

1.) Circle T for true and F for false.

[4] 1a.) The derivative of the polar coordinate transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $T(r, \theta) = (x(r, \theta), y(r, \theta))$ has determinant $|T'(r, \theta)| = r$. T F

[4] 1b.) The derivative of the polar coordinate transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $T(r, \theta) = (x(r, \theta), y(r, \theta))$ has determinant $|T'(r, \theta)| = r^2$. T F

[12] 2.) The base radius r and height h of a right circular **cylinder** are measured as 4m and 20m respectively. There is a possible error of as much as 10% in each of the measurements. Use differentials to estimate the maximum possible error in computing the volume of the **cylinder**.

Answer: _____

1.) Circle T for true and F for false.

[4] 1a.) The maximum value of $f(x, y)$ subject to the constraint $g(x, y) = 0$ could occur at a point P where $\nabla g(P) = 0$. T F

[4] 1b.) The maximum value of $f(x, y)$ subject to the constraint $g(x, y) = 0$ could occur at a point P where $\nabla f(P) = 0$. T F

[12] 2.) Find $\frac{\partial z}{\partial x}$ as functions of x, y , and z , where $z = f(x, y)$ satisfies the equation $xz + yx^2 + yz^2 = y^2$

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$$V = (\text{base})(\text{height}) = \pi r^2 h \qquad dr = 0.4, \quad dh = 2$$

$$\nabla V = \left\langle \frac{\partial V}{\partial r}, \frac{\partial V}{\partial h} \right\rangle = \langle 2\pi r h, \pi r^2 \rangle \qquad \nabla V(4, 20) = \langle 2(4)(20)\pi, (4)^2\pi \rangle = \langle 160\pi, 16\pi \rangle$$

$$dV = \left[\frac{\partial V}{\partial r} \quad \frac{\partial V}{\partial h} \right] \begin{bmatrix} dr \\ dh \end{bmatrix} = \frac{\partial V}{\partial r} dr + \frac{\partial V}{\partial h} dh = 160(0.4)\pi + 16(2)\pi = 16(6)\pi = 96\pi$$

Answer: 96π

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[12] 2.) Find $\frac{\partial z}{\partial x}$ as functions of x, y , and z , where $z = f(x, y)$ satisfies the equation $xz + yx^2 + yz^2 = y^2$

Note: x, y are independent variables, while z depends on x and y . Thus z is a function of x , while y is treated as a constant when computing $\frac{\partial}{\partial x}$

$$\begin{aligned} \frac{\partial}{\partial x}(xz + yx^2 + yz^2) &= \frac{\partial}{\partial x}(y^2) & \frac{\partial}{\partial x}(xz) + \frac{\partial}{\partial x}(yx^2) + \frac{\partial}{\partial x}(yz^2) &= 0 \\ (z + x\frac{\partial z}{\partial x}) + (2yx) + (2y\frac{\partial z}{\partial x}) &= 0 \end{aligned}$$

Note due to chain rule, it will always be easy to solve for $\frac{\partial z}{\partial x}$ by factoring it out:

$$\frac{\partial z}{\partial x}(x + 2y) = -z - 2xy \qquad \text{Thus } \frac{\partial z}{\partial x} = \frac{-z-2xy}{x+2y}$$

Answer: $\frac{\partial z}{\partial x} = \frac{-z-2xy}{x+2y}$