

Section 1.6: \mathbf{R}^n

Thm (Cauchy-Schwarz Inequality): Let \mathbf{u} and $\mathbf{v} \in \mathbf{R}^n$.
Then

$$\mathbf{u} \cdot \mathbf{v} \leq \|\mathbf{u}\| \|\mathbf{v}\|$$

Recall in \mathbf{R}^2 and in \mathbf{R}^3 , $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$

Thm (Triangle Inequality): Let \mathbf{u} and $\mathbf{v} \in \mathbf{R}^n$. Then

$$\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$$

A matrix is a vector of vectors

Example of a 2×3 matrix:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \qquad \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \qquad \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix}$$

Operations on Matrices

$$A = (a_{ij}), B = (b_{ij}), C = (c_{ij}).$$

Defn: Two matrices A and B are equal, if they have the same size and $a_{ij} = b_{ij}$ for all $i = 1, \dots, n, j = 1, \dots, m$

$$\text{Defn: } A + B = (a_{ij} + b_{ij}).$$

$$\text{Defn: } cA = (ca_{ij}).$$

$$\text{Defn: } -B = (-1)B.$$

$$\text{Defn: } A - B = A + (-B).$$

Defn: The zero matrix $= 0 = (a_{ij})$ where $a_{ij} = 0$ for all i, j .

Defn: The identity matrix $= I = (a_{ij})$ where $a_{ij} = 0$ for all $i \neq j$ and $a_{ii} = 1$ for all i and I is a square matrix.

The transpose of the $m \times n$ matrix $A = A^T = (a_{ji})$.

Suppose A is an $n \times r$ matrix, B is an $r \times n$. $AB = C$ where

$$c_{ij} = \text{row}(i) \text{ of } A \cdot \text{column}(j) \text{ of } B$$

$$= a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{ir}b_{rj}.$$

Ex: $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 10 & 1 \\ 0 & 4 \end{bmatrix} =$

j th column of $AB = A[j\text{th column of } B]$

In other words $AB = A[b_1 \dots b_n] = [Ab_1 \dots Ab_n]$

i th row of $AB = [i\text{th row of } A]B$

In other words $AB = \begin{bmatrix} a(1) \\ \cdot \\ \cdot \\ a(n) \end{bmatrix} B = \begin{bmatrix} a(1)B \\ \cdot \\ \cdot \\ a(n)B \end{bmatrix}$

Thm (Properties of matrix arithmetic) Let A, B, C be matrices. Let a, b be scalars. Assuming that the following operations are defined, then

- a.) $A + B = B + A$
- b.) $A + (B + C) = (A + B) + C$
- c.) $A + 0 = A$
- d.) $A + (-A) = 0$
- e.) $A(BC) = (AB)C$
- f.) $AI = A, IB = B$
- g.) $A(B + C) = AB + AC,$
 $(B + C)A = BA + CA$
- h.) $a(B + C) = aB + aC$
- i.) $(a + b)C = aC + bC$
- j.) $(ab)C = a(bC)$
- k.) $a(AB) = (aA)B = A(aB)$
- l.) $1A = A$
- Cor.) $A0 = 0, 0B = 0$
- a.) $(A^T)^T = A$
- c.) $(kA)^T = kA^T$

Defn.) $-A = -1A$

Cor.) $a0 = 0$

b.) $(A + B)^T = A^T + B^T$

d.) $(AB)^T = B^T A^T$

Note

$$AB \neq BA$$

It is also possible that $AB = AC$, but $B \neq C$.

In particular it is possible for $AB = 0$, but $A \neq 0$ AND $B \neq 0$

Defn: A is invertible if there exists a matrix B such that $AB = BA = I$, and B is called the inverse of A . If the inverse of A does not exist, then A is said to be singular.

$$\text{Ex: } \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} 7 & -3 \\ -2 & 1 \end{bmatrix} =$$

Note that if A is invertible, then A is a square matrix.

Thm: If A is invertible, then its inverse is unique.

Proof: Suppose $AB = I$ and $CA = I$. Then, $B = IB = CAB = CI = C$.

Defn: A **linear transformation** is a function $T : \mathbf{R}^n \rightarrow \mathbf{R}^m$ that satisfies the following two conditions. For each \mathbf{u} and \mathbf{v} in \mathbf{R}^n and scalar a ,

i.) $T(a\mathbf{u}) = aT(\mathbf{u})$

ii.) $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$

Thm: Let $T : V \rightarrow W$ be a linear transformation. Then $T(\mathbf{0}) = \mathbf{0}$

Pf: $T(\mathbf{0}) = T(\mathbf{0} + \mathbf{0}) = T(\mathbf{0}) + T(\mathbf{0})$

Thm: Let A be an $m \times n$ matrix. Then the function

$$\begin{aligned} T : \mathbf{R}^n &\rightarrow \mathbf{R}^m \\ T(\mathbf{x}) &= A\mathbf{x} \end{aligned}$$

is a linear transformation.

Prove that $T : \mathbf{R}^3 \rightarrow \mathbf{R}^2$, $T(x, y, z) = (4x - 5y, 8)$ is NOT a linear transformation.

Examples of linear transformations:

Thm 4.3.3: If $T : R^n \rightarrow R^m$ is a linear transformation, then $T(\mathbf{x}) = A\mathbf{x}$ where $A = [T(\mathbf{e}_1) \dots T(\mathbf{e}_n)]$.

Proof: Let $\mathbf{x} = \begin{bmatrix} x_1 \\ \cdot \\ \cdot \\ \cdot \\ x_n \end{bmatrix} = x_1\mathbf{e}_1 + \dots + x_n\mathbf{e}_n$.

Thus $T(\mathbf{x}) = T(x_1\mathbf{e}_1 + \dots + x_n\mathbf{e}_n)$
 $= x_1T(\mathbf{e}_1) + \dots + x_nT(\mathbf{e}_n)$
 $= [T(\mathbf{e}_1) \dots T(\mathbf{e}_n)] \begin{bmatrix} x_1 \\ \cdot \\ \cdot \\ \cdot \\ x_n \end{bmatrix}$

Ex: If $T : \mathbf{R}^2 \rightarrow \mathbf{R}$ is a linear transformation and $T(1, 0) = 3$, $T(0, 1) = 4$, then

$$T(x, y) = xT(1, 0) + yT(0, 1) = 3x + 4y = (3, 4) \begin{pmatrix} x \\ y \end{pmatrix}$$