
1. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.40.pg

Let S be a set of m vectors in \mathbb{R}^n with $m > n$.
Select the best statement.

- A. The set S is linearly independent, as long as it does not include the zero vector.
- B. The set S is linearly dependent.
- C. The set S is linearly independent, as long as no vector in S is a scalar multiple of another vector in the set.
- D. The set S is linearly independent.
- E. The set S could be either linearly dependent or linearly independent, depending on the case.
- F. none of the above

2. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.41.pg

Let A be a matrix with more rows than columns.
Select the best statement.

- A. The columns of A are linearly independent, as long as no column is a scalar multiple of another column in A .
- B. The columns of A could be either linearly dependent or linearly independent depending on the case.
- C. The columns of A are linearly independent, as long as they does not include the zero vector.
- D. The columns of A must be linearly dependent.
- E. The columns of A must be linearly independent.
- F. none of the above

3. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.42.pg

Let A be a matrix with more columns than rows.
Select the best statement.

- A. The columns of A are linearly independent, as long as they does not include the zero vector.
- B. The columns of A could be either linearly dependent or linearly independent depending on the case.
- C. The columns of A must be linearly dependent.
- D. The columns of A are linearly independent, as long as no column is a scalar multiple of another column in A .
- E. none of the above

4. (1 pt) local/Library/UI/MatrixAlgebra/Euclidean/2.3.43.pg

Let A be a matrix with linearly independent columns.
Select the best statement.

- A. The equation $A\mathbf{x} = \mathbf{0}$ always has nontrivial solutions.
- B. There is insufficient information to determine if such an equation has nontrivial solutions.
- C. The equation $A\mathbf{x} = \mathbf{0}$ has nontrivial solutions precisely when it has more rows than columns.
- D. The equation $A\mathbf{x} = \mathbf{0}$ never has nontrivial solutions.
- E. The equation $A\mathbf{x} = \mathbf{0}$ has nontrivial solutions precisely when it has more columns than rows.
- F. The equation $A\mathbf{x} = \mathbf{0}$ has nontrivial solutions precisely when it is a square matrix.
- G. none of the above

5. (1 pt) local/Library/UI/MatrixAlgebra/Euclidean/2.3.44.pg

Let A be a matrix with linearly independent columns.
Select the best statement.

- A. The equation $A\mathbf{x} = \mathbf{b}$ has a solution for all \mathbf{b} precisely when it has more columns than rows.
- B. The equation $A\mathbf{x} = \mathbf{b}$ always has a solution for all \mathbf{b} .
- C. The equation $A\mathbf{x} = \mathbf{b}$ has a solution for all \mathbf{b} precisely when it is a square matrix.
- D. The equation $A\mathbf{x} = \mathbf{b}$ never has a solution for all \mathbf{b} .
- E. There is insufficient information to determine if $A\mathbf{x} = \mathbf{b}$ has a solution for all \mathbf{b} .
- F. The equation $A\mathbf{x} = \mathbf{b}$ has a solution for all \mathbf{b} precisely when it has more rows than columns.
- G. none of the above

6. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.46.pg

Let $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ be a linearly dependent set of vectors.
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is a linearly independent set of vectors unless $\mathbf{u}_4 = \mathbf{0}$.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ could be a linearly independent or linearly dependent set of vectors depending on the vectors chosen.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly independent set of vectors.

- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is a linearly independent set of vectors unless \mathbf{u}_4 is a linear combination of other vectors in the set.
- E. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly dependent set of vectors.
- F. none of the above

7. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps_1-4/2.3.47.pg

Let $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ be a linearly independent set of vectors. Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is never a linearly independent set of vectors.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ could be a linearly independent or linearly dependent set of vectors depending on the vectors chosen.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is always a linearly independent set of vectors.
- D. none of the above

8. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps_1-4/2.3.49.pg

Let \mathbf{u}_4 be a linear combination of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$. Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ could be a linearly dependent or linearly independent set of vectors depending on the vectors chosen.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is a linearly dependent set of vectors unless one of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is the zero vector.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly independent set of vectors.
- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is never a linearly independent set of vectors.
- E. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is never a linearly dependent set of vectors.
- F. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ could be a linearly dependent or linearly independent set of vectors depending on the vector space chosen.
- G. none of the above

9. (1 pt) Library/Rochester/setLinearAlgebra9Dependence/ur_la_9_7.pg

The vectors

$$v = \begin{bmatrix} -1 \\ 0 \\ 3 \end{bmatrix}, u = \begin{bmatrix} -4 \\ -12 \\ 31+k \end{bmatrix}, \text{ and } w = \begin{bmatrix} -3 \\ -7 \\ 16 \end{bmatrix}.$$

are linearly independent if and only if $k \neq$ _____.

10. (1 pt) Library/TCNJ/TCNJ_LinearIndependence/problem3.pg

If k is a real number, then the vectors $(1, k), (k, 3k + 40)$ are linearly independent precisely when

$$k \neq a, b,$$

where $a =$ ____, $b =$ ____, and $a < b$.

11. (1 pt) Library/Rochester/setLinearAlgebra4InverseMatrix/ur_la_4_2.pg

The matrix $\begin{bmatrix} 4 & -5 \\ -6 & k \end{bmatrix}$ is invertible if and only if $k \neq$ ____.

12. (1 pt) Library/Rochester/setAlgebra34Matrices/scalarmult3.pg

$$\text{If } A = \begin{bmatrix} 1 & -2 & 1 \\ 0 & -4 & -1 \\ 3 & -1 & -2 \end{bmatrix} \text{ and } B = \begin{bmatrix} 4 & -3 & 3 \\ 1 & -2 & 2 \\ 1 & -1 & 2 \end{bmatrix}, \text{ then}$$

$$2A - 3B = \begin{bmatrix} _ & _ & _ \\ _ & _ & _ \\ _ & _ & _ \end{bmatrix} \text{ and}$$

$$A^T = \begin{bmatrix} _ & _ & _ \\ _ & _ & _ \\ _ & _ & _ \end{bmatrix}.$$

13. (1 pt) Library/Rochester/setAlgebra34Matrices/cubing_2x2.pg

Given the matrix $A = \begin{bmatrix} 4 & -3 \\ 0 & 3 \end{bmatrix}$, find A^3 .

$$A^3 = \begin{bmatrix} _ & _ \\ _ & _ \end{bmatrix}.$$

14. (1 pt) Library/maCalcDB/setLinearAlgebra3Matrices/ur_la_3_6.pg

If A and B are 6×2 matrices, and C is a 4×6 matrix, which of the following are defined?

- A. $C + B$
- B. CA
- C. $B + A$
- D. B^T
- E. $B^T C^T$
- F. AB

15. (1 pt) Library/NAU/setLinearAlgebra/m1.pg

Find the inverse of AB if

$$A^{-1} = \begin{bmatrix} 3 & -2 \\ 3 & 5 \end{bmatrix} \text{ and } B^{-1} = \begin{bmatrix} 2 & -3 \\ 2 & -1 \end{bmatrix}.$$

$$(AB)^{-1} = \begin{bmatrix} _ & _ \\ _ & _ \end{bmatrix}$$

16. (1 pt) Library/Rochester/setLinearAlgebra4InverseMatrix/ur_Ch2.1.4.pg

Are the following matrices invertible? Enter "Y" or "N". You must get all of the answers correct to receive credit.

- 1. $\begin{bmatrix} -5 & 0 \\ 0 & 5 \end{bmatrix}$
 —2. $\begin{bmatrix} 25 & -8 \\ 0 & 0 \end{bmatrix}$
 —3. $\begin{bmatrix} -7 & 6 \\ -1 & -2 \end{bmatrix}$
 —4. $\begin{bmatrix} -5 & -8 \\ 25 & 40 \end{bmatrix}$

17. (1 pt) Library/ASU-topics/set119MatrixAlgebra/p13.pg

Consider the following two systems.

(a)

$$\begin{cases} x - 3y = 2 \\ -3x + 3y = -3 \end{cases}$$

(b)

$$\begin{cases} x - 3y = 3 \\ -3x + 3y = -3 \end{cases}$$

(i) Find the inverse of the (common) coefficient matrix of the two systems.

$$A^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}$$

(ii) Find the solutions to the two systems by using the inverse, i.e. by evaluating $A^{-1}B$ where B represents the right hand side

(i.e. $B = \begin{bmatrix} 2 \\ -3 \end{bmatrix}$ for system (a) and $B = \begin{bmatrix} 3 \\ -3 \end{bmatrix}$ for system

(b)).

Solution to system (a): $x = \underline{\quad}$, $y = \underline{\quad}$

Solution to system (b): $x = \underline{\quad}$, $y = \underline{\quad}$

18. (1 pt) Library/ASU-topics/set119MatrixAlgebra/p13.pg

Consider the following two systems.

(a)

$$\begin{cases} -2x + y = -3 \\ 3x - y = -3 \end{cases}$$

(b)

$$\begin{cases} -2x + y = -2 \\ 3x - y = -2 \end{cases}$$

(i) Find the inverse of the (common) coefficient matrix of the two systems.

$$A^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}$$

(ii) Find the solutions to the two systems by using the inverse, i.e. by evaluating $A^{-1}B$ where B represents the right hand side (i.e. $B = \begin{bmatrix} -3 \\ -3 \end{bmatrix}$ for system (a) and $B = \begin{bmatrix} -2 \\ -2 \end{bmatrix}$ for system (b)).

Solution to system (a): $x = \underline{\quad}$, $y = \underline{\quad}$

Solution to system (b): $x = \underline{\quad}$, $y = \underline{\quad}$

19. (1 pt) Library/TCNJ/TCNJ_MatrixInverse/problem1.pg

If

$$A = \begin{bmatrix} -3 & 4 \\ 1 & 7 \end{bmatrix},$$

then

$$A^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}.$$

Given $\vec{b} = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$, solve $A\vec{x} = \vec{b}$.

$$\vec{x} = \begin{bmatrix} \underline{\quad} \\ \underline{\quad} \end{bmatrix}.$$

20. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/3.3.42.pg

A must be a square matrix to be invertible.

21. (1 pt) Library/Rochester/setLinearAlgebra4InverseMatrix/ur.la.4.11.pg

$$\text{If } A = \begin{bmatrix} -2e^{2t} \sin(4t) & -2e^{5t} \cos(4t) \\ -6e^{2t} \cos(4t) & 6e^{5t} \sin(4t) \end{bmatrix}$$

$$\text{then } A^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}.$$

22. (1 pt) Library/maCalcDB/setLinearAlgebra4InverseMatrix/ur.la.4.8.pg

Determine which of the formulas hold for all invertible $n \times n$ matrices A and B

- A. $ABA^{-1} = B$
- B. $(A+B)(A-B) = A^2 - B^2$
- C. $A^7 B^6$ is invertible
- D. $A+B$ is invertible
- E. $(I_n - A)(I_n + A) = I_n - A^2$
- F. $(A + A^{-1})^9 = A^9 + A^{-9}$