

1. (1 pt) Library/ASU-topics/set119MatrixAlgebra/p13.pg

Consider the following two systems.

(a)

$$\begin{cases} x + 4y = 3 \\ -3x - 9y = -3 \end{cases}$$

(b)

$$\begin{cases} x + 4y = -2 \\ -3x - 9y = 4 \end{cases}$$

(i) Find the inverse of the (common) coefficient matrix of the two systems.

$$A^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}$$

(ii) Find the solutions to the two systems by using the inverse, i.e. by evaluating $A^{-1}B$ where B represents the right hand side(i.e. $B = \begin{bmatrix} 3 \\ -3 \end{bmatrix}$ for system (a) and $B = \begin{bmatrix} -2 \\ 4 \end{bmatrix}$ for system

(b)).

Solution to system (a): $x = \underline{\quad}$, $y = \underline{\quad}$ Solution to system (b): $x = \underline{\quad}$, $y = \underline{\quad}$ **2. (1 pt) Library/NAU/setLinearAlgebra/m1.pg**Find the inverse of AB if

$$A^{-1} = \begin{bmatrix} 4 & 4 \\ -5 & 3 \end{bmatrix} \text{ and } B^{-1} = \begin{bmatrix} 3 & -2 \\ -2 & 5 \end{bmatrix}.$$

$$(AB)^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}$$

3. (1 pt) Library/Rochester/setAlgebra34Matrices/cubing_2x2.pgGiven the matrix $A = \begin{bmatrix} 3 & 3 \\ 0 & 3 \end{bmatrix}$, find A^3 .

$$A^3 = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}.$$

4. (1 pt) Library/Rochester/setAlgebra34Matrices/scalarmult3.pgIf $A = \begin{bmatrix} -1 & 1 & 0 \\ -3 & 4 & 1 \\ 3 & -2 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 4 & 4 & -4 \\ -3 & 2 & -4 \\ -1 & 2 & -4 \end{bmatrix}$, then

$$3A - 4B = \begin{bmatrix} \underline{\quad} & \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} & \underline{\quad} \end{bmatrix} \text{ and}$$

$$A^T = \begin{bmatrix} \underline{\quad} & \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} & \underline{\quad} \end{bmatrix}.$$

5. (1 pt) Library/Rochester/setLinearAlgebra4InverseMatrix-/ur_Ch2.1.4.pg

Are the following matrices invertible? Enter "Y" or "N". You must get all of the answers correct to receive credit.

$$\text{---1. } \begin{bmatrix} 6 & -2 \\ 3 & -6 \end{bmatrix}$$

$$\text{---2. } \begin{bmatrix} 32 & -3 \\ 0 & 0 \end{bmatrix}$$

$$\text{---3. } \begin{bmatrix} -8 & -3 \\ 32 & 12 \end{bmatrix}$$

$$\text{---4. } \begin{bmatrix} -2 & -8 \\ -6 & -4 \end{bmatrix}$$

6. (1 pt) Library/Rochester/setLinearAlgebra4InverseMatrix-/ur_la_4.2.pgThe matrix $\begin{bmatrix} 4 & -6 \\ 9 & k \end{bmatrix}$ is invertible if and only if $k \neq \underline{\quad}$.**7. (1 pt) Library/Rochester/setLinearAlgebra4InverseMatrix-/ur_la_4.11.pg**

$$\text{If } A = \begin{bmatrix} 5e^{3t} \sin(9t) & 5e^{4t} \cos(9t) \\ 4e^{3t} \cos(9t) & -4e^{4t} \sin(9t) \end{bmatrix}$$

$$\text{then } A^{-1} = \begin{bmatrix} \underline{\quad} & \underline{\quad} \\ \underline{\quad} & \underline{\quad} \end{bmatrix}.$$

8. (1 pt) Library/Rochester/setLinearAlgebra9Dependence-/ur_la_9-7.pg

The vectors

$$v = \begin{bmatrix} -2 \\ -4 \\ -4 \end{bmatrix}, u = \begin{bmatrix} 4 \\ 0 \\ -18 + k \end{bmatrix}, \text{ and } w = \begin{bmatrix} 4 \\ 2 \\ -4 \end{bmatrix}.$$

are linearly independent if and only if $k \neq \underline{\quad}$.**9. (1 pt) Library/Rochester/setLinearAlgebra9Dependence-/ur_la_9-10.pg**Express the vector $v = \begin{bmatrix} 22 \\ 16 \end{bmatrix}$ as a linear combination of

$$x = \begin{bmatrix} 4 \\ 1 \end{bmatrix} \text{ and } y = \begin{bmatrix} 3 \\ 6 \end{bmatrix}.$$

$$v = \underline{\quad} x + \underline{\quad} y.$$

10. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-/ur_la_23.2.pg

Find the eigenvalues of the matrix

$$M = \begin{bmatrix} 30 & -40 \\ -40 & -30 \end{bmatrix}.$$

Enter the two eigenvalues, separated by a comma:

Classify the quadratic form $Q(x) = x^T Ax$:

- A. $Q(x)$ is positive semidefinite
- B. $Q(x)$ is negative semidefinite
- C. $Q(x)$ is negative definite
- D. $Q(x)$ is indefinite
- E. $Q(x)$ is positive definite

11. (1 pt) Library/Rochester/setLinearAlgebra23QuadraticForms-ur.la.23.3.pg

The matrix

$$A = \begin{bmatrix} 3 & -1 & 0 \\ -1 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

has three distinct eigenvalues, $\lambda_1 < \lambda_2 < \lambda_3$,

$$\lambda_1 = \underline{\hspace{2cm}},$$

$$\lambda_2 = \underline{\hspace{2cm}},$$

$$\lambda_3 = \underline{\hspace{2cm}}.$$

Classify the quadratic form $Q(x) = x^T Ax$:

- A. $Q(x)$ is negative definite
- B. $Q(x)$ is positive definite
- C. $Q(x)$ is positive semidefinite
- D. $Q(x)$ is negative semidefinite
- E. $Q(x)$ is indefinite

12. (1 pt) Library/TCNJ/TCNJ_BasesLinearlyIndependentSet/problem5.pg

Let W_1 be the set: $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$.

Determine if W_1 is a basis for \mathbb{R}^3 and check the correct answer(s) below.

- A. W_1 is not a basis because it is linearly dependent.
- B. W_1 is not a basis because it does not span \mathbb{R}^3 .
- C. W_1 is a basis.

Let W_2 be the set: $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$.

Determine if W_2 is a basis for \mathbb{R}^3 and check the correct answer(s) below.

- A. W_2 is not a basis because it does not span \mathbb{R}^3 .
- B. W_2 is a basis.
- C. W_2 is not a basis because it is linearly dependent.

13. (1 pt) Library/TCNJ/TCNJ_LinearIndependence/problem3.pg

If k is a real number, then the vectors $(1, k), (k, 3k + 40)$ are linearly independent precisely when

$$k \neq a, b,$$

where $a = \underline{\hspace{2cm}}, b = \underline{\hspace{2cm}},$ and $a < b.$

14. (1 pt) Library/TCNJ/TCNJ_LinearSystems/problem1.pg

Determine whether the following system has no solution, an infinite number of solutions or a unique solution.

$$\begin{cases} -5x - 3y = 9 \\ ?1. \quad 6x + 2y = 6 \\ \quad 7x + 1y = 18 \end{cases}$$

$$\begin{cases} -5x - 3y = 9 \\ ?2. \quad 6x + 2y = 6 \\ \quad 7x + 1y = 21 \end{cases}$$

$$\begin{cases} 8x - 16y = -8 \\ ?3. \quad -6x + 12y = 6 \\ \quad 14x - 28y = -14 \end{cases}$$

15. (1 pt) Library/TCNJ/TCNJ_LinearSystems/problem2.pg

Determine whether the following system has no solution, an infinite number of solutions or a unique solution.

$$\begin{cases} ?1. \quad 30x + 18y - 24z = 18 \\ \quad 10x + 6y - 8z = 8 \end{cases}$$

$$\begin{cases} ?2. \quad 3x - 6y + 2z = 3 \\ \quad 3x - 5y + 7z = 6 \end{cases}$$

$$\begin{cases} ?3. \quad 30x + 18y - 24z = 18 \\ \quad 10x + 6y - 8z = 6 \end{cases}$$

16. (1 pt) Library/TCNJ/TCNJ_LinearSystems/problem3.pg

Give a geometric description of the following systems of equations

$$\begin{cases} ?1. \quad -7x - 3y = 3 \\ \quad -2x - 3y = 5 \\ \quad -3x + 3y = -8 \end{cases}$$

$$\begin{cases} ?2. \quad -20x - 8y = -8 \\ \quad -15x - 6y = -6 \\ \quad 35x + 14y = 14 \end{cases}$$

$$\begin{cases} ?3. \quad -7x - 3y = 3 \\ \quad -2x - 3y = 5 \\ \quad -3x + 3y = -7 \end{cases}$$

17. (1 pt) Library/TCNJ/TCNJ_LinearSystems/problem4.pg

Give a geometric description of the following system of equations

$$\begin{cases} ?1. \quad 2x + 4y - 6z = -12 \\ \quad -3x - 6y + 9z = 18 \end{cases}$$

$$\begin{aligned} \boxed{?}2. \quad & 2x + 4y - 6z = 12 \\ & -3x - 6y + 9z = 16 \\ \boxed{?}3. \quad & 2x + 4y - 6z = 12 \\ & -x + 5y - 9z = 1 \end{aligned}$$

18. (1 pt) Library/TCNJ/TCNJ_LinearSystems/problem11.pg

Give a geometric description of the following systems of equations.

$$\begin{aligned} \boxed{?}1. \quad & x - 9y = -2 \\ & -6x - 6y = 3 \\ \boxed{?}2. \quad & 2x - 10y = -10 \\ & 5x - 25y = -25 \\ \boxed{?}3. \quad & 2x - 10y = -10 \\ & 5x - 25y = -28 \end{aligned}$$

19. (1 pt) Library/TCNJ/TCNJ_MatrixEquations/problem4.pg

Let $A = \begin{bmatrix} -5 & 2 & 4 \\ -4 & 4 & -3 \\ 4 & 2 & 1 \end{bmatrix}$ and $x = \begin{bmatrix} 2 \\ 3 \\ -4 \end{bmatrix}$.

$\boxed{?}1.$ What does Ax mean?

20. (1 pt) Library/TCNJ/TCNJ_MatrixEquations/problem13.pg

Do the following sets of vectors span \mathbb{R}^3 ?

$$\begin{aligned} \boxed{?}1. \quad & \begin{bmatrix} -2 \\ -3 \\ -3 \end{bmatrix}, \begin{bmatrix} -6 \\ -9 \\ -8 \end{bmatrix}, \begin{bmatrix} -10 \\ -15 \\ -13 \end{bmatrix}, \begin{bmatrix} 14 \\ 21 \\ 18 \end{bmatrix} \\ \boxed{?}2. \quad & \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix}, \begin{bmatrix} -4 \\ -6 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \\ \boxed{?}3. \quad & \begin{bmatrix} -2 \\ 3 \\ 3 \end{bmatrix}, \begin{bmatrix} 5 \\ -5 \\ 7 \end{bmatrix}, \begin{bmatrix} -4 \\ 2 \\ -10 \end{bmatrix} \\ \boxed{?}4. \quad & \begin{bmatrix} -3 \\ 3 \\ -2 \end{bmatrix}, \begin{bmatrix} -9 \\ 9 \\ -7 \end{bmatrix} \end{aligned}$$

21. (1 pt) Library/TCNJ/TCNJ_MatrixInverse/problem1.pg

If

$$A = \begin{bmatrix} -5 & -6 \\ -3 & 1 \end{bmatrix},$$

then

$$A^{-1} = \begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix}.$$

Given $\vec{b} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$, solve $A\vec{x} = \vec{b}$.

$$\vec{x} = \begin{bmatrix} \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} \end{bmatrix}.$$

22. (1 pt) Library/TCNJ/TCNJ_VectorEquations/problem5.pg

Let $H = \text{span}\{u, v\}$. For each of the following sets of vectors determine whether H is a line or a plane.

$$\begin{aligned} \boxed{?}1. \quad & u = \begin{bmatrix} -2 \\ -1 \\ -5 \end{bmatrix}, v = \begin{bmatrix} -7 \\ -2 \\ -7 \end{bmatrix}, \\ \boxed{?}2. \quad & u = \begin{bmatrix} -1 \\ -3 \\ -2 \end{bmatrix}, v = \begin{bmatrix} 3 \\ 9 \\ 6 \end{bmatrix}, \\ \boxed{?}3. \quad & u = \begin{bmatrix} 5 \\ -5 \\ 3 \end{bmatrix}, v = \begin{bmatrix} 20 \\ -19 \\ 11 \end{bmatrix}, \\ \boxed{?}4. \quad & u = \begin{bmatrix} 8 \\ 5 \\ 3 \end{bmatrix}, v = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \end{aligned}$$

23. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.2.8.pg

Let $\mathbf{a}_1 = \begin{bmatrix} 7 \\ 4 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} 21 \\ 12 \end{bmatrix}$.

Is \mathbf{b} in the span of \mathbf{a}_1 ?

- A. Yes, \mathbf{b} is in the span.
- B. No, \mathbf{b} is not in the span.
- C. We cannot tell if \mathbf{b} is in the span.

Either fill in the coefficients of the vector equation, or enter "NONE" if no solution is possible.

$$\mathbf{b} = \underline{\hspace{1cm}} \mathbf{a}_1$$

24. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.2.31.pg

$$\text{Let } A = \begin{bmatrix} -5 & 20 \\ 5 & -32 \\ 1 & -9 \end{bmatrix}.$$

We want to determine if the system $Ax = \mathbf{b}$ has a solution for every $\mathbf{b} \in \mathbb{R}^3$.

Select the best answer.

- A. There is not a solution for every $\mathbf{b} \in \mathbb{R}^3$ since $2 < 3$.
- B. There is a solution for every $\mathbf{b} \in \mathbb{R}^3$ but we need to row reduce A to show this.
- C. There is a solution for every $\mathbf{b} \in \mathbb{R}^3$ since $2 < 3$.
- D. There is a not solution for every $\mathbf{b} \in \mathbb{R}^3$ but we need to row reduce A to show this.
- E. We cannot tell if there is a solution for every $\mathbf{b} \in \mathbb{R}^3$.

25. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.2.56.pg

What conditions on a matrix A insures that $Ax = \mathbf{b}$ has a solution for all \mathbf{b} in \mathbb{R}^n ?

Select the best statement. (The best condition should work with any positive integer n .)

- A. The equation will have a solution for all \mathbf{b} in \mathbb{R}^n as long as the columns of A do not include the zero column.
- B. The equation will have a solution for all \mathbf{b} in \mathbb{R}^n as long as the columns of A span \mathbb{R}^n .
- C. The equation will have a solution for all \mathbf{b} in \mathbb{R}^n as long as no column of A is a scalar multiple of another column.
- D. There is no easy test to determine if the equation will have a solution for all \mathbf{b} in \mathbb{R}^n .
- E. none of the above

26. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.2.57.pg

Assume $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ spans \mathbb{R}^3 .
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ always spans \mathbb{R}^3 .
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ spans \mathbb{R}^3 unless \mathbf{u}_4 is the zero vector.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ spans \mathbb{R}^3 unless \mathbf{u}_4 is a scalar multiple of another vector in the set.
- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ never spans \mathbb{R}^3 .
- E. There is no easy way to determine if $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ spans \mathbb{R}^3 .
- F. none of the above

27. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.2.58.pg

Assume $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ does not span \mathbb{R}^3 .
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ always spans \mathbb{R}^3 .
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ may, but does not have to, span \mathbb{R}^3 .
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ never spans \mathbb{R}^3 .
- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ spans \mathbb{R}^3 unless \mathbf{u}_4 is the zero vector.
- E. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ spans \mathbb{R}^3 unless \mathbf{u}_4 is a scalar multiple of another vector in the set.
- F. none of the above

28. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.40.pg

Let \mathbf{S} be a set of m vectors in \mathbb{R}^n with $m > n$.
Select the best statement.

- A. The set \mathbf{S} is linearly dependent.
- B. The set \mathbf{S} is linearly independent, as long as no vector in \mathbf{S} is a scalar multiple of another vector in the set.
- C. The set \mathbf{S} is linearly independent.
- D. The set \mathbf{S} could be either linearly dependent or linearly independent, depending on the case.

- E. The set \mathbf{S} is linearly independent, as long as it does not include the zero vector.
- F. none of the above

29. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.41.pg

Let A be a matrix with more rows than columns.
Select the best statement.

- A. The columns of A are linearly independent, as long as they does not include the zero vector.
- B. The columns of A must be linearly dependent.
- C. The columns of A must be linearly independent.
- D. The columns of A are linearly independent, as long as no column is a scalar multiple of another column in A .
- E. The columns of A could be either linearly dependent or linearly independent depending on the case.
- F. none of the above

30. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.42.pg

Let A be a matrix with more columns than rows.
Select the best statement.

- A. The columns of A could be either linearly dependent or linearly independent depending on the case.
- B. The columns of A are linearly independent, as long as no column is a scalar multiple of another column in A .
- C. The columns of A are linearly independent, as long as they does not include the zero vector.
- D. The columns of A must be linearly dependent.
- E. none of the above

31. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.46.pg

Let $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ be a linearly dependent set of vectors.
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is a linearly independent set of vectors unless \mathbf{u}_4 is a linear combination of other vectors in the set.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ could be a linearly independent or linearly dependent set of vectors depending on the vectors chosen.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly dependent set of vectors.
- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is a linearly independent set of vectors unless $\mathbf{u}_4 = \mathbf{0}$.
- E. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly independent set of vectors.

- F. none of the above

32. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/2.3.47.pg

Let $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ be a linearly independent set of vectors. Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ could be a linearly independent or linearly dependent set of vectors depending on the vectors chosen.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is never a linearly independent set of vectors.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is always a linearly independent set of vectors.
- D. none of the above

33. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/3.3.42.pg

A must be a square matrix to be invertible.

34. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/4.1.22.pg

Find the null space for $A = \begin{bmatrix} 9 & 2 \\ 7 & 6 \end{bmatrix}$.

What is $\text{null}(A)$?

- A. $\text{span}\left\{\begin{bmatrix} 7 \\ 9 \end{bmatrix}\right\}$
- B. $\text{span}\left\{\begin{bmatrix} -2 \\ 9 \end{bmatrix}\right\}$
- C. $\text{span}\left\{\begin{bmatrix} 9 \\ 2 \end{bmatrix}\right\}$
- D. $\text{span}\left\{\begin{bmatrix} 9 \\ 7 \end{bmatrix}\right\}$
- E. $\left\{\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right\}$
- F. \mathbb{R}^2
- G. $\text{span}\left\{\begin{bmatrix} -7 \\ 9 \end{bmatrix}\right\}$
- H. none of the above

35. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/4.1.27.pg

Find the null space for $A = \begin{bmatrix} 2 & -3 \\ 1 & 4 \\ -7 & -4 \end{bmatrix}$.

What is $\text{null}(A)$?

- A. $\text{span}\left\{\begin{bmatrix} 2 \\ 1 \\ -7 \end{bmatrix}\right\}$

- B. $\text{span}\left\{\begin{bmatrix} -3 \\ 2 \end{bmatrix}\right\}$
- C. $\left\{\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right\}$
- D. \mathbb{R}^3
- E. $\text{span}\left\{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}\right\}$
- F. $\text{span}\left\{\begin{bmatrix} +3 \\ 2 \end{bmatrix}\right\}$
- G. $\text{span}\left\{\begin{bmatrix} 2 \\ -3 \end{bmatrix}\right\}$
- H. \mathbb{R}^2
- I. none of the above

36. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/4.1.28.pg

Find the null space for $A = \begin{bmatrix} 3 & -15 \\ 2 & -10 \\ 5 & -25 \end{bmatrix}$.

What is $\text{null}(A)$?

- A. $\text{span}\left\{\begin{bmatrix} -25 \\ 5 \end{bmatrix}\right\}$
- B. \mathbb{R}^2
- C. \mathbb{R}^3
- D. $\text{span}\left\{\begin{bmatrix} +5 \\ 1 \end{bmatrix}\right\}$
- E. $\text{span}\left\{\begin{bmatrix} 0 \\ 0 \end{bmatrix}\right\}$
- F. $\text{span}\left\{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}\right\}$
- G. $\text{span}\left\{\begin{bmatrix} 3 \\ 2 \\ 5 \end{bmatrix}\right\}$
- H. none of the above

37. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/4.1.30.pg

Find the null space for $A = \begin{bmatrix} 1 & 2 & 9 \\ -6 & -2 & -24 \\ -1 & 4 & 9 \end{bmatrix}$.

What is $\text{null}(A)$?

- A. $\text{span}\left\{\begin{bmatrix} 1 \\ -6 \\ -1 \end{bmatrix}\right\}$
- B. $\text{span}\left\{\begin{bmatrix} 1 \\ 2 \\ 9 \end{bmatrix}\right\}$

- C. \mathbb{R}^3
- D. $\text{span} \left\{ \begin{bmatrix} -3 \\ -3 \\ 1 \end{bmatrix} \right\}$
- E. $\text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 9 \end{bmatrix}, \begin{bmatrix} -6 \\ -2 \\ -24 \end{bmatrix} \right\}$
- F. $\text{span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$
- G. none of the above

38. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/4.2.32a.pg

Find a basis for the null space of matrix A .

$$A = \begin{bmatrix} 1 & 0 & -4 & 3 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$

$$\text{Basis} = \left[\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \right] \left[\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \right]$$

39. (1 pt) Library/WHFreeman/Holt_linear_algebra/Chaps.1-4/4.3.47.pg

Indicate whether the following statement is true or false.

1. If A and B are equivalent matrices, then $\text{col}(A) = \text{col}(B)$.

40. (1 pt) Library/maCalcDB/setLinearAlgebra3Matrices/ur_la.3.6.pg

If A and B are 4×9 matrices, and C is a 2×4 matrix, which of the following are defined?

- A. B^T
- B. $C - A$
- C. $A - B$
- D. CB
- E. AB^T
- F. AC

41. (1 pt) Library/maCalcDB/setLinearAlgebra4InverseMatrix/ur_la.4.8.pg

Determine which of the formulas hold for all invertible $n \times n$ matrices A and B

- A. $A^2 B^9$ is invertible
- B. $(A + A^{-1})^4 = A^4 + A^{-4}$
- C. $(I_n - A)(I_n + A) = I_n - A^2$
- D. $(A + B)(A - B) = A^2 - B^2$
- E. $AB = BA$
- F. $A + I_n$ is invertible

42. (1 pt) UI/DIAGtproblem1.pg

A , P and D are $n \times n$ matrices.

Check the true statements below:

- A. If A is diagonalizable, then A has n distinct eigenvalues.
- B. If A is invertible, then A is diagonalizable.
- C. A is diagonalizable if A has n distinct linearly independent eigenvectors.
- D. If A is diagonalizable, then A is invertible.
- E. If A is orthogonally diagonalizable, then A is symmetric.
- F. A is diagonalizable if A has n distinct eigenvectors.
- G. If $AP = PD$, with D diagonal, then the nonzero columns of P must be eigenvectors of A .
- H. If there exists a basis for \mathbb{R}^n consisting entirely of eigenvectors of A , then A is diagonalizable.
- I. If A is symmetric, then A is diagonalizable.
- J. A is diagonalizable if and only if A has n eigenvalues, counting multiplicities.
- K. A is diagonalizable if $A = PDP^{-1}$ for some diagonal matrix D and some invertible matrix P .
- L. If A is symmetric, then A is orthogonally diagonalizable.
- M. If A is diagonalizable, then A is symmetric.

43. (1 pt) UI/Fall14/lin_span2.pg

Which of the following sets of vectors span \mathbb{R}^3 ?

- A. $\begin{bmatrix} -7 \\ -4 \\ 8 \end{bmatrix}, \begin{bmatrix} -6 \\ 9 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}$
- B. $\begin{bmatrix} 1 \\ -5 \\ 0 \end{bmatrix}, \begin{bmatrix} -7 \\ 1 \\ 8 \end{bmatrix}$
- C. $\begin{bmatrix} 0 \\ 0 \\ 5 \end{bmatrix}, \begin{bmatrix} -2 \\ 8 \\ 2 \end{bmatrix}, \begin{bmatrix} -6 \\ -4 \\ -4 \end{bmatrix}$
- D. $\begin{bmatrix} 5 \\ 7 \\ -7 \end{bmatrix}, \begin{bmatrix} 2 \\ -8 \\ -5 \end{bmatrix}, \begin{bmatrix} -6 \\ -4 \\ -9 \end{bmatrix}$
- E. $\begin{bmatrix} 8 \\ 0 \\ -2 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 7 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 5 \end{bmatrix}$
- F. $\begin{bmatrix} -2 \\ 6 \\ 5 \end{bmatrix}, \begin{bmatrix} 7 \\ 2 \\ -8 \end{bmatrix}, \begin{bmatrix} 5 \\ 8 \\ -3 \end{bmatrix}$

Which of the following sets of vectors are linearly independent?

- A. $\begin{bmatrix} -7 \\ -4 \\ 8 \end{bmatrix}, \begin{bmatrix} -6 \\ 9 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}$
- B. $\begin{bmatrix} 1 \\ -5 \end{bmatrix}, \begin{bmatrix} -7 \\ 1 \end{bmatrix}$
- C. $\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 8 \end{bmatrix}$
- D. $\begin{bmatrix} 5 \\ 7 \end{bmatrix}, \begin{bmatrix} 2 \\ -8 \end{bmatrix}, \begin{bmatrix} -6 \\ -4 \end{bmatrix}$
- E. $\begin{bmatrix} -7 \\ 8 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} -9 \\ 4 \\ 0 \end{bmatrix}$
- F. $\begin{bmatrix} -2 \\ 6 \\ 5 \end{bmatrix}, \begin{bmatrix} 7 \\ 2 \\ -8 \end{bmatrix}, \begin{bmatrix} 5 \\ 8 \\ -3 \end{bmatrix}$

44. (1 pt) UI/Fall14/lin_span.pg

Let $A = \begin{bmatrix} 1 \\ 1 \\ -4 \end{bmatrix}$, $B = \begin{bmatrix} 4 \\ -1 \\ -21 \end{bmatrix}$, and $C = \begin{bmatrix} -1 \\ 0 \\ 5 \end{bmatrix}$.

Which of the following best describes the span of the above 3 vectors?

- A. 0-dimensional point in \mathbb{R}^3
- B. 1-dimensional line in \mathbb{R}^3
- C. 2-dimensional plane in \mathbb{R}^3
- D. \mathbb{R}^3

Determine whether or not the three vectors listed above are linearly independent or linearly dependent.

- A. linearly dependent
- B. linearly independent

If they are linearly dependent, determine a non-trivial linear relation. Otherwise, if the vectors are linearly independent, enter 0's for the coefficients, since that relationship **always** holds.

$\underline{\hspace{1cm}}A + \underline{\hspace{1cm}}B + \underline{\hspace{1cm}}C = 0.$

45. (1 pt) UI/orthog.pg

All vectors and subspaces are in \mathbb{R}^n .

Check the true statements below:

- A. If \mathbf{v} and \mathbf{w} are both eigenvectors of A and if A is symmetric, then $\mathbf{v} \cdot \mathbf{w} = 0$.
- B. If x is not in a subspace W , then $x - \text{proj}_W(x)$ is not zero.
- C. If $W = \text{Span}\{x_1, x_2, x_3\}$ and if $\{v_1, v_2, v_3\}$ is an orthonormal set in W , then $\{v_1, v_2, v_3\}$ is an orthonormal basis for W .
- D. If $A\mathbf{v} = r\mathbf{v}$ and $A\mathbf{w} = s\mathbf{w}$ and $r \neq s$, then $\mathbf{v} \cdot \mathbf{w} = 0$.

- E. If $\{v_1, v_2, v_3\}$ is an orthonormal set, then the set $\{v_1, v_2, v_3\}$ is linearly independent.
- F. In a QR factorization, say $A = QR$ (when A has linearly independent columns), the columns of Q form an orthonormal basis for the column space of A .
- G. If A is symmetric, $A\mathbf{v} = r\mathbf{v}$, $A\mathbf{w} = s\mathbf{w}$ and $r \neq s$, then $\mathbf{v} \cdot \mathbf{w} = 0$.

46. (1 pt) local/Library/Rochester/setLinearAlgebra3Matrices/ur_la_3_14.pg

Find the ranks of the following matrices.

$\text{rank} \begin{bmatrix} 4 & -5 \\ -8 & 10 \end{bmatrix} = \underline{\hspace{1cm}}$

$\text{rank} \begin{bmatrix} 5 & 1 & -5 \\ 0 & 4 & 0 \\ -4 & 0 & 4 \end{bmatrix} = \underline{\hspace{1cm}}$

$\text{rank} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 8 & 0 \end{bmatrix} = \underline{\hspace{1cm}}$

47. (1 pt) local/Library/TCNJ/TCNJ_BasesLinearlyIndependentSet/3.pg

Check the true statements below:

- A. The column space of a matrix A is the set of solutions of $Ax = b$.
- B. A basis is a spanning set that is as large as possible.
- C. If B is an echelon form of a matrix A , then the pivot columns of B form a basis for $\text{Col}A$.
- D. The columns of an invertible $n \times n$ matrix form a basis for \mathbb{R}^n .
- E. If $H = \text{Span}\{b_1, \dots, b_p\}$, then $\{b_1, \dots, b_p\}$ is a basis for H .

48. (1 pt) local/Library/TCNJ/TCNJ_LinearSystems/problem6.pg

Give a geometric description of the following systems of equations

1.
$$\begin{aligned} 5x + 15y + 49z &= 3 \\ -x - 2y - 7z &= 3 \\ 4x + 12y + 40z &= 0 \end{aligned}$$

2.
$$\begin{aligned} 9x + 12y + 9z &= 15 \\ 15x + 20y + 15z &= 25 \\ -18x - 24y - 18z &= -30 \end{aligned}$$

3.
$$\begin{aligned} 5x - y + 3z &= -5 \\ 4x + 4y - 5z &= 4 \\ -23x - 5y + z &= 7 \end{aligned}$$

4.
$$\begin{aligned} 5x - y + 3z &= -5 \\ 4x + 4y - 5z &= 4 \\ -23x - 5y + z &= 8 \end{aligned}$$

Hint: (Instructor hint preview: show the student hint after 1 attempts. The current number of attempts is 0.)

Reduce the augmented matrix and solve for it. If it has unique solutions, three planes intersect at a point; no solutions indicates no common intersection; one free variable shows intersection on a line; two free variables means identical planes.

49. (1 pt) local/Library/UI/2.3.49.pg

Let \mathbf{u}_4 be a linear combination of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$.
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is never a linearly dependent set of vectors.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is a linearly dependent set of vectors unless one of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is the zero vector.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly independent set of vectors.
- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is a linearly dependent set of vectors.
- E. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ could be a linearly dependent or linearly independent set of vectors depending on the vectors chosen.
- F. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is never a linearly independent set of vectors.
- G. none of the above

50. (1 pt) local/Library/UI/4.1.23.pg

Find the null space for $A = \begin{bmatrix} 1 & 0 & 9 \\ 0 & 1 & -8 \end{bmatrix}$.

What is $\text{null}(A)$?

- A. \mathbb{R}^2
- B. $\text{span} \left\{ \begin{bmatrix} +8 \\ -9 \\ 1 \end{bmatrix} \right\}$
- C. \mathbb{R}^3
- D. $\text{span} \left\{ \begin{bmatrix} -9 \\ +8 \end{bmatrix} \right\}$
- E. $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ -9 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ +8 \end{bmatrix} \right\}$
- F. $\text{span} \left\{ \begin{bmatrix} +8 \\ -9 \end{bmatrix} \right\}$
- G. $\text{span} \left\{ \begin{bmatrix} -9 \\ +8 \\ 1 \end{bmatrix} \right\}$
- H. none of the above

51. (1 pt) local/Library/UI/4.1.77.pg

The null space for the matrix $\begin{bmatrix} 1 & 7 & -2 & 14 & 0 \\ 3 & 0 & 1 & -2 & 3 \\ 6 & 1 & -1 & 0 & 4 \end{bmatrix}$

is $\text{span}\{A, B\}$ where $A = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$ $B = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$

52. (1 pt) local/Library/UI/4.3.3.pg

Find bases for the column space and the null space of matrix A. You should verify that the Rank-Nullity Theorem holds. An equivalent echelon form of matrix A is given to make your work easier.

$$A = \begin{bmatrix} 1 & 0 & -4 & -3 \\ -2 & 1 & 15 & 7 \\ 0 & 1 & 7 & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 0 & -4 & -3 \\ 0 & 1 & 7 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Basis for the column space of A = $\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$ $\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$

Basis for the null space of A = $\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$ $\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$

53. (1 pt) local/Library/UI/6a.pg

The null space for the matrix $\begin{bmatrix} 2 & 0 & 5 \\ -1 & 6 & 2 \\ 4 & 4 & -1 \\ 5 & 1 & 0 \\ 4 & 1 & 1 \end{bmatrix}$

is $\begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$

54. (1 pt) local/Library/UI/Fall14/HW7.4.pg

Determine if the subset of \mathbb{R}^2 consisting of vectors of the form $\begin{bmatrix} a \\ b \end{bmatrix}$, where a and b are integers, is a subspace.

Select true or false for each statement.

The set contains the zero vector

- A. True
- B. False

This set is closed under vector addition

- A. True
- B. False

This set is closed under scalar multiplications

- A. True
- B. False

This set is a subspace

- A. True
- B. False

55. (1 pt) local/Library/UI/Fall14/HW7.5.pg

Determine if the subset of \mathbb{R}^3 consisting of vectors of the form $\begin{bmatrix} a \\ b \\ c \end{bmatrix}$, where $a \geq 0$, $b \geq 0$, and $c \geq 0$ is a subspace.

Select true or false for each statement.

The set contains the zero vector

- A. True
- B. False

This set is closed under vector addition

- A. True
- B. False

This set is closed under scalar multiplications

- A. True
- B. False

This set is a subspace

- A. True
- B. False

56. (1 pt) local/Library/UI/Fall14/HW7.6.pg

If A is an $n \times n$ matrix and $\mathbf{b} \neq \mathbf{0}$ in \mathbb{R}^n , then consider the set of solutions to $A\mathbf{x} = \mathbf{b}$.

Select true or false for each statement.

The set contains the zero vector

- A. True
- B. False

This set is closed under vector addition

- A. True
- B. False

This set is closed under scalar multiplications

- A. True
- B. False

This set is a subspace

- A. True
- B. False

57. (1 pt) local/Library/UI/Fall14/HW7.11.pg

Find all values of x for which $\text{rank}(A) = 2$.

$$A = \begin{bmatrix} 2 & 2 & 0 & 7 \\ 4 & 8 & x & 21 \\ -6 & -18 & -12 & -42 \end{bmatrix}$$

$x =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3

- I. 4
- J. none of the above

58. (1 pt) local/Library/UI/Fall14/HW7.12.pg

Suppose that A is a 6×7 matrix which has a null space of dimension 6. The rank of $A =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

59. (1 pt) local/Library/UI/Fall14/HW7.25.pg

Indicate whether the following statement is true or false?

If $S = \text{span}\{u_1, u_2, u_3\}$, then $\dim(S) = 3$.

- A. True
- B. False

60. (1 pt) local/Library/UI/Fall14/HW7.27.pg

Determine the rank and nullity of the matrix.

$$\begin{bmatrix} 2 & -1 & 0 & 1 \\ 5 & 2 & 1 & -4 \\ -1 & -4 & -1 & 6 \\ -8 & -5 & -2 & 9 \end{bmatrix}$$

The rank of the matrix is

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

The nullity of the matrix is

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

61. (1 pt) local/Library/UI/Fall14/HW8.2.pg

Evaluate the following 3×3 determinant. Use the properties of determinants to your advantage.

$$\begin{vmatrix} -7 & 0 & -4 \\ -7 & 0 & 3 \\ -8 & 0 & 2 \end{vmatrix}$$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Does the matrix have an inverse?

- A. No
- B. Yes

62. (1 pt) local/Library/UI/Fall14/HW8.3.pg

Given the matrix $\begin{bmatrix} -2 \\ 0 \\ -1 \\ 0 \\ -4 \\ -4 \\ -1 \\ 0 \\ -2 \end{bmatrix}$

(a) find its determinant

- A. -12
- B. -5
- C. -4
- D. -2
- E. -1
- F. 0
- G. 1
- H. 3
- I. 5
- J. 7
- K. None of those above

(b) Does the matrix have an inverse?

- A. No
- B. Yes

63. (1 pt) local/Library/UI/Fall14/HW8.4.pg

If A and B are 4×4 matrices, $\det(A) = -4$, $\det(B) = 9$, then $\det(AB) =$

- A. -15
- B. -36
- C. -11
- D. -8
- E. -5
- F. 0
- G. 3
- H. 6
- I. 8
- J. 12
- K. None of those above

$\det(-3A) =$

- A. -40
- B. -324
- C. -28
- D. -21
- E. -10
- F. -1
- G. 10
- H. 21
- I. 28
- J. 36
- K. 40
- L. None of those above

$\det(A^T) =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. None of those above

$\det(B^{-1}) =$

- A. -0.5

- B. -0.4
- C. -0.1111111111111111
- D. 0
- E. 0.1111111111111111
- F. 0.4
- G. 0.5
- H. 1
- I. None of those above

$$\det(B^2) =$$

- A. -81
- B. -36
- C. -12
- D. 0
- E. 12
- F. 36
- G. 81
- H. 1024
- I. None of those above

64. (1 pt) local/Library/UI/Fall14/HW8.5.pg

Find the determinant of the matrix

$$A = \begin{bmatrix} -1 & 0 & 0 & 0 \\ -8 & -5 & 0 & 0 \\ -1 & 1 & -4 & 0 \\ 6 & -2 & 8 & 6 \end{bmatrix}.$$

$$\det(A) =$$

- A. -400
- B. -360
- C. -288
- D. 0
- E. 120
- F. -120
- G. 240
- H. 360
- I. 400
- J. None of those above

65. (1 pt) local/Library/UI/Fall14/HW8.7.pg

Suppose that a 4×4 matrix A with rows $v_1, v_2, v_3,$ and v_4 has determinant $\det A = 6$. Find the following determinants:

$$B = \begin{bmatrix} 2v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \det(B) =$$

- A. -18
- B. -15
- C. -12

- D. -9
- E. 0
- F. 9
- G. 12
- H. 15
- I. 18
- J. None of those above

$$C = \begin{bmatrix} v_4 \\ v_1 \\ v_2 \\ v_3 \end{bmatrix} \det(C) =$$

- A. -18
- B. -6
- C. -9
- D. -3
- E. 0
- F. 3
- G. 9
- H. 12
- I. 18
- J. None of those above

$$D = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 + 3v_2 \end{bmatrix} \det(D) =$$

- A. -18
- B. 6
- C. -9
- D. -3
- E. 0
- F. 3
- G. 9
- H. 12
- I. 18
- J. None of those above

66. (1 pt) local/Library/UI/Fall14/HW8.8.pg

Use determinants to determine whether each of the following sets of vectors is linearly dependent or independent.

$$\begin{bmatrix} -1 \\ -4 \end{bmatrix}, \begin{bmatrix} 7 \\ 7 \end{bmatrix},$$

- A. Linearly Dependent
- B. Linearly Independent

$$\begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix}, \begin{bmatrix} -2 \\ -8 \\ -6 \end{bmatrix}, \begin{bmatrix} -5 \\ -19 \\ -11 \end{bmatrix},$$

- A. Linearly Dependent
- B. Linearly Independent

$$\begin{bmatrix} -5 \\ 10 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \end{bmatrix},$$

- A. Linearly Dependent
- B. Linearly Independent

$$\begin{bmatrix} -1 \\ -5 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 10 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 5 \\ 1 \end{bmatrix},$$

- A. Linearly Dependent
- B. Linearly Independent

67. (1 pt) local/Library/UI/Fall14/HW8.10.pg

$$A = \begin{bmatrix} -9 & 2 & 0 & -4 \\ 1 & -2 & 0 & 0 \\ 0 & -7 & 0 & 0 \\ -5 & 9 & 1 & -6 \end{bmatrix}$$

The determinant of the matrix is

- A. -1890
- B. -1024
- C. -630
- D. -28
- E. -210
- F. 0
- G. 324
- H. 630
- I. 1024
- J. None of those above

Hint: Find a good row or column and expand by minors.

68. (1 pt) local/Library/UI/Fall14/HW8.11.pg

Find the determinant of the matrix

$$M = \begin{bmatrix} 3 & 0 & 0 & 2 & 0 \\ 2 & 0 & -3 & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & -1 & -1 \\ 0 & 2 & -2 & 0 & 0 \end{bmatrix}.$$

$\det(M) =$

- A. -48

- B. -35
- C. -20
- D. -10
- E. -5
- F. 5
- G. 18
- H. 20
- I. 81
- J. None of those above

69. (1 pt) local/Library/UI/Fall14/HW8.12.pg

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \end{bmatrix}$$

And now for the grand finale: The determinant of the matrix is

- A. -362880
- B. -5
- C. 0
- D. 5
- E. 20
- F. 30
- G. 40
- H. 362880
- I. None of the above

Hint: Remember that a square linear system has a unique solution if the determinant of the coefficient matrix is non-zero.

A system of equations can have exactly 2 solution.

- A. True
- B. False

A system of linear equations can have exactly 2 solution.

- A. True
- B. False

A system of linear equations has no solution if and only if the last column of its augmented matrix corresponds to a pivot column.

- A. True
- B. False

A system of linear equations has an infinite number of solutions if and only if its associated augmented matrix has a column corresponding to a free variable.

- A. True
- B. False

If a system of linear equations has an infinite number of solutions, then its associated augmented matrix has a column corresponding to a free variable.

- A. True
- B. False

If a linear system has four equations and seven variables, then it must have infinitely many solutions.

- A. True
- B. False

Every linear system with free variables has infinitely many solutions.

- A. True
- B. False

Any linear system with more variables than equations cannot have a unique solution.

- A. True
- B. False

If a linear system has the same number of equations and variables, then it must have a unique solution.

- A. True
- B. False

A vector b is a linear combination of the columns of a matrix A if and only if the equation $Ax = b$ has at least one solution.

- A. True
- B. False

If the columns of an $m \times n$ matrix, A span \mathbb{R}^m , then the equation, $Ax = b$ is consistent for each b in \mathbb{R}^m .

- A. True
- B. False

If A is an $m \times n$ matrix and if the equation $Ax = b$ is inconsistent for some b in \mathbb{R}^m , then A cannot have a pivot position in every row.

- A. True
- B. False

Any linear combination of vectors can always be written in the form Ax for a suitable matrix A and vector x .

- A. True
- B. False

If the equation $Ax = b$ is inconsistent, then b is not in the set spanned by the columns of A .

- A. True
- B. False

If A is an $m \times n$ matrix whose columns do not span \mathbb{R}^m , then the equation $Ax = b$ is inconsistent for some b in \mathbb{R}^m .

- A. True
- B. False

Every linear system with free variables has infinitely many solutions.

- A. True
- B. False

86. (1 pt) local/Library/UI/Fall14/quiz2.2.pg

Find the area of the triangle with vertices (1,3), (8,5), and (4,9).

Area =

- A. 2
- B. 5
- C. 6
- D. 8
- E. 9
- F. 12
- G. 18
- H. 20
- I. 25
- J. None of those above

Hint: The area of a triangle is half the area of a parallelogram. Find the vectors that determine the parallelogram of interest. If you have difficulty, visualizing the problem may be helpful: plot the 3 points.

87. (1 pt) local/Library/UI/Fall14/quiz2.6.pg

Determine if v is an eigenvector of the matrix A .

1. $A = \begin{bmatrix} 5 & -3 & -10 \\ -2 & 4 & 8 \\ 3 & -3 & -8 \end{bmatrix}$, $v = \begin{bmatrix} -1 \\ 1 \\ -1 \end{bmatrix}$

- A. Yes
- B. No

2. $A = \begin{bmatrix} -1 & -2 & 0 \\ 0 & -3 & 0 \\ -6 & -2 & 5 \end{bmatrix}$, $v = \begin{bmatrix} 5 \\ 7 \\ -1 \end{bmatrix}$

- A. Yes
- B. No

3. $A = \begin{bmatrix} 0 & -2 & -4 \\ 10 & 2 & -6 \\ -5 & -2 & 1 \end{bmatrix}$, $v = \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}$

- A. Yes
- B. No

4. $A = \begin{bmatrix} 5 & 1 & 8 \\ 6 & 0 & 8 \\ -3 & -1 & -6 \end{bmatrix}$, $v = \begin{bmatrix} 4 \\ 5 \\ 1 \end{bmatrix}$

- A. Yes
- B. No

88. (1 pt) local/Library/UI/Fall14/quiz2.7.pg

Given that $v_1 = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$ and $v_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ are eigenvectors of the matrix $A = \begin{bmatrix} 24 & 36 \\ -12 & -18 \end{bmatrix}$, determine the corresponding eigenvalues.

a. $\lambda_1 =$

- A. -6
- B. -5
- C. -4
- D. -3
- E. -2
- F. -1
- G. 0
- H. 1
- I. 2
- J. None of those above

b. $\lambda_2 =$

- A. -5
- B. -4
- C. -3
- D. -2
- E. -1
- F. 0
- G. 6
- H. 1
- I. 2
- J. 3
- K. None of those above

89. (1 pt) local/Library/UI/Fall14/volume1.pg

Find the volume of the parallelepiped determined by vectors

$\begin{bmatrix} -3 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ -2 \\ 0 \end{bmatrix}$, and $\begin{bmatrix} 4 \\ -3 \\ -3 \end{bmatrix}$

- A. 18
- B. -5
- C. -4
- D. -2
- E. -1

- F. 0
- G. 1
- H. 3
- I. 5
- J. 7
- K. None of those above

Suppose a 3×5 augmented matrix contains a pivot in every row. Then the corresponding system of equations has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution, or an infinite number of solutions, depending on the system of equations
- H. none of the above

Given the following augmented matrix,

$$A = \begin{bmatrix} 8 & 5 & -2 \\ 7 & 4 & \\ 0 & -7 & 3 \\ 9 & 6 & \\ 0 & 0 & 0 \\ 0 & 1 & \end{bmatrix},$$

the corresponding system of equations has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Given the following augmented matrix,

$$A = \begin{bmatrix} -9 & 3 & 0 \\ 1 & -6 & \\ 0 & 7 & 5 \\ -9 & -2 & \\ 0 & 0 & 0 \\ 7 & -4 & \end{bmatrix},$$

the corresponding system of equations has

- A. No solution
- B. Unique solution

- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose an augmented matrix contains a pivot in the last column. Then the corresponding system of equations has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose a coefficient matrix A contains a pivot in the last column. Then $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose a coefficient matrix A contains a pivot in every row. Then $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose a coefficient matrix A contains a pivot in every column. Then $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose $A\vec{x} = \vec{0}$ has an infinite number of solutions, then given a vector \vec{b} of the appropriate dimension, $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose $A\vec{x} = \vec{b}$ has an infinite number of solutions, then $A\vec{x} = \vec{0}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose $A\vec{x} = \vec{0}$ has a unique solution, then given a vector \vec{b} of the appropriate dimension, $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations

- H. none of the above

Suppose $A\vec{x} = \vec{b}$ has a unique solution, then $A\vec{x} = \vec{0}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose $A\vec{x} = \vec{b}$ has no solution, then $A\vec{x} = \vec{0}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose A is a square matrix and $A\vec{x} = \vec{0}$ has a unique solution, then given a vector \vec{b} of the appropriate dimension, $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions
- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

Suppose A is a square matrix and $A\vec{x} = \vec{0}$ has an infinite number of solutions, then given a vector \vec{b} of the appropriate dimension, $A\vec{x} = \vec{b}$ has

- A. No solution
- B. Unique solution
- C. Infinitely many solutions
- D. at most one solution
- E. either no solution or an infinite number of solutions
- F. either a unique solution or an infinite number of solutions

- G. no solution, a unique solution or an infinite number of solutions, depending on the system of equations
- H. none of the above

104. (1 pt) local/Library/UI/LinearSystems/spanHW4.pg

$$\text{Let } A = \begin{bmatrix} -1 & 2 & 0 \\ 0 & -3 & 3 \\ -5 & 7 & 0 \end{bmatrix}, \text{ and } b = \begin{bmatrix} 6 \\ -5 \\ -1 \end{bmatrix}.$$

Denote the columns of A by a_1, a_2, a_3 , and let $W = \text{span}\{a_1, a_2, a_3\}$.

1. Determine if b is in W
2. Determine if b is in $\{a_1, a_2, a_3\}$

How many vectors are in $\{a_1, a_2, a_3\}$? (For infinitely many, enter -1) _____

How many vectors are in W ? (For infinitely many, enter -1) _____

105. (1 pt) local/Library/UI/MatrixAlgebra/Euclidean/2.3.43.pg

Let A be a matrix with linearly independent columns. Select the best statement.

- A. The equation $Ax = \mathbf{0}$ always has nontrivial solutions.
- B. The equation $Ax = \mathbf{0}$ has nontrivial solutions precisely when it has more columns than rows.
- C. The equation $Ax = \mathbf{0}$ has nontrivial solutions precisely when it is a square matrix.
- D. There is insufficient information to determine if such an equation has nontrivial solutions.
- E. The equation $Ax = \mathbf{0}$ has nontrivial solutions precisely when it has more rows than columns.
- F. The equation $Ax = \mathbf{0}$ never has nontrivial solutions.
- G. none of the above

106. (1 pt) local/Library/UI/MatrixAlgebra/Euclidean/2.3.44.pg

Let A be a matrix with linearly independent columns. Select the best statement.

- A. There is insufficient information to determine if $Ax = \mathbf{b}$ has a solution for all \mathbf{b} .
- B. The equation $Ax = \mathbf{b}$ has a solution for all \mathbf{b} precisely when it has more columns than rows.
- C. The equation $Ax = \mathbf{b}$ has a solution for all \mathbf{b} precisely when it is a square matrix.
- D. The equation $Ax = \mathbf{b}$ never has a solution for all \mathbf{b} .
- E. The equation $Ax = \mathbf{b}$ always has a solution for all \mathbf{b} .
- F. The equation $Ax = \mathbf{b}$ has a solution for all \mathbf{b} precisely when it has more rows than columns.
- G. none of the above

107. (1 pt) local/Library/UI/eigenTF.pg

A is $n \times n$ matrices.

Check the true statements below:

- A. The vector $\mathbf{0}$ is an eigenvector of A if and only if $Ax = 0$ has a nonzero solution
- B. 0 is an eigenvalue of A if and only if $Ax = 0$ has an infinite number of solutions
- C. The vector $\mathbf{0}$ is an eigenvector of A if and only if the columns of A are linearly dependent.
- D. The eigenspace corresponding to a particular eigenvalue of A contains an infinite number of vectors.
- E. A will have at most n eigenvectors.
- F. 0 is an eigenvalue of A if and only if the columns of A are linearly dependent.
- G. 0 is an eigenvalue of A if and only if $\det(A) = 0$
- H. 0 is an eigenvalue of A if and only if $Ax = 0$ has a nonzero solution
- I. The vector $\mathbf{0}$ is an eigenvector of A if and only if $\det(A) = 0$
- J. A will have at most n eigenvalues.
- K. The vector $\mathbf{0}$ can never be an eigenvector of A
- L. 0 can never be an eigenvalue of A .
- M. There are an infinite number of eigenvectors that correspond to a particular eigenvalue of A .

108. (1 pt) local/Library/UI/problem7.pg

A and B are $n \times n$ matrices.

Adding a multiple of one row to another does not affect the determinant of a matrix.

- A. True
- B. False

If the columns of A are linearly dependent, then $\det A = 0$.

- A. True
- B. False

$\det(A + B) = \det A + \det B$.

- A. True
- B. False

Suppose A is a 11×9 matrix. If rank of $A = 7$, then nullity of $A =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

The vector \vec{b} is NOT in $ColA$ if and only if $A\vec{v} = \vec{b}$ does NOT have a solution

- A. True
- B. False

The vector \vec{b} is in $ColA$ if and only if $A\vec{v} = \vec{b}$ has a solution

- A. True
- B. False

Suppose $A = PDP^{-1}$ where D is a diagonal matrix. If $P = [\vec{p}_1 \vec{p}_2 \vec{p}_3]$, then $2\vec{p}_1$ is an eigenvector of A

- A. True
- B. False

Suppose $A = PDP^{-1}$ where D is a diagonal matrix. If $P = [\vec{p}_1 \vec{p}_2 \vec{p}_3]$, then $\vec{p}_1 + \vec{p}_2$ is an eigenvector of A

- A. True
- B. False

Suppose $A = PDP^{-1}$ where D is a diagonal matrix. Suppose also the d_{ii} are the diagonal entries of D . If $P = [\vec{p}_1 \vec{p}_2 \vec{p}_3]$ and $d_{11} = d_{22}$, then $\vec{p}_1 + \vec{p}_2$ is an eigenvector of A

- A. True
- B. False

Suppose $A = PDP^{-1}$ where D is a diagonal matrix. Suppose also the d_{ii} are the diagonal entries of D . If $P = [\vec{p}_1 \vec{p}_2 \vec{p}_3]$ and $d_{22} = d_{33}$, then $\vec{p}_1 + \vec{p}_2$ is an eigenvector of A

- A. True
- B. False

The vector \vec{v} is in $NulA$ if and only if $A\vec{v} = \vec{0}$

- A. True
- B. False

If the equation $A\vec{x} = \vec{b}_1$ has at least one solution and if the equation $A\vec{x} = \vec{b}_2$ has at least one solution, then the equation $A\vec{x} = -6\vec{b}_1 - 3\vec{b}_2$ also has at least one solution.

- A. True
- B. False

Hint: (Instructor hint preview: show the student hint after 0 attempts. The current number of attempts is 0.)
Is $colA$ a subspace? Is $colA$ closed under linear combinations?

If \vec{v}_1 and \vec{v}_2 are eigenvectors of A corresponding to eigenvalue λ_0 , then $2\vec{v}_1 - 5\vec{v}_2$ is also an eigenvector of A corresponding to eigenvalue λ_0 when $2\vec{v}_1 - 5\vec{v}_2$ is not $\vec{0}$.

- A. True
- B. False

Hint: (Instructor hint preview: show the student hint after 0 attempts. The current number of attempts is 0.)
Is an eigenspace a subspace? Is an eigenspace closed under linear combinations?
Also, is $2\vec{v}_1 - 5\vec{v}_2$ nonzero?

If \vec{x}_1 and \vec{x}_2 are solutions to $A\vec{x} = \vec{0}$, then $-8\vec{x}_1 - 9\vec{x}_2$ is also a solution to $A\vec{x} = \vec{0}$.

- A. True
- B. False

Hint: (Instructor hint preview: show the student hint after 0 attempts. The current number of attempts is 0.)
Is $NulA$ a subspace? Is $NulA$ closed under linear combinations?

If \vec{x}_1 and \vec{x}_2 are solutions to $A\vec{x} = \vec{b}$, then $6\vec{x}_1 - 7\vec{x}_2$ is also a solution to $A\vec{x} = \vec{b}$.

- A. True
- B. False

Hint: (Instructor hint preview: show the student hint after 0 attempts. The current number of attempts is 0.)
Is the solution set to $A\vec{x} = \vec{b}$ a subspace even when \vec{b} is not $\vec{0}$? Is the solution set to $A\vec{x} = \vec{b}$ closed under linear combinations even when \vec{b} is not $\vec{0}$?

Find the area of the parallelogram determined by the vectors $\begin{bmatrix} 2.666666666666667 \\ 3 \end{bmatrix}$ and $\begin{bmatrix} 3 \\ 3 \end{bmatrix}$.

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. 5

Use Cramer's rule to solve the following system of equations for x :

$$\begin{aligned} 38x + 9y &= 32 \\ 4x + 1y &= 4 \end{aligned}$$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Which of the following is an eigenvalue of $\begin{bmatrix} -4 & 0 \\ 1 & -6 \end{bmatrix}$.

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Let $A = \begin{bmatrix} 2 & -4 & -5 \\ 0 & -2 & -1 \\ 0 & 0 & 2 \end{bmatrix}$. Is A = diagonalizable?

- A. yes
- B. no
- C. none of the above

Let $A = \begin{bmatrix} 6 & 0 & 12 \\ 0 & 6 & 3 \\ 0 & 0 & 6 \end{bmatrix}$. Is A = diagonalizable?

- A. yes
- B. no
- C. none of the above

Let $A = \begin{bmatrix} 2 & 13 \\ 9 & -9 \end{bmatrix}$. Is A = diagonalizable?

- A. yes
- B. no
- C. none of the above

Hint: (Instructor hint preview: show the student hint after 0 attempts. The current number of attempts is 0.)

You do NOT need to do much work for this problem. You just need to know if the matrix A is diagonalizable. Since A is a 2×2 matrix, you need 2 linearly independent eigenvectors of A to form P . Does A have 2 linearly independent eigenvectors? Note you don't need to know what these eigenvectors are. You don't even need to know the eigenvalues.

Let $A = \begin{bmatrix} -0.904761904761905 & 6.53571428571429 & -4.85714285714286 \\ 1.22751322751323 & -0.761904761904762 & 1.396825396825397 \\ -2.22222222222222 & 5 & -1.66666666666667 \end{bmatrix}$
and let $P = \begin{bmatrix} 9 & -9 & -6 \\ 4 & -8 & 8 \\ 0 & -6 & -5 \end{bmatrix}$.

Suppose $A = PDP^{-1}$. Then if d_{ii} are the diagonal entries of D , $d_{11} =$,

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. 5

Hint: (Instructor hint preview: show the student hint after 0 attempts. The current number of attempts is 0.)

Use definition of eigenvalue since you know an eigenvector corresponding to eigenvalue d_{11} .

Suppose A is a 7×3 matrix. Then $\text{nul } A$ is a subspace of \mathbb{R}^k where $k =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Suppose A is a 2×4 matrix. Then $\text{col } A$ is a subspace of \mathbb{R}^k where $k =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Calculate the dot product: $\begin{bmatrix} 5 \\ 5 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 3 \\ -8 \end{bmatrix}$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Calculate the determinant of $\begin{bmatrix} -2.33333333333333 & 6 \\ & -4 & 9 \end{bmatrix}$.

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2

- H. 3
- I. 4
- J. 5

Suppose $A \begin{bmatrix} 3 \\ 4 \\ -1 \end{bmatrix} = \begin{bmatrix} -3 \\ -4 \\ 1 \end{bmatrix}$. Then an eigenvalue of A is

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Determine the length of $\begin{bmatrix} -1 \\ 3.87298334620742 \end{bmatrix}$.

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. 5

If the characteristic polynomial of $A = (\lambda + 1)^2(\lambda - 6)(\lambda - 8)^9$, then the algebraic multiplicity of $\lambda = 6$ is

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

If the characteristic polynomial of $A = (\lambda - 9)^2(\lambda + 3)(\lambda + 4)^2$, then the geometric multiplicity of $\lambda = -3$ is

- A. -4
- B. -3
- C. -2

- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

If the characteristic polynomial of $A = (\lambda - 5)^7(\lambda + 3)^2(\lambda - 4)^7$, then the algebraic multiplicity of $\lambda = -3$ is

- A. 0
- B. 1
- C. 2
- D. 3
- E. 0 or 1
- F. 0 or 2
- G. 1 or 2
- H. 0, 1, or 2
- I. 0, 1, 2, or 3
- J. none of the above

If the characteristic polynomial of $A = (\lambda + 8)^3(\lambda - 8)^2(\lambda + 2)^5$, then the geometric multiplicity of $\lambda = 8$ is

- A. 0
- B. 1
- C. 2
- D. 3
- E. 0 or 1
- F. 0 or 2
- G. 1 or 2
- H. 0, 1, or 2
- I. 0, 1, 2, or 3
- J. none of the above

Suppose the orthogonal projection of $\begin{bmatrix} -141 \\ 7 \\ -8 \end{bmatrix}$ onto

$\begin{bmatrix} 1 \\ -1 \\ -5 \end{bmatrix}$ is (z_1, z_2, z_3) . Then $z_1 =$

- A. -4
- B. -3
- C. -2
- D. -1
- E. 0
- F. 1
- G. 2
- H. 3
- I. 4
- J. none of the above

Suppose $\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$ is a unit vector in the direction of $\begin{bmatrix} 4 \\ -2 \\ 4.94413232473044 \end{bmatrix}$. Then $u_1 =$

- A. -0.8
- B. -0.6
- C. -0.4
- D. -0.2
- E. 0
- F. 0.2
- G. 0.4
- H. 0.6
- I. 0.8
- J. 1

140. (1 pt) local/Library/UI/volumn2.pg

A and B are $n \times n$ matrices.

Check the true statements below:

- A. $\det A^T = (-1)\det A$.
- B. If A is 3×3 , with columns a_1, a_2, a_3 , then $\det A$ equals the volume of the parallelepiped determined by the vectors a_1, a_2, a_3 .
- C. If A is 3×3 , with columns a_1, a_2, a_3 , then the absolute value of $\det A$ equals the volume of the parallelepiped determined by the vectors a_1, a_2, a_3 .