

A *scalar field* on \mathbf{R}^n is a function $f : \mathbf{R}^n \rightarrow \mathbf{R}$.

Visualized by drawing graph in $\mathbf{R}^n \times \mathbf{R}$ or by drawing level sets in domain \mathbf{R}^n .

A *vector field* on \mathbf{R}^n is a function $F : \mathbf{R}^n \rightarrow \mathbf{R}^n$.

Visualized by drawing vectors in domain \mathbf{R}^n .

Vector Fields can represent many things

Example 1: multiple paths.

Vectors represent velocity (tangent) vectors of paths.

Defn: A *flow line* of a vector field $F : \mathbf{R}^n \rightarrow \mathbf{R}^n$ is a differentiable path $\mathbf{x} : I \subset \mathbf{R} \rightarrow \mathbf{R}^n$ such that

$$\mathbf{x}'(t) = F(\mathbf{x}(t))$$

That is that tangent vector to \mathbf{x} at time t is $\mathbf{x}'(t) = F(\mathbf{x}(t))$.

Ex 8 (p. 212): $F : \mathbf{R}^2 \rightarrow \mathbf{R}^2$, $F(x, y) = (-y, x)$

To find flow line(s) need $\mathbf{x} : \mathbf{R} \rightarrow \mathbf{R}^n$ such that $\mathbf{x}'(t) = F(\mathbf{x}(t))$

$$\text{I.e, need } (x'(t), y'(t)) = F(x(t), y(t))$$

$$\text{I.e, need } (x'(t), y'(t)) = (-y(t), x(t))$$

That is need to solve $x'(t) = -y(t)$ and $y'(t) = x(t)$.

Solution: $\mathbf{x}(t) = (a \cos t - b \sin t, a \sin t + b \cos t)$

Check: $\mathbf{x}'(t) = (-a \sin t - b \cos t, a \cos t - b \sin t)$

$$F(\mathbf{x}(t)) = F(a \cos t - b \sin t, a \sin t + b \cos t) = (-a \sin t - b \cos t, a \cos t - b \sin t)$$

Example 2: A vector field can represent a gradient field.

Vectors = ∇f , for some scalar field f .

Defn: A *gradient field* on \mathbf{R}^n is a vector field $F : \mathbf{R}^n \rightarrow \mathbf{R}^n$ such that $F(x, y) = \nabla f$, for some scalar field $f : \mathbf{R}^n \rightarrow \mathbf{R}$

f is called the *potential function* for F .

Ex: $f : \mathbf{R}^2 \rightarrow \mathbf{R}$, $f(x, y) = x^2 + 3y^2$, $\nabla f = (2x, 6y)$.

$F : \mathbf{R}^2 \rightarrow \mathbf{R}^2$, $F(x, y) = (2x, 6y)$ is a gradient field with potential function f .

Equipotential set of F = level set of f .

Thus the vector $F(x, y)$ is perpendicular to an equipotential set of F = level set of f since $F(x, y) = \nabla f$ points in the direction of steepest ascent for the terrain described by the graph of f in $\mathbf{R}^2 \times \mathbf{R}$.

Magnitude of the vector $F(x, y)$ indicate the steepness of the slope

Calc 1 Review:

Taylor's Thm for $f : \mathbf{R} \rightarrow \mathbf{R}$. Suppose $f \in C^k$,

$$\text{Let } p_k(x) = f(a) + f'(a)(x-a) + \dots + \frac{f^{(k)}(a)}{k!}(x-a)^k$$

Then $f(x) = p_k(x) + R_k(x, a)$ where $\lim_{x \rightarrow a} \frac{R_k(x, a)}{(x-a)^k} = 0$.

Prop 1.2: If $f^{(k+1)}$ exists, then there exists c between a and x such that $R_k(x, a) = \frac{f^{(k+1)}(c)}{(k+1)!}(x-a)^{k+1}$

Estimate $\ln(2)$ using degree 3 Taylor polynomial for $f(x) = \ln(x)$ about $a = 1$

$$f(x) = \ln(x) \quad f'(x) = x^{-1} \quad f''(x) = -x^{-2} \quad f'''(x) = 2x^{-3}$$

$$p_3(x) =$$

Thus $\ln(2) \sim p_3(2) =$

$$\ln(x) = p_3(x) + R_3(x-1)$$

$$f^{(4)}(x) = -6x^{-4} = -\frac{6}{x^4}$$

$$R_3(x-1) = \frac{f^{(4)}(c)}{(4)!}(x-1)^4 =$$

where c is btwn 1 and 2.

$$\ln(2) = p_3(2) + R_3(2, 1) =$$

where $c \in (1, 2)$

Multivariable version:

Taylor's Thm for $f : \mathbf{R} \rightarrow \mathbf{R}$. Suppose $f \in C^k$,

$$\text{Let } p_k(\mathbf{x}) = f(\mathbf{a}) + \sum_{i=1}^n f_{x_i}(\mathbf{a})(x_i - a_i) + \dots$$

$$+ \frac{1}{k!} \sum_{i_1, \dots, i_k=1}^n f_{i_1 \dots i_k}(\mathbf{a})(x_{i_1} - a_{i_1}) \dots (x_{i_k} - a_{i_k})$$

Then $f(\mathbf{x}) = p_k(\mathbf{x}) + R_k(\mathbf{x}, \mathbf{a})$ where $\lim_{\mathbf{x} \rightarrow \mathbf{a}} \frac{R_k(\mathbf{x}, \mathbf{a})}{\|\mathbf{x} - \mathbf{a}\|^k} = 0$.

If $f : \mathbf{R}^n \rightarrow \mathbf{R} \in C^2$, then

$$R_1(\mathbf{x}, \mathbf{a}) = \frac{1}{2} \sum_{i,j=1}^n f_{x_i x_j}(\mathbf{c})(x_i - a_i)(x_j - a_j)$$

for some \mathbf{c} on the line segment joining \mathbf{a} and \mathbf{x} .

If $f : \mathbf{R}^n \rightarrow \mathbf{R} \in C^{k+1}$, then

$$(x_{i_{k+1}} - a_{i_{k+1}})$$

$$R_k(\mathbf{x}, \mathbf{a}) = \frac{1}{(k+1)!} \sum_{i_1, \dots, i_{k+1}=1}^n f_{i_1 \dots i_{k+1}}(\mathbf{c})(x_{i_1} - a_{i_1}) \dots (x_{i_{k+1}} - a_{i_{k+1}}) \blacksquare$$

for some \mathbf{c} on the line segment joining \mathbf{a} and \mathbf{x} .