

$\mathbf{R}^n$  a vector space over  $\mathbf{R}$  (or  $\mathbf{C}$ ) with canonical basis  $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  where  $\mathbf{e}_i = (0, \dots, 0, 1, 0, \dots, 0)$

Inner product on  $\mathbf{R}^n$ :  $(\mathbf{x}, \mathbf{y}) = \sum_{i=1}^n x_i y_i$

The basis is orthonormal:  $(\mathbf{e}_i, \mathbf{e}_j) = \delta_{ij} = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$

$d(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\| = (\mathbf{x}, \mathbf{y})^{\frac{1}{2}}$

The *norm* of  $\mathbf{x} = \|\mathbf{x}\| = \mathbf{d}(\mathbf{x}, \mathbf{0})$

$B_\epsilon^n(\mathbf{x}) = \{\mathbf{y} \in \mathbf{R}^n \mid \mathbf{d}(\mathbf{x}, \mathbf{y}) < \epsilon\}$  = ball of radius  $\epsilon$  centered at  $\mathbf{x}$ .

$C_\epsilon^n(\mathbf{x}) = \{\mathbf{y} \in \mathbf{R}^n \mid |x_i - y_i| < \epsilon, i = 1, \dots, n\}$  = cube of side  $2\epsilon$  centered at  $\mathbf{x}$ .

$\mathbf{R}^1 = \mathbf{R}, \mathbf{R}^0 = \{\mathbf{0}\}$ .

I.2

$\mathbf{R}^n = \mathbf{E}^n$  where a coordinate system is defined on  $\mathbf{E}^n$

A property is *Euclidean* if it does not depend on the choice of an orthonormal coordinate system.

I.3 Topological Manifolds

Defn:  $M$  is *locally Euclidean of dimension  $n$*  if for all  $p \in M$ , there exists an open set  $U_p$  such that  $p \in U_p$  and there exists a homeomorphism  $f_p : U_p \rightarrow V_p$  where  $V_p \subset \mathbf{R}^n$ .

Defn 3.1: An  *$n$ -manifold*,  $M$ , is a topological space with the following properties:

- 1.)  $M$  is locally Euclidean of dimension  $n$ .
- 2.)  $M$  is Hausdorff.
- 3.)  $M$  has a countable basis.

Give an example of a locally Euclidean space which is not Hausdorff:

Ex 3.2: If  $U$  is an open subset of an  $n$ -manifold, then  $U$  is also an  $n$ -manifold.

Ex 3.3:  $S^n = \{\mathbf{x} \in \mathbf{R}^{n+1} \mid \|\mathbf{x}\| = 1\}$  is an \_\_\_\_\_ manifold

Proof. stereographic projection:

projection:

Remark 3.5. For a “smooth” manifold,  $M \subset \mathbf{R}^n$ , can choose a projection by using the fact that for all  $p \in M$  there exists a unit normal vector  $N_p$  and tangent plane  $T_p(M)$  which varies continuously with  $p$ .

Example: smooth and non-smooth curve.

Example 3.4: The product of two manifolds is also a manifold.

Example: Torus =  $S^1 \times S^1$ .

Theorem 3.6: A manifold is

1.) locally connected, 2.) locally compact, 3.) a union of a countable collection of compact subsets, 4.) normal, and 5.) metrizable.

Defn:  $X$  is **locally connected at**  $x$  if for every neighborhood  $U$  of  $x$ , there exists connected open set  $V$  such that  $x \in V \subset U$ .  $X$  is **locally connected** if  $x$  is locally connected at each of its points.

Defn:  $X$  is **locally compact at**  $x$  if there exists a compact set  $C \subset X$  and a set  $V$  open in  $X$  such that  $x \in V \subset C$ .  $X$  is **locally compact** if it is locally compact at each of its points.

Defn:  $X$  is **regular** if one-point sets are closed in  $X$  and if for all closed sets  $B$  and for all points  $x \notin B$ , there exist disjoint open sets,  $U, V$ , such that  $x \in U$  and  $B \subset V$ .

Defn:  $X$  is **normal** if one-point sets are closed in  $X$  and if for all pairs of disjoint closed sets  $A, B$ , there exist disjoint open sets,  $U, V$ , such that  $A \subset U$  and  $B \subset V$ .

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Brouwer’s Theorem on Invariance of Domain (1911). If  $\mathbf{R}^n = \mathbf{R}^m$ , then  $n = m$ .

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Recall:  $M$  is *locally Euclidean of dimension*  $n$  if for all  $p \in M$ , there exists an open set  $U_p$  such that  $p \in U_p$  and there exists a homeomorphism  $f : U_p \rightarrow V_p$  where  $V_p \subset \mathbf{R}^n$ .

$(U_p, f)$  is a *coordinate nbhd* of  $p$ .

Given  $(U_p, f)$  Let  $q \in U \subset M$ .  $f(q) = (f_1(q), f_2(q), \dots, f_n(q)) \in \mathbf{R}^n$  are the *coordinates* of  $q$ .

#### I.4 Manifolds with boundary and Cutting and Pasting

If  $\dim M = 0$ , then  $M =$

If  $M$  is connected and  $\dim M = 1$ , then

Thm 4.1: Every compact, connected, orientable 2-manifold is homeomorphic to a sphere, or to a connected sum of tori, or to a connected sum of projective planes

Let upper half-space,  $H^n = \{(x_1, x_2, \dots, x_n) \in \mathbf{R}^n \mid x_n \geq 0\}$ ,

$$\partial H^n = \{(x_1, x_2, \dots, x_{n-1}, 0) \in \mathbf{R}^n\} \sim \mathbf{R}^{n-1}$$

$M$  is a manifold with boundary if it is Hausdorff, has a countable basis, and if for all  $p \in U$ , there exists an open set  $U_p$  such that  $p \in U_p$  and there exists a homeomorphism  $f : U_p \rightarrow V_p$  one of the following holds:

- i.)  $V_p \subset H^n - \partial H^n$  ( $p$  is an interior point) or
- ii.)  $V_p \subset H^n$  and  $f(p) \in \partial H^n$  ( $p$  is a boundary point).

$\partial M =$  set of all boundary points of  $M$  is an  $(n-1)$ -dimensional manifold.