

# Study guide for third exam

Math 2374, Fall 2006

## 1. Cylindrical and spherical coordinates (Section 11.8)

(a) We'll use them for changing variables.

(b) ~~Sample book problems: 1.4 #4, #12~~

## 2. Change of variables (Section 13.9)

(a) In double integrals

i. Key idea: Evaluate integral in new region over new coordinates with

area measure  $dA = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$ .

ii. Formula:  $\iint_D f(x,y) dx dy = \iint_{D^*} f(\mathbf{T}(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$ .

iii. Important special case: polar coordinates, where  $dx dy = r dr d\theta$ .

(b) In triple integrals

i. Key idea: Evaluate integral in new region over new coordinates with new

volume measure  $dV = \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| du dv dw$ .

ii. Formula:  $\iiint_W f(x,y,z) dx dy dz = \iiint_{W^*} f(\mathbf{T}(u,v,w)) \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| du dv dw$ .

iii. Important special cases: cylindrical coordinates ( $dx dy dz = r dr d\theta dz$ ),  
spherical coordinates ( $dx dy dz = \rho^2 \sin \varphi d\rho d\varphi d\theta$ )

~~(c) Sample book problems: 6.1 #2, 6.2 #2, #14, #23, #26, #30~~

## 3. Parametrized surfaces (~~Section 7.3~~)

(a) Parametrize key surfaces: spheres, cylinders, cones, planes, surface of form  $z = h(x,y)$ .

(b) Tangent vectors:  $\mathbf{T}_u = \frac{\partial \Phi}{\partial u}$  and  $\mathbf{T}_v = \frac{\partial \Phi}{\partial v}$

(c) Normal vector:  $\mathbf{N} = \mathbf{T}_u \times \mathbf{T}_v$

(d) Use normal vector to find equation for tangent plane

(e) Unit normal vector  $\mathbf{n} = \frac{\mathbf{T}_u \times \mathbf{T}_v}{\|\mathbf{T}_u \times \mathbf{T}_v\|}$  specifies orientation. Positive side of surface is side with normal.

~~(f) Sample book problems: 7.3 #3, #7, #14~~

## 4. Surface area of a parametrized surface (Section 13.8)

(a) Key idea: surface area element of  $\mathbf{x} = \Phi(u,v)$  is  $dS = \|\mathbf{T}_u \times \mathbf{T}_v\| du dv$

(b) Formula: Surface area  $\iint_D \|\mathbf{T}_u \times \mathbf{T}_v\| du dv$ .

~~(c) Sample book problems: 7.4 #5, #8, #13~~

5. Surface integrals of scalar-valued function (Section 14.5)

(a) Key idea: Integrate  $f(\mathbf{x})$  across surface (i.e.,  $f(\Phi(u, v))$ ) using above  $dS$ .

(b) Formula:  $\iint_S f dS = \iint_D f(\Phi(u, v)) \|\mathbf{T}_u \times \mathbf{T}_v\| du dv$ .

(c) Formula for graphs (special case of above formula):

$$\iint_S f dS = \iint_D f(x, y, g(x, y)) \sqrt{1 + \left(\frac{\partial g}{\partial x}\right)^2 + \left(\frac{\partial g}{\partial y}\right)^2} dx dy$$

~~(d) Sample book problems: 7.5 #3, #8, #14~~

6. Surface integrals of vector-valued functions (Section 14.5)

(a) Key idea: Integrate normal component of  $\mathbf{F}(\mathbf{x})$  across surface (i.e.,  $\mathbf{F}(\Phi(u, v)) \cdot \mathbf{n}$ ) using above  $dS$ .

(b) Formula:  $\iint_S \mathbf{F} \cdot d\mathbf{S} = \pm \iint_D \mathbf{F}(\Phi(u, v)) \cdot (\mathbf{T}_u \times \mathbf{T}_v) du dv$ . (minus sign if  $\mathbf{T}_u \times \mathbf{T}_v$  points in the opposite direction as  $\mathbf{n}$ )

(c) Formula for graphs (special case of above formula, upward normal):

$$\iint_S \mathbf{F} \cdot d\mathbf{S} = \iint_D \mathbf{F}(x, y, g(x, y)) \cdot \left(-\frac{\partial g}{\partial x}, -\frac{\partial g}{\partial y}, 1\right) dx dy$$

~~(d) Sample book problems: 7.6 #1, #6, #16~~

~~7. Stokes' Theorem (Section 8.2)~~

~~(a) Key idea 1: to calculate circulation of  $\mathbf{F}$  around closed curve  $C$ , you can choose any surface with boundary  $C$  and calculate flux integral of  $\nabla \times \mathbf{F}$  over surface.~~

~~(b) Key idea 2: if calculating the surface integral of a vector field  $\mathbf{G} = \nabla \times \mathbf{F}$  over a surface  $S$ , then you can either~~

~~i. convert it to the integral of  $\mathbf{F}$  over the boundary  $\partial S$ , or~~

~~ii. change the surface  $S$  to any other surface  $S'$  with the same boundary  $\partial S' = \partial S$  and compute the integral over  $S'$  rather than over  $S$ .~~

~~(c) Need positively oriented boundary: orient using the right hand rule (alternatively, walk on positive side of surface near boundary and surface is on left).~~

~~(d) Formula:  $\int_{\partial S} \mathbf{F} \cdot d\mathbf{s} = \iint_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S}$~~

~~(e) Sample book problems: 8.2 #1, #9, #21, #25~~

8. Conservative vector fields (Section 14.3)

We focused on conservative vector fields in R2 will look at R3 case later.

(a) Key idea: test if a vector field is conservative. If it is, your life got a lot easier (that is, if you're trying to compute a line integral of the vector field).

(b) Fact: if a vector field  $\mathbf{F}$  is conservative, then

i. its line integral depends only on the endpoints (so is zero over closed curves)

ii.  $\mathbf{F} = \nabla f$  for some potential function  $f$ .

iii.  $\int_C \mathbf{F} \cdot d\mathbf{s} = f(\mathbf{q}) - f(\mathbf{p})$ , where  $\mathbf{p}$  and  $\mathbf{q}$  are the endpoints of the path.

(c) Test for conservative vector fields:

- i. In 2D where  $\mathbf{F}$  is defined in all  $\mathbf{R}^2$ :  $\mathbf{F}$  is path-independent if and only if  $\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} = 0$ .
- ~~ii. In 3D where  $\mathbf{F}$  is defined in all  $\mathbf{R}^3$  except for possibly a finite number of points:  $\mathbf{F}$  is path-independent if and only if  $\nabla \times \mathbf{F} = \mathbf{0}$ .~~
- (d) Don't forget the consequence of having a hole through the domain in  $\mathbf{R}^2$ .
- (e) If  $\mathbf{F}$  is conservative, find potential function  $f$  so that  $\nabla f = \mathbf{F}$ .
- ~~(f) Sample book Problems: 8.3 #2, #3, #9, #13(b)~~