus V$ where V is absolutely irreducible, or
 - Γ acts nonabsolutely irreducibly on E^c
- **Theorem:** Fix Γ . At Hopf bifurcation, generically, Γ acts Γ -simply on center subspace E^c
- Reduction implies that there is a unique Hopf bifurcation theory for each irreducible rep

Spatiotemporal Symmetries

- What kind of symmetries do periodic solutions have?
- Let $x(t)$ be a **time-periodic** solution
 - $K = \{\gamma \in \Gamma : \gamma x(t) = x(t)\}$ **space symmetries**
 - $H = \{\gamma \in \Gamma : \gamma\{x(t)\} = \{x(t)\}\}$ **spatiotemporal symms**
- $\gamma \in H \implies \theta \in \mathbf{S}^1$ such that $\gamma x(t) = x(t + \theta)$

Spatiotemporal Symmetries

- Let $x(t)$ be a time-periodic solution
 - $K = \{\gamma \in \Gamma : \gamma x(t) = x(t)\}$ **space symmetries**
 - $H = \{\gamma \in \Gamma : \gamma\{x(t)\} = \{x(t)\}\}$ **spatiotemporal symm's**
- $\gamma \in H \implies \theta \in \mathbf{S}^1$ such that $\gamma x(t) = x(t + \theta)$
- **Example:** $\Gamma = \mathbf{O}(2)$; $E^c = \mathbf{R}^2 \oplus \mathbf{R}^2$

Two periodic solutions types emanate from bifurcation

- **rotating waves:** $H = \mathbf{SO}(2)$; $K = \mathbf{1}$
- **standing waves:** $H = \mathbf{Z}_2(\kappa) \oplus \mathbf{Z}_2(R_\pi)$; $K = \mathbf{Z}_2(\kappa)$,
where κ is a reflection

Spatiotemporal Symmetries

- Let $x(t)$ be a time-periodic solution
 - $K = \{\gamma \in \Gamma : \gamma x(t) = x(t)\}$ **space symmetries**
 - $H = \{\gamma \in \Gamma : \gamma\{x(t)\} = \{x(t)\}\}$ **spatiotemporal symm's**
- $\gamma \in H \implies \theta \in \mathbf{S}^1$ such that $\gamma x(t) = x(t + \theta)$
- H/K is **cyclic** or **\mathbf{S}^1** since
 $\gamma \mapsto \theta$ is a homomorphism with kernel K

Summary on Pattern Formation

- There is a codimension one steady-state bifurcation from a group invariant equilibrium corresponding to each **absolutely irreducible** subspace

There is a codimension one Hopf bifurcation from a group invariant equilibrium corresponding to each **irreducible** subspace

Summary on Pattern Formation

- There is a codimension one steady-state bifurcation from a group invariant equilibrium corresponding to each **absolutely irreducible** subspace

There is a codimension one Hopf bifurcation from a group invariant equilibrium corresponding to each **irreducible** subspace

- Mathematics leads to a **menu of patterns**

This menu is **model independent**

Physics & Biology **choose** from that menu

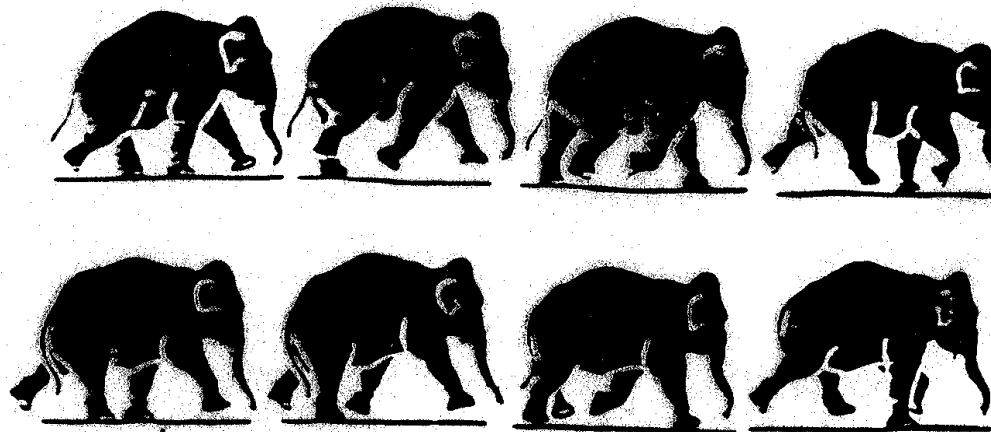
This choice is **model dependent**

Quadruped Gaits

- **Bound** of the Siberian Souslik

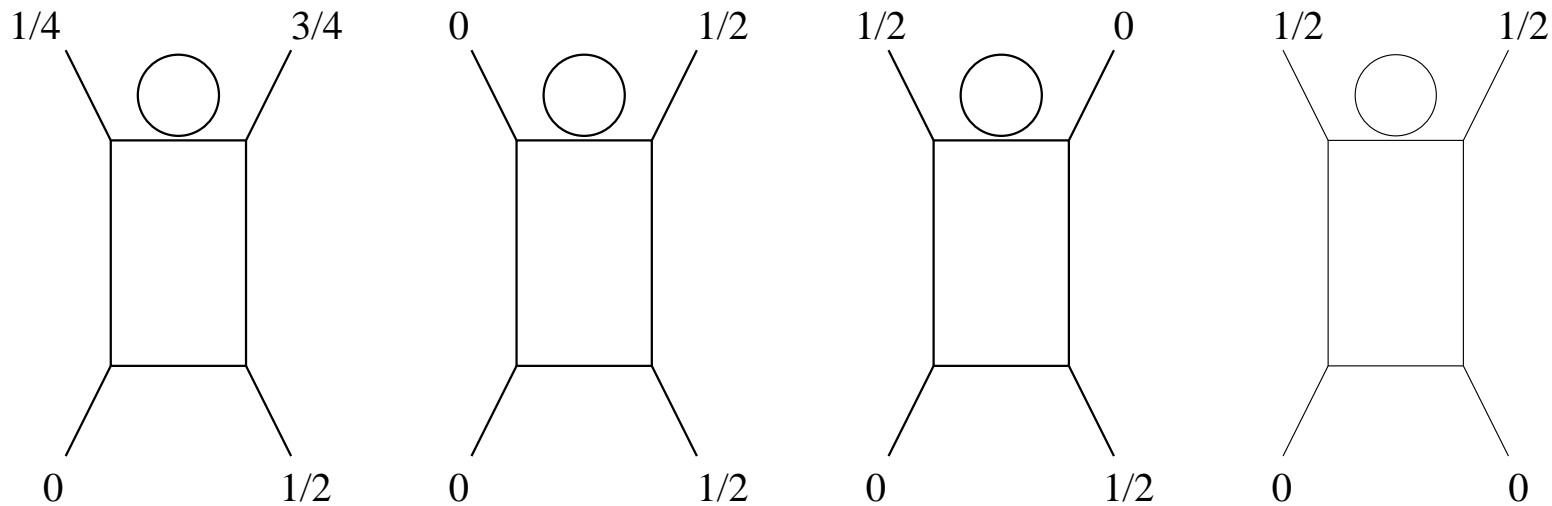


- **Amble** of the Elephant



- **Trot** of the Horse

Standard Gait Phases

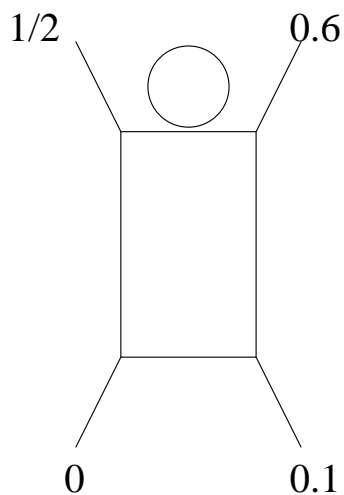


WALK

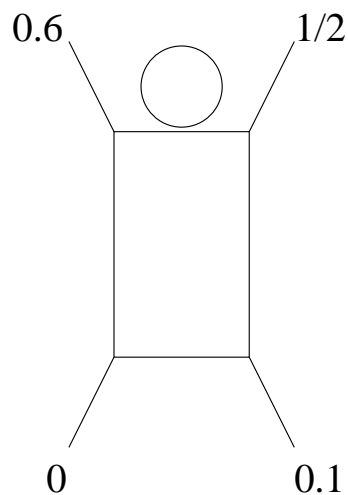
PACE

TROT

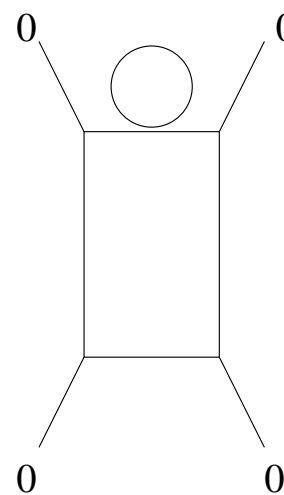
BOUND



TRANSVERSE
GALLOP

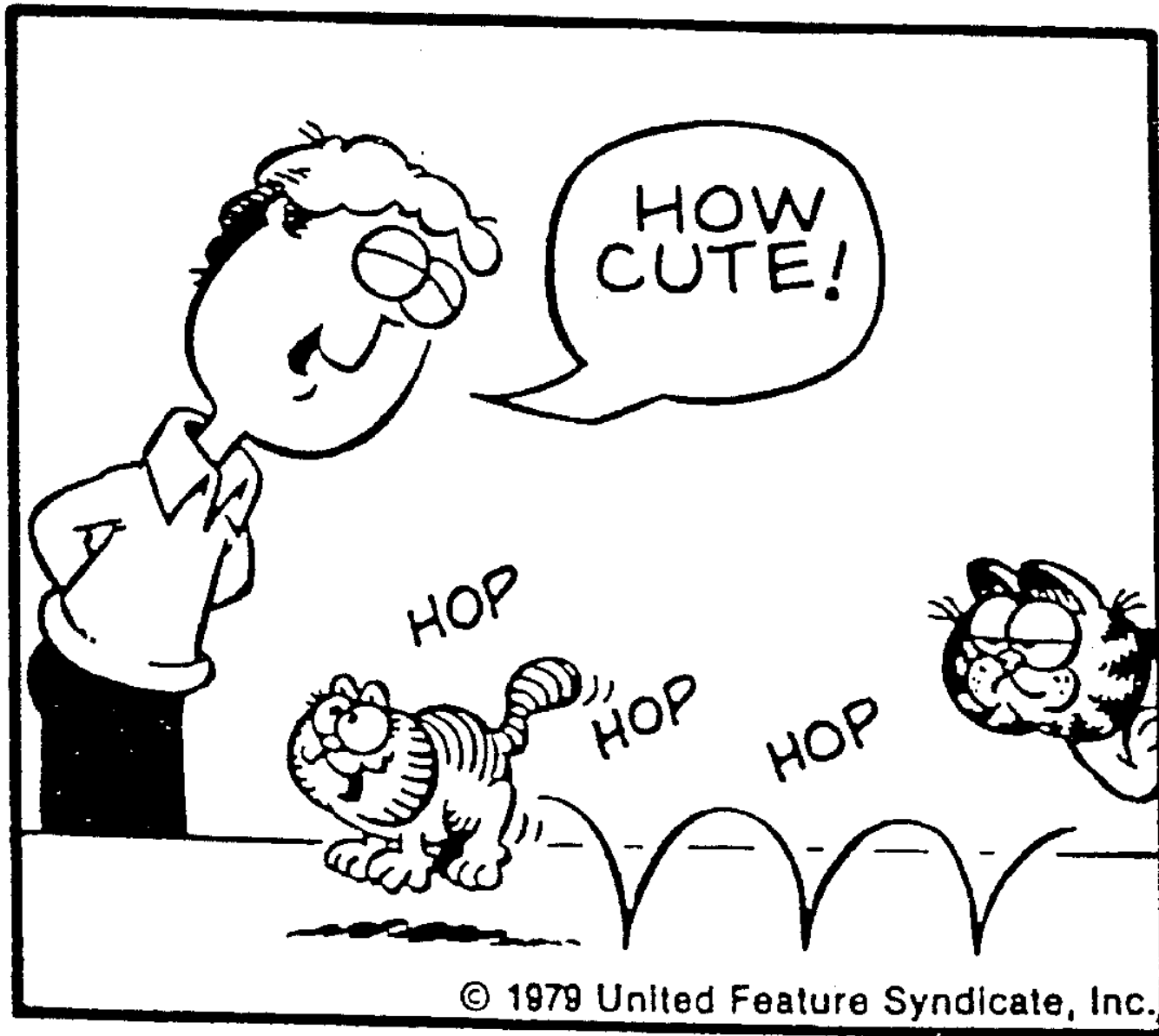


ROTARY
GALLOP



PRONK

The Pronk



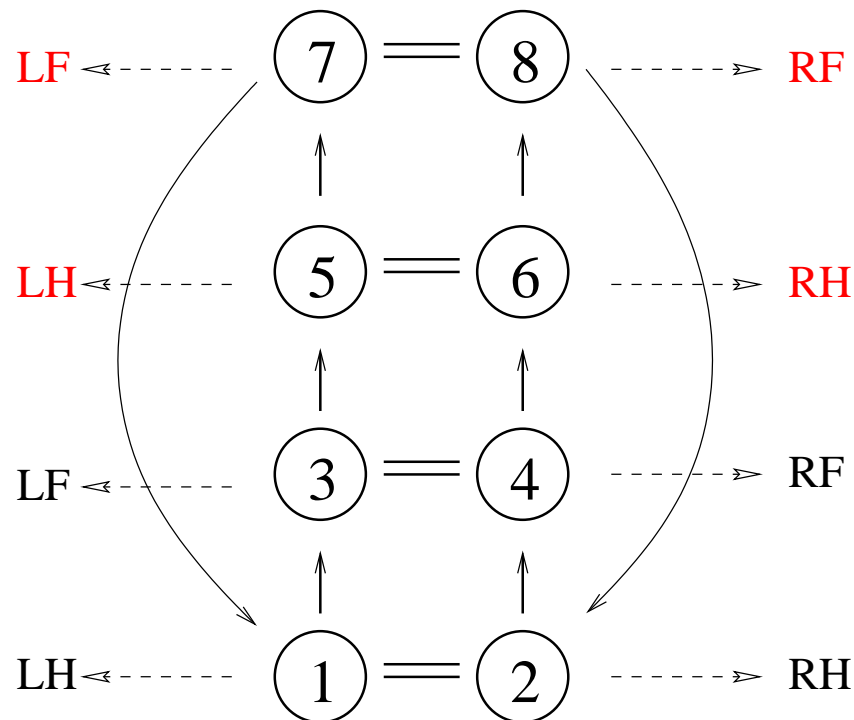
Gait Symmetries

Gait	Spatio-temporal symmetries
Trot	(Left/Right, $\frac{1}{2}$) and (Front/Back, $\frac{1}{2}$)
Pace	(Left/Right, $\frac{1}{2}$) and (Front/Back, 0)
Walk	(Figure Eight, $\frac{1}{4}$)

- **Three gaits are different**
- Assumption: **There is a network in the nervous system that produces the characteristic rhythms of each gait**
- Design **simplest** network to produce **walk**, **trot**, and **pace**

Central Pattern Generators (CPG)

- Use gait symmetries to construct coupled network
 - 1) **walk** \implies four-cycle ω in symmetry group
 - 2) **pace** or **trot** \implies transposition κ in symmetry group
- Simplest network has $\mathbf{Z}_4(\omega) \times \mathbf{Z}_2(\kappa)$ symmetry

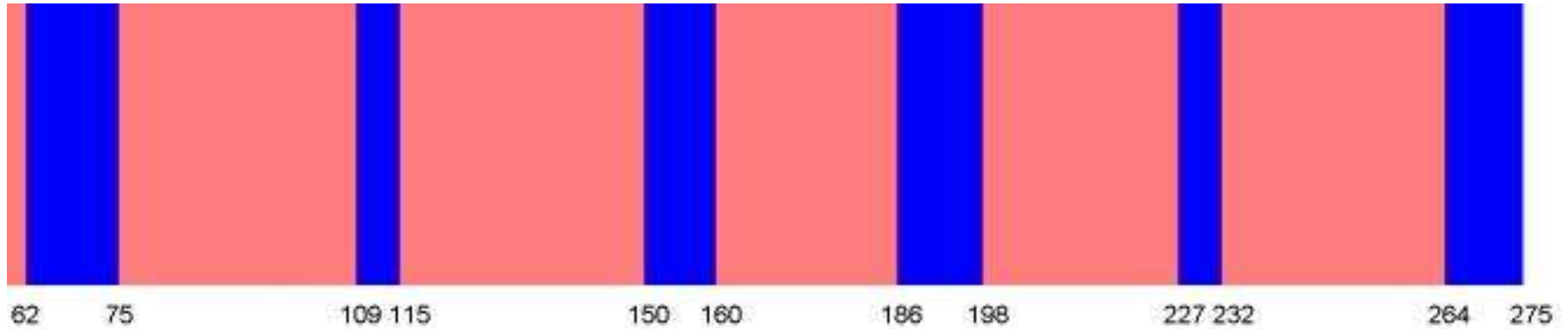


Primary Gaits: Hopf from Stand

Six Irreducible Representations of $\mathbf{Z}_4(\omega) \times \mathbf{Z}_2(\kappa)$

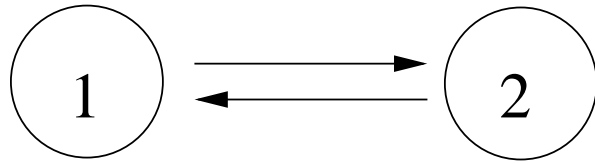
Phase Diagram	Gait
$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$	pronk
$\begin{pmatrix} 0 & \frac{1}{2} \\ 0 & \frac{1}{2} \end{pmatrix}$	pace
$\begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$	trot
$\begin{pmatrix} 0 & 0 \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$	bound
$\begin{pmatrix} \pm \frac{1}{4} & \pm \frac{3}{4} \\ 0 & \frac{1}{2} \end{pmatrix}$	walk $^\pm$
$\begin{pmatrix} 0 & 0 \\ \pm \frac{1}{4} & \pm \frac{1}{4} \end{pmatrix}$	jump $^\pm$

The Jump



- Average Right Rear to Right Front = 31.2 frames
- Average Right Front to Right Rear = 11.4 frames
- $\frac{31.2}{11.4} = 2.74$

Two Identical Cells



$$\dot{x}_1 = f(x_1, x_2)$$

$$\dot{x}_2 = f(x_2, x_1)$$

where $x_1, x_2 \in \mathbf{R}^k$

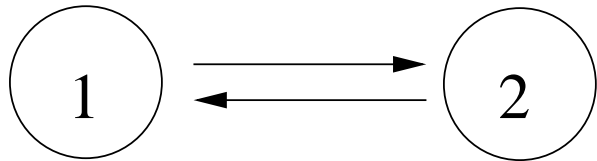
- Time-periodic solutions exist **robustly** where two cells oscillate **in phase**

$$x_2(t) = x_1(t)$$

- Time-periodic solutions exist **robustly** where two cells oscillate **half-period out of phase**

$$x_2(t) = x_1\left(t + \frac{1}{2}\right)$$

Two Identical Cells

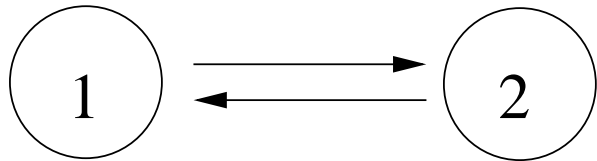


$$\begin{aligned}\dot{x}_1 &= f(x_1, x_2, \lambda) \\ \dot{x}_2 &= f(x_2, x_1, \lambda) \quad x_1, x_2 \in \mathbf{R}^k \\ 0 &= f(0, 0, \lambda)\end{aligned}$$

• $J(\lambda) = \begin{bmatrix} \alpha(\lambda) & \beta(\lambda) \\ \beta(\lambda) & \alpha(\lambda) \end{bmatrix}; \begin{bmatrix} x \\ x \end{bmatrix}, \begin{bmatrix} x \\ -x \end{bmatrix}$ invariant subsp's

eigenvalues of J are eigenvalues of $\alpha + \beta$ and $\alpha - \beta$

Two Identical Cells



$$\begin{aligned}\dot{x}_1 &= f(x_1, x_2, \lambda) \\ \dot{x}_2 &= f(x_2, x_1, \lambda) \quad x_1, x_2 \in \mathbf{R}^k \\ 0 &= f(0, 0, \lambda)\end{aligned}$$

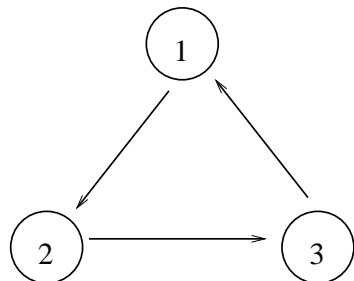
• $J(\lambda) = \begin{bmatrix} \alpha(\lambda) & \beta(\lambda) \\ \beta(\lambda) & \alpha(\lambda) \end{bmatrix}$; $\begin{bmatrix} x \\ x \end{bmatrix}$, $\begin{bmatrix} x \\ -x \end{bmatrix}$ invariant subsp's

eigenvalues of J are eigenvalues of $\alpha + \beta$ and $\alpha - \beta$

• $\alpha + \beta$ critical: **synchronous** periodic solutions

• $\alpha - \beta$ critical: periodic solutions where two cells are **half-period out of phase** $x_2(t) = x_1(t + \frac{T}{2})$

Three-Cell Unidirectional Ring: $\Gamma = \mathbf{Z}_3$

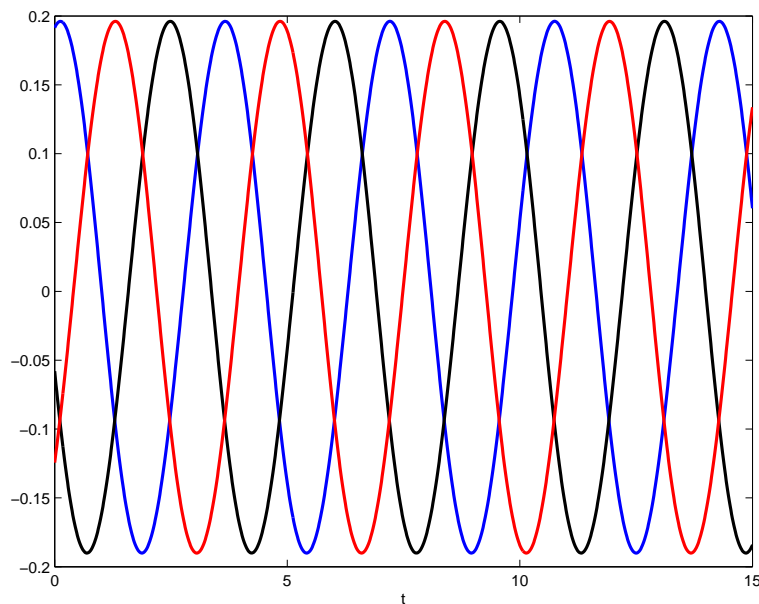
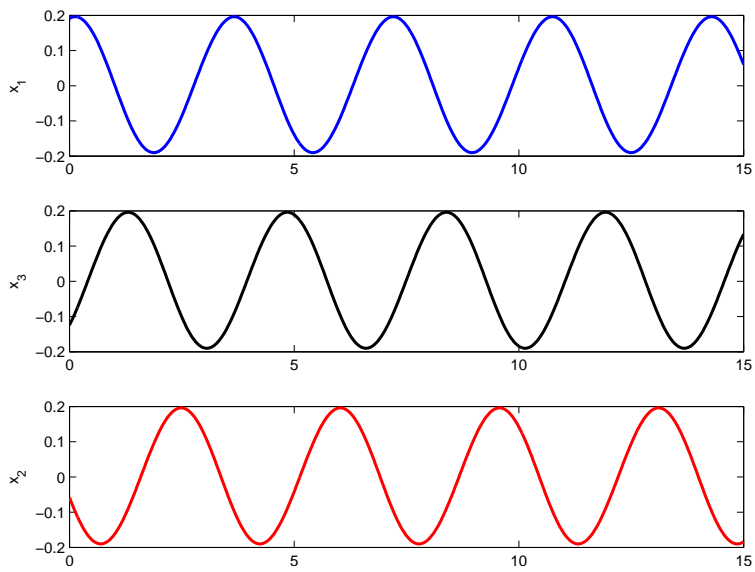


$$\dot{x}_1 = f(x_1, x_3)$$

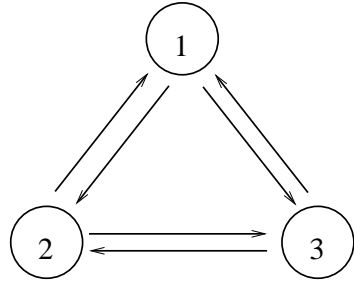
$$\dot{x}_2 = f(x_2, x_1)$$

$$\dot{x}_3 = f(x_3, x_2)$$

● Discrete rotating waves



Three-Cell Bidirectional Ring: $\Gamma = S_3$



$$\dot{x}_1 = f(x_1, x_2, x_3)$$

$$\dot{x}_2 = f(x_2, x_3, x_1) \quad f(x_2, x_1, x_3) = f(x_2, x_3, x_1)$$

$$\dot{x}_3 = f(x_3, x_1, x_2)$$

● Discrete rotating waves

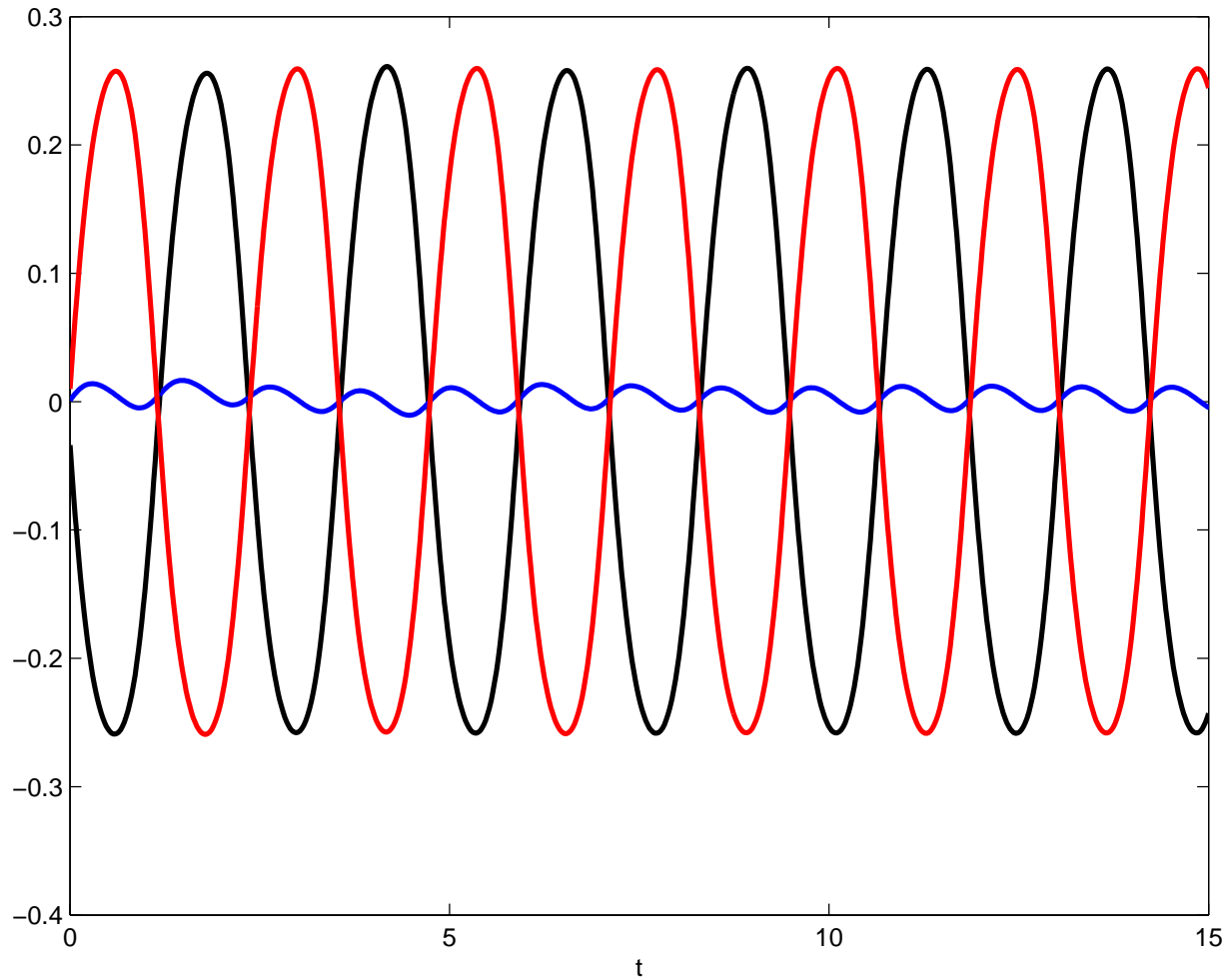
In-phase periodic solutions: $x_3(t) = x_1(t)$

Out-of-phase periodic solutions:

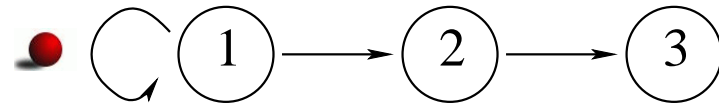
$$x_3(t) = x_1\left(t + \frac{T}{2}\right) \quad \text{and} \quad x_2(t) = x_2\left(t + \frac{T}{2}\right)$$

G. and Stewart (1986)

Bidirectional Three-Cell Ring (2)



Three-Cell Feed-Forward Network



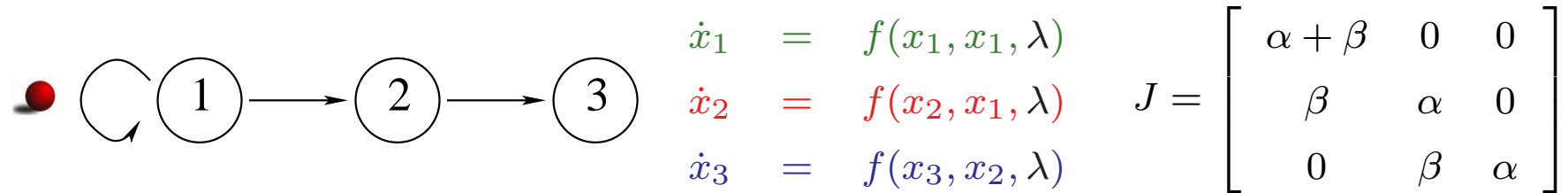
$$\dot{x}_1 = f(x_1, x_1, \lambda)$$

$$\dot{x}_2 = f(x_2, x_1, \lambda)$$

$$\dot{x}_3 = f(x_3, x_2, \lambda)$$

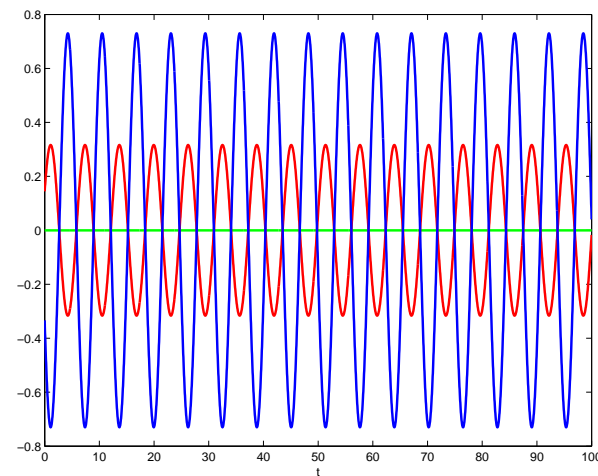
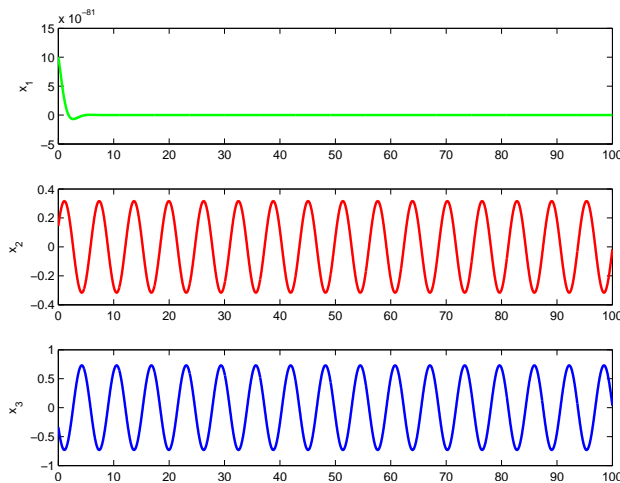
$$J = \begin{bmatrix} \alpha + \beta & 0 & 0 \\ \beta & \alpha & 0 \\ 0 & \beta & \alpha \end{bmatrix}$$

Three-Cell Feed-Forward Network



- Network supports solution by Hopf bifurcation where $x_1(t)$ **equilibrium** $x_2(t), x_3(t)$ **time periodic**

- $x_2(t) \approx \lambda^{1/2}$ $x_3(t) \approx \lambda^{1/6}$



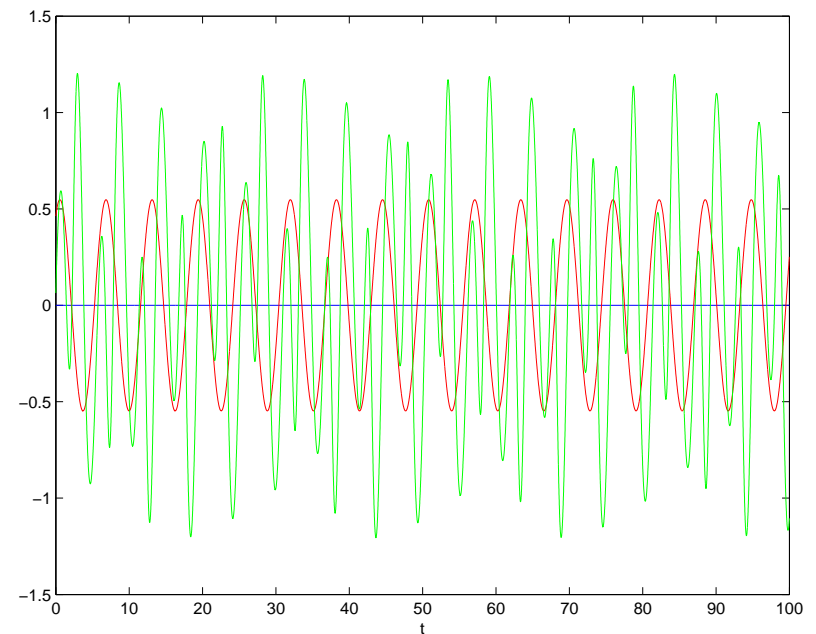
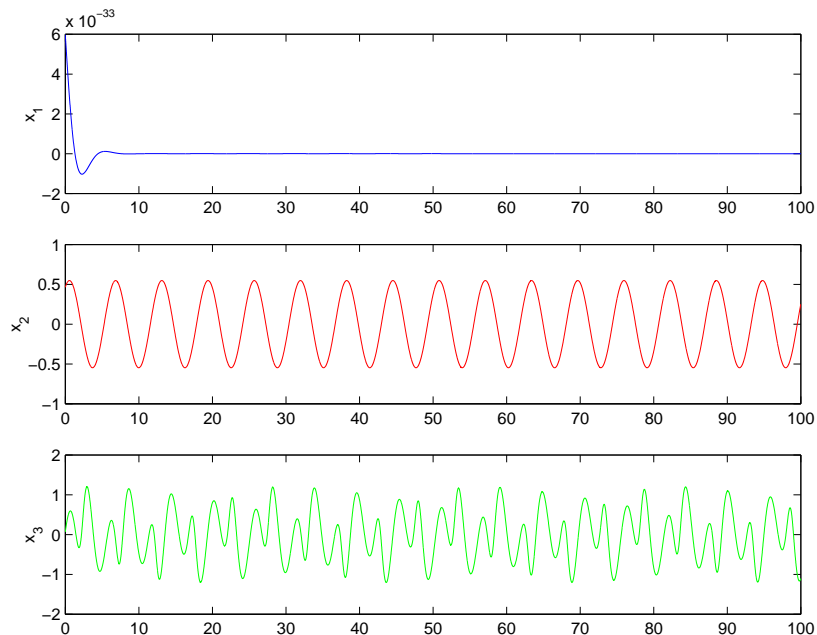
G., Nicol, and Stewart (2004); Elmhirst and G. (2005)

Quasiperiodic Solutions in FF Network

Network supports solution where

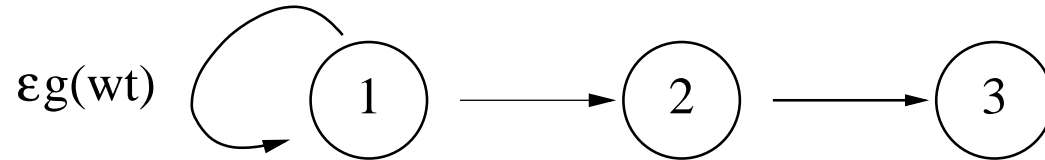
$x_1(t)$ equilibrium, $x_2(t)$ time periodic, $x_3(t)$ quasiperiodic

$$f(y_1, y_2) = (i + 0.3 - |y_1|^2)y_1 - y_2 - 1.83|y_2|^2y_2 + (2.33 + 4.71i)|y_2|^2y_1$$



G., Nicol, and Stewart (2004); Broer and Vegter (2007)

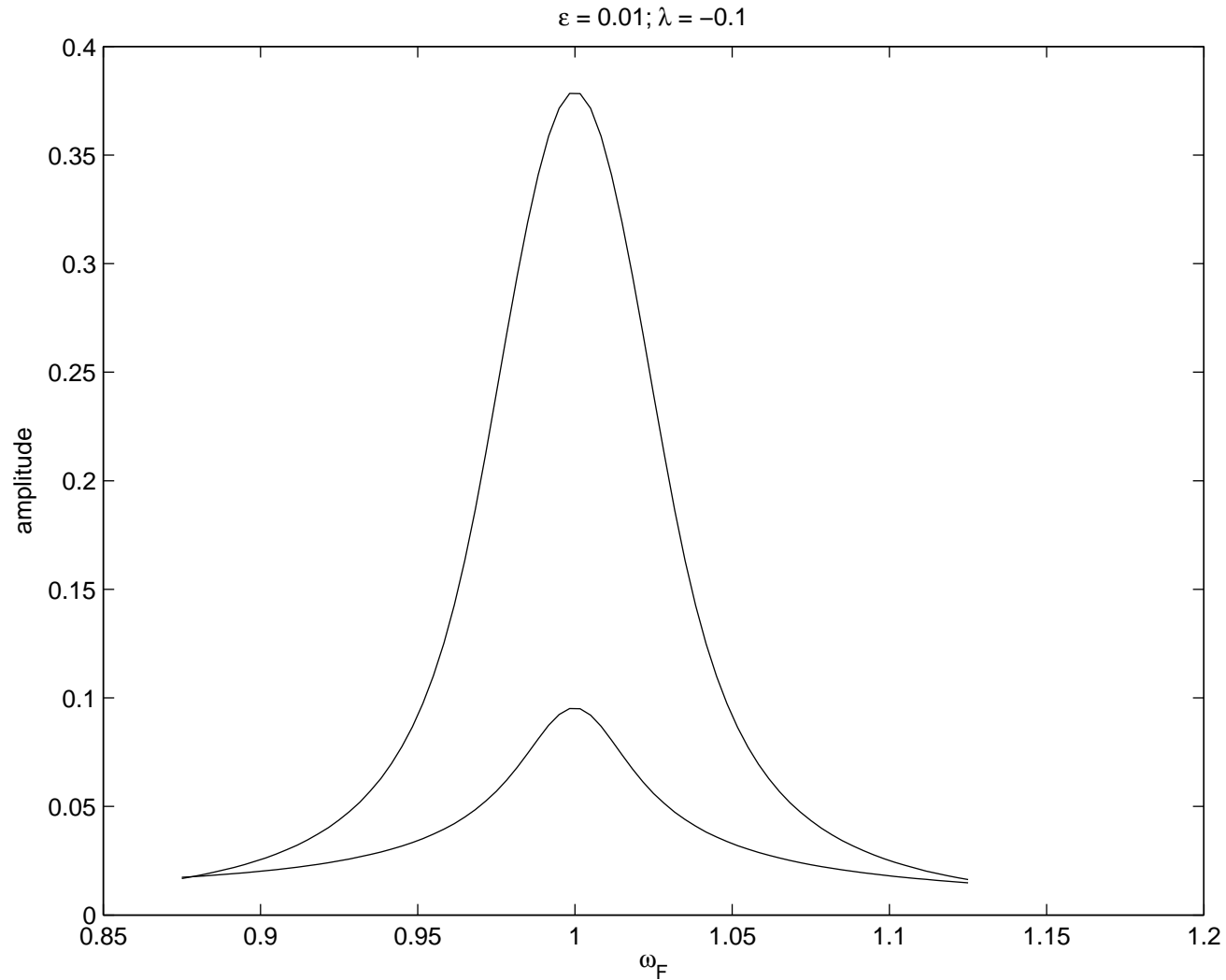
Forced Feed Forward Network



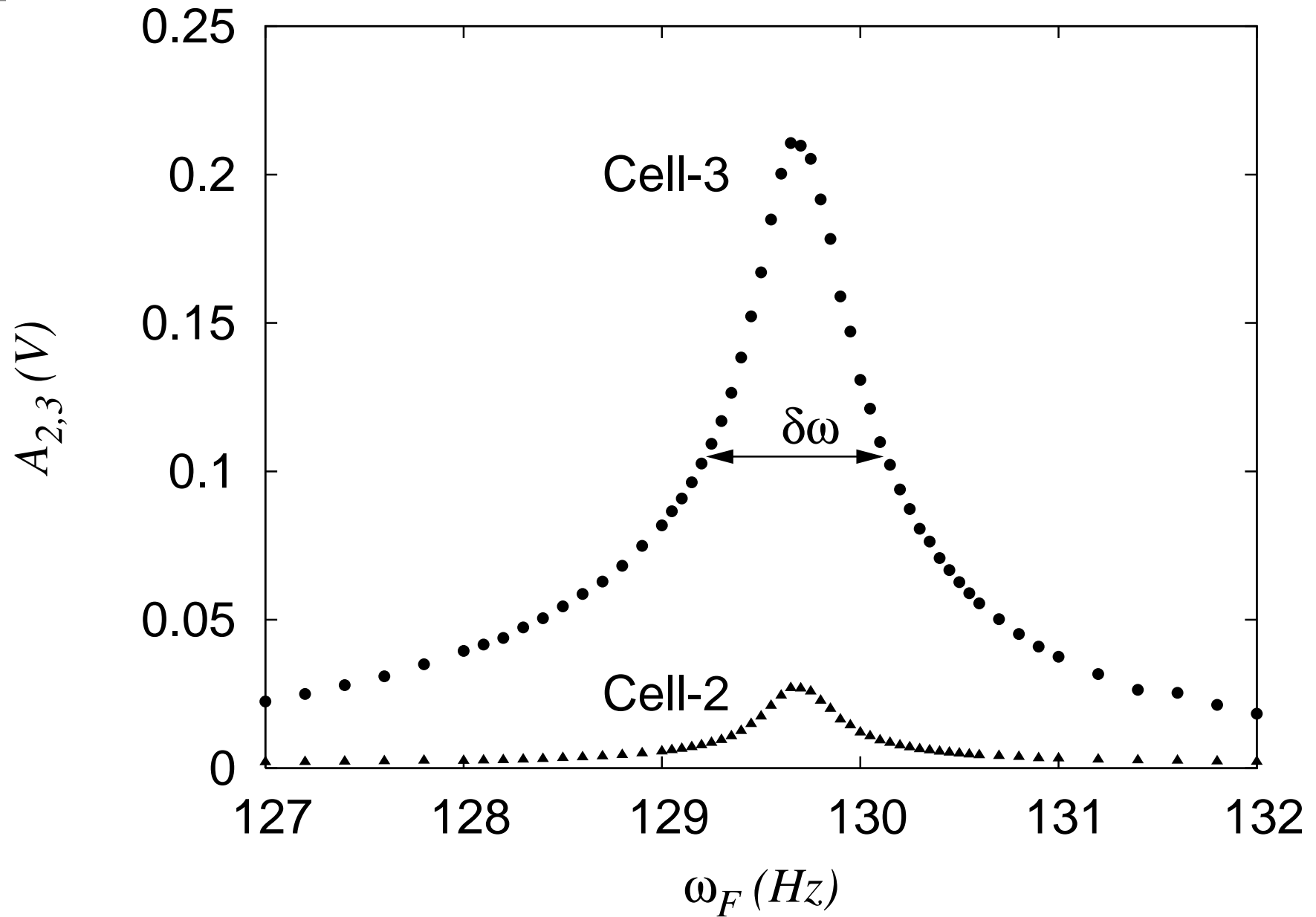
- forcing at **frequency** ω_f and **amplitude** ϵ
- network tuned near Hopf bifurcation with **frequency** ω_h
- $\lambda < 0$ so that equilibrium is stable
- Three parameters: $\lambda, \epsilon, \omega_f - \omega_h$

Numerics with Aronson

$$g(t) = \varepsilon(e^{i\omega_F t} + 2e^{2i\omega_F t} - 0.5e^{3i\omega_F t}) \quad \lambda = -0.1 \quad \varepsilon = 0.01$$



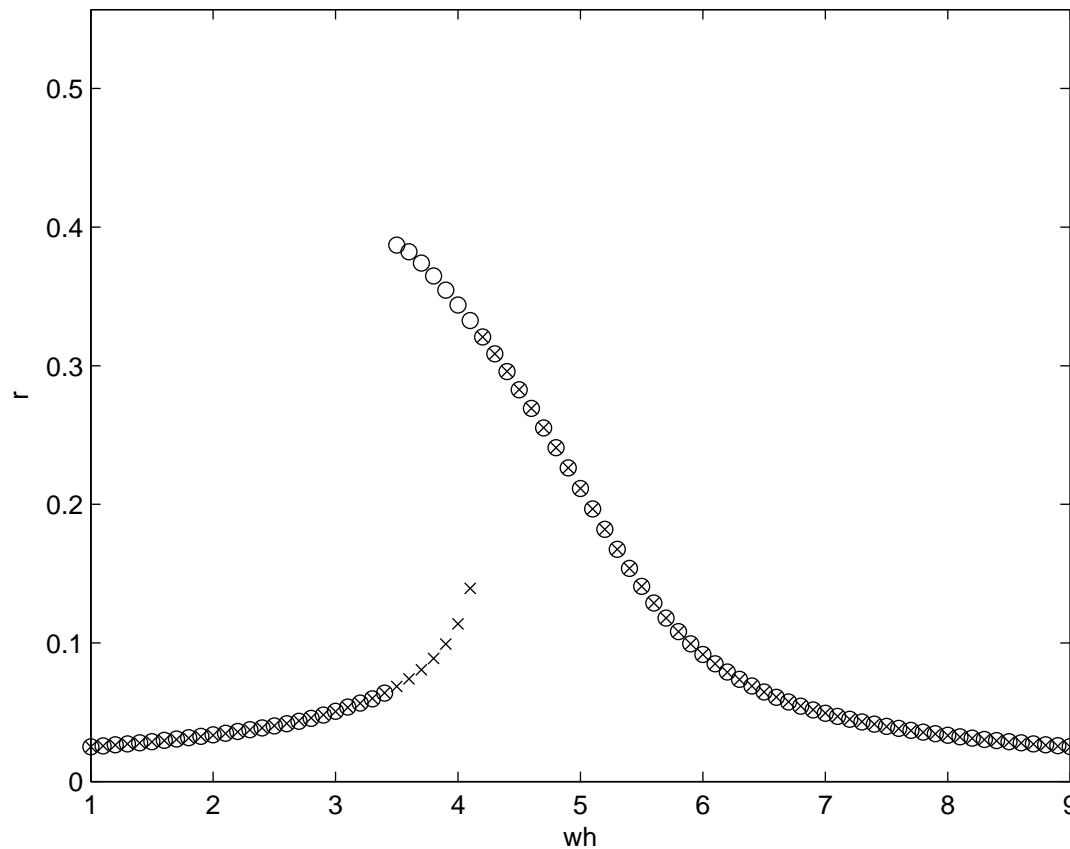
McCullen-Mullin Experiment



More Precisely

• $\omega_f = 5, \lambda = -0.109, \varepsilon = 0.1, \gamma = 10$

• $\dot{z} = (\lambda + \omega_H i - (1 + i\gamma)|z|^2)z + \varepsilon e^{2\pi i \omega_f t}$



Best Guess

- Fix $\lambda < 0$ and $\varepsilon > 0$ near 0
- For all $\gamma > \gamma_c$ there is a region of multiple small amplitude periodic solutions near ω_0 as ω_F is varied
- $\omega_0 \rightarrow \omega_H$ and $\gamma_c \rightarrow \sqrt{3}$ as $\lambda, \varepsilon \rightarrow 0$

Postlethwaite and G. (2008)

Many Thanks To Ian Stewart

Feedforward

Toby Elmhirst	<i>Cook's U</i>
Matt Nicol	<i>Houston</i>
Nick McCullen	<i>Bath</i>
Tom Mullin	<i>Manchester</i>
Don Aronson	<i>Minnesota</i>

Quadrupedal Gaits

Luciano Buono	<i>Oshawa</i>
Jim Collins	<i>Boston U</i>

Coupled Cells

Reiner Lauterbach	<i>Hamburg</i>
Maria Leite	<i>Oklahoma</i>
Marcus Pivato	<i>Trent</i>
Andrew Török	<i>Houston</i>

Pictures of Patterns

Mike Gorman	<i>Houston</i>
Steve Morris	<i>Toronto</i>