

$$[14] \text{ 1.) } \det \begin{bmatrix} 4 & 8 & 3 & 4 \\ 5 & 0 & 10 & 4 \\ 2 & 4 & 3 & 1 \\ 2 & 0 & 2 & 1 \end{bmatrix} = \underline{116}$$

$$\det \begin{bmatrix} 4 & 8 & 3 & 4 \\ 5 & 0 & 10 & 4 \\ 2 & 4 & 3 & 1 \\ 2 & 0 & 2 & 1 \end{bmatrix} = \det \begin{bmatrix} 0 & 0 & -3 & 2 \\ 5 & 0 & 10 & 4 \\ 2 & 4 & 3 & 1 \\ 2 & 0 & 2 & 1 \end{bmatrix} = -4 \det \begin{bmatrix} 0 & -3 & 2 \\ 5 & 10 & 4 \\ 2 & 2 & 1 \end{bmatrix}$$

$$= -4[-(-3)\det \begin{bmatrix} 5 & 4 \\ 2 & 1 \end{bmatrix} + 2\det \begin{bmatrix} 5 & 10 \\ 2 & 2 \end{bmatrix}]$$

$$= -4[-(-3)(5 - 8) + 2(10 - 20)] = -4[-(-3)(-3) + 2(-10)] = -4[-9 - 20] = -4[-29] = 116$$

[6] 2a.) The orthogonal projection of the vector $(4, 5)$ onto the vector $(1, 2)$ is $\underline{\left(\frac{14}{5}, \frac{28}{5}\right)}$

$$(4, 5) \cdot (1, 2) = 4 + 10 = 14$$

$$(1, 2) \cdot (1, 2) = 1 + 4 = 5$$

$$\text{proj}_a u = \frac{14}{5}(1, 2) = \left(\frac{14}{5}, \frac{28}{5}\right)$$

[6] 2b.) The orthogonal component of the vector $(4, 5)$ orthogonal to $(1, 2)$ is $\underline{\left(\frac{6}{5}, \frac{-3}{5}\right)}$

$$(4, 5) - \left(\frac{14}{5}, \frac{28}{5}\right) = \left(\frac{6}{5}, \frac{-3}{5}\right)$$

[12] 3.) Solve each of the following system of linear equations by using Gauss-Jordan elimination.

3a.)
$$\begin{aligned} x_2 + 3x_3 &= 1 \\ 3x_1 + 2x_2 &= 0 \\ 6x_1 + 5x_2 + 3x_3 &= 1 \end{aligned}$$

3b.)
$$\begin{aligned} x_2 + 3x_3 &= 1 \\ 3x_1 + 2x_2 &= 0 \\ 6x_1 + 5x_2 + 3x_3 &= 0 \end{aligned}$$

$$\begin{aligned} \begin{bmatrix} 0 & 1 & 3 & 1 & 1 \\ 3 & 2 & 0 & 0 & 0 \\ 6 & 5 & 3 & 1 & 0 \end{bmatrix} &\xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 3 & 2 & 0 & 0 & 0 \\ 0 & 1 & 3 & 1 & 1 \\ 6 & 5 & 3 & 1 & 0 \end{bmatrix} \xrightarrow{R_3 - 2R_1 \rightarrow R_3} \begin{bmatrix} 3 & 2 & 0 & 0 & 0 \\ 0 & 1 & 3 & 1 & 1 \\ 0 & 1 & 3 & 1 & 0 \end{bmatrix} \xrightarrow{R_3 - R_2 \rightarrow R_3} \\ \begin{bmatrix} 3 & 2 & 0 & 0 & 0 \\ 0 & 1 & 3 & 1 & 1 \\ 0 & 0 & 0 & 0 & -1 \end{bmatrix} &\xrightarrow{R_1 - 2R_2 \rightarrow R_1} \begin{bmatrix} 3 & 0 & -6 & -2 & -2 \\ 0 & 1 & 3 & 1 & 1 \\ 0 & 0 & 0 & 0 & -1 \end{bmatrix} \xrightarrow{\frac{R_1}{3} \rightarrow R_1} \begin{bmatrix} 1 & 0 & -2 & -\frac{2}{3} & -\frac{2}{3} \\ 0 & 1 & 3 & 1 & 1 \\ 0 & 0 & 0 & 0 & -1 \end{bmatrix} \end{aligned}$$

Answer 3a.) $x_1 = -\frac{2}{3} + 2t, x_2 = 1 - 3t, x_3 = t$

3b.) no solution

[2] 3c.) If A = coefficient matrix in 1a, does A^{-1} exist? NO

[2] 3d.) If A = coefficient matrix in 1a, $\det A = \underline{0}$

[1] 3d.) The answer to 1a is a hyperplane that lives in R^m where $m = \underline{3}$.

[1] 3e.) The dimension of the hyperplane in 1a is 1.

[5] 3f.) An equation of the hyperplane in 1a in point-parallel vector form is

$$\mathbf{x} = \left(-\frac{2}{3}, 1, 0\right) + t(2, -3, 1)$$

[3] 3g.) Using different numbers, an equivalent equation of the hyperplane in 1a in point-parallel vector form is

$$\mathbf{x} = \left(0, 0, \frac{1}{3}\right) + t(6, -9, 3)$$

Note many other answers are possible. I multiplied $(2, -3, 1)$ by 3 to get the vector $(6, -9, 3)$ which also describes the direction of this line. Any scalar multiple (except 0) of $(2, -3, 1)$ would also describe the direction of this line. I set $t = \frac{1}{3}$ to find that $(0, 0, \frac{1}{3})$ is a point on this line. Any other point on this line could also be used (can choose any value for t to find another point on this line).

[20] 4.) Find and use an LU factorization to solve:

$$\begin{bmatrix} 4 & 8 \\ 3 & 7 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 4 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 8 \\ 3 & 7 \end{bmatrix} \xrightarrow{\frac{R_1}{4} \rightarrow R_1} \begin{bmatrix} 1 & 2 \\ 3 & 7 \end{bmatrix} \xrightarrow{R_2 - 3R_1 \rightarrow R_2} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

Thus $U = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ and $L = \begin{bmatrix} 4 & 0 \\ 3 & 1 \end{bmatrix}$. Check $LU = \begin{bmatrix} 4 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 8 \\ 3 & 7 \end{bmatrix}$

Solve $L(Ux) = b$. Let $Ux = y$. Then 1) Solve $Ly = b$ for y and 2) Solve $Ux = y$ for x .

Step 1) Solve $Ly = b$ for y

$$\begin{bmatrix} 4 & 0 & 4 \\ 3 & 1 & 0 \end{bmatrix} \xrightarrow{\frac{R_1}{4} \rightarrow R_1} \begin{bmatrix} 1 & 0 & 1 \\ 3 & 1 & 0 \end{bmatrix} \xrightarrow{R_2 - 3R_1 \rightarrow R_2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -3 \end{bmatrix}$$

Thus $y = (1, -3)$

Step 2) Solve $Ux = y$ for x .

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{R_1 - 2R_2 \rightarrow R_1} \begin{bmatrix} 1 & 0 & 7 \\ 0 & 1 & -3 \end{bmatrix}$$

Thus $x = (7, -3)$

Check $\begin{bmatrix} 4 & 8 \\ 3 & 7 \end{bmatrix} \begin{bmatrix} 7 \\ -3 \end{bmatrix} = \begin{bmatrix} 4 \\ 0 \end{bmatrix}$

Answer: $L = \begin{bmatrix} 4 & 0 \\ 3 & 1 \end{bmatrix}$

$U = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$

$\mathbf{x} = (7, -3)$

5.) Circle T for True or F for False.

[3] a.) Suppose a homogeneous system of 3 linear equations with 2 unknowns has exactly one solution, then any system with the same coefficients will also have exactly one solution. F

[3] b.) Suppose a homogeneous system of 3 linear equations with 3 unknowns has exactly one solution, then any system with the same coefficients will also have exactly one solution. T

[10] 6.) Suppose $\begin{bmatrix} 1 & 5 & 2 \\ 0 & 1 & 0 \\ 1 & 0 & 3 \end{bmatrix} \begin{bmatrix} 3 & -15 & -2 \\ 0 & 1 & 0 \\ -1 & 5 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

Solve the following system of equations using the method of inverses: $3x_1 - 15x_2 - 2x_3 = 10$
 $x_2 = 0$
 $-x_1 + 5x_2 + x_3 = 2$

Solve $\begin{bmatrix} 3 & -15 & -2 \\ 0 & 1 & 0 \\ -1 & 5 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 10 \\ 0 \\ 2 \end{bmatrix}$

$Ax = b$ implies $A^{-1}Ax = A^{-1}b$. Thus $x = A^{-1}b$.

$$\begin{bmatrix} 1 & 5 & 2 \\ 0 & 1 & 0 \\ 1 & 0 & 3 \end{bmatrix} \begin{bmatrix} 10 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 14 \\ 0 \\ 16 \end{bmatrix}$$

Answer 6.) (14, 0, 16)

[5] 7a.) Given the line $x_1 = 3 + 2t, x_2 = 1 + t, x_3 = 5 + 4t$, then $\mathbf{x} = (3, 1, 5) + t(2, 1, 4)$ and a point on the line is (3, 1, 5)

and a vector describing the direction of the line is (2, 1, 4).

[5] 7b.) A vector perpendicular to (1, 4, 0) and (5, 1, 2) is (8, -2, -19).

$$\det \begin{bmatrix} i & j & k \\ 1 & 4 & 0 \\ 5 & 1 & 2 \end{bmatrix} = i(8 - 0) - j(2 - 0) + k(1 - 20) = 8i - 2j - 19k = (8, -2, -19)$$

[5] 7c.) Find an equation for the plane in point-parallel form that contains the line $x_1 = 3 + 2t, x_2 = 1 + t, x_3 = 5 + 4t$ and is parallel to the line of intersection of the planes $x_1 + 4x_2 + 1 = 0$ and $5x_1 + x_3 + 2x_3 = 0$ (Hint: use the point in 7a and the vectors in 7a and 7b).

Answer 7c.) $\mathbf{x} = (3, 1, 5) + t(2, 1, 4) + s(8, -2, -19)$.

Alternate method:

$$\begin{bmatrix} 1 & 4 & 0 & -1 \\ 5 & 1 & 2 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & -19 & 2 & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 0 & -1 \\ 0 & 1 & -\frac{2}{19} & -\frac{5}{19} \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & \frac{8}{19} & \frac{1}{19} \\ 0 & 1 & -\frac{2}{19} & -\frac{5}{19} \end{bmatrix}$$

Thus in parametric form, the line of intersection of the planes $x_1 + 4x_2 + 1 = 0$ and $5x_1 + x_3 + 2x_3 = 0$ is $x_1 = \frac{1}{19} - \frac{8}{19}t, x_2 = -\frac{5}{19} + \frac{2}{19}t, x_3 = t$.

In point parallel vector form: $\mathbf{x} = (\frac{1}{19}, -\frac{5}{19}, 0) + t(-\frac{8}{19}, \frac{2}{19}, 1)$

Thus $(-\frac{8}{19}, \frac{2}{19}, 1)$ is a vector describing the direction of this line.