

Summary of sections 3.1, 3, 4: Solve linear homogeneous 2nd order DE with constant coefficients.

Solve $ay'' + by' + cy = 0$. Educated guess $y = e^{rt}$, then

$$ar^2e^{rt} + bre^{rt} + ce^{rt} = 0 \text{ implies } ar^2 + br + c = 0,$$

Suppose $r = r_1, r_2$ are solutions to $ar^2 + br + c = 0$

$$r_1, r_2 = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

If $r_1 \neq r_2$, then $b^2 - 4ac \neq 0$. Hence a general solution is $y = c_1e^{r_1t} + c_2e^{r_2t}$

If $b^2 - 4ac > 0$, general solution is $y = c_1e^{r_1t} + c_2e^{r_2t}$.

If $b^2 - 4ac < 0$, change format to linear combination of real-valued functions instead of complex valued functions by using Euler's formula.

general solution is $y = c_1e^{dt}\cos(nt) + c_2e^{dt}\sin(nt)$ where $r = d \pm in$

If $b^2 - 4ac = 0$, $r_1 = r_2$, so need 2nd (independent) solution: te^{r_1t}

Hence general solution is $y = c_1e^{r_1t} + c_2te^{r_1t}$.

Initial value problem: use $y(t_0) = y_0$, $y'(t_0) = y'_0$ to solve for c_1, c_2 to find unique solution.

Examples:

Ex 1: Solve $y'' - 3y' - 4y = 0$, $y(0) = 1$, $y'(0) = 2$.

If $y = e^{rt}$, then $y' = re^{rt}$ and $y'' = r^2e^{rt}$.

$$r^2e^{rt} - 3re^{rt} - 4e^{rt} = 0$$

$r^2 - 3r - 4 = 0$ implies $(r - 4)(r + 1) = 0$. Thus $r = 4, -1$

Hence general solution is $y = c_1e^{4t} + c_2e^{-t}$

Solution to IVP:

Need to solve for 2 unknowns, c_1 & c_2 ; thus need 2 eqns:

$$y = c_1e^{4t} + c_2e^{-t}, \quad y(0) = 1 \quad \text{implies} \quad 1 = c_1 + c_2$$

$$y' = 4c_1e^{4t} - c_2e^{-t}, \quad y'(0) = 2 \quad \text{implies} \quad 2 = 4c_1 - c_2$$

Thus $3 = 5c_1$ & hence $c_1 = \frac{3}{5}$ and $c_2 = 1 - c_1 = 1 - \frac{3}{5} = \frac{2}{5}$

$$\text{Thus IVP soln: } y = \frac{3}{5}e^{4t} + \frac{2}{5}e^{-t}$$

Ex 2: Solve $y'' - 3y' + 4y = 0$.

$y = e^{rt}$ implies $r^2 - 3r + 4 = 0$ and hence

$$r = \frac{3 \pm \sqrt{(-3)^2 - 4(1)(4)}}{2} = \frac{3}{2} \pm \frac{\sqrt{9-16}}{2} = \frac{3}{2} \pm i\frac{\sqrt{7}}{2}$$

Hence general sol'n is $y = c_1e^{\frac{3}{2}t}\cos\left(\frac{\sqrt{7}}{2}t\right) + c_2e^{\frac{3}{2}t}\sin\left(\frac{\sqrt{7}}{2}t\right)$

Ex 3: $y'' - 6y' + 9y = 0$ implies $r^2 - 6r + 9 = (r - 3)^2 = 0$

Repeated root, $r = 3$ implies

$$\text{general solution is } y = c_1e^{3t} + c_2te^{3t}$$

So why did we guess $y = e^{rt}$?

Goal: Solve linear homogeneous 2nd order DE with constant coefficients,

$$ay'' + by' + cy = 0 \text{ where } a, b, c \text{ are constants}$$

Standard mathematical technique: make up simpler problems and see if you can generalize to the problem of interest. ■

Ex: linear homogeneous 1st order DE: $y' + 2y = 0$

integrating factor $u(t) = e^{\int 2dt} = e^{2t}$

$$y'e^{2t} + 2e^{2t}y = 0$$

$(e^{2t}y)' = 0$. Thus $\int (e^{2t}y)' dt = \int 0 dt$. Hence $e^{2t}y = C$

So $y = Ce^{-2t}$.

Thus exponential function could also be a solution to a linear homogeneous 2nd order DE

Ex: Simple linear homog 2nd order DE $y'' + 2y' = 0$.

Let $v = y'$, then $v' = y''$

$y'' + 2y' = 0$ implies $v' + 2v = 0$ implies $v = e^{-2t}$.

Thus $v = y' = \frac{dy}{dt} = Ce^{-2t}$. Hence $dy = Ce^{-2t} dt$ and

$$y = c_1 e^{-2t} + c_2.$$

$$y = c_1 e^{-2t} + c_2.$$

Note 2 integrations give us 2 constants.

Note also that the general solution is a linear combination of two solutions:

Let $c_1 = 1$, $c_2 = 0$, then we see, $y(t) = e^{-2t}$ is a solution.

Let $c_1 = 0$, $c_2 = 1$, then we see, $y(t) = 1$ is a solution.

The general solution is a linear combination of two solutions:

$$y = c_1 e^{-2t} + c_2(1).$$

Recall: you have seen this before:

Solve linear homogeneous matrix equation $A\mathbf{y} = \mathbf{0}$.

The general solution is a linear combination of linearly independent vectors that span the solution space:

$$\mathbf{y} = c_1 \mathbf{v}_1 + \dots c_n \mathbf{v}_n$$

FYI: You could see this again:

Math 4050: Solve homogeneous linear recurrence relation $x_n - x_{n-1} - x_{n-2} = 0$ where $x_1 = 1$ and $x_2 = 1$.

Fibonacci sequence: $x_n = x_{n-1} + x_{n-2}$

$$1, 1, 2, 3, 5, 8, 13, 21, \dots$$

Note $x_n = \frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2} \right)^n - \frac{1}{\sqrt{5}} \left(\frac{1-\sqrt{5}}{2} \right)^n$

Proof: $x_n = x_{n-1} + x_{n-2}$ implies $x_n - x_{n-1} - x_{n-2} = 0$

Suppose $x_n = r^n$. Then $x_{n-1} = r^{n-1}$ and $x_{n-2} = r^{n-2}$

Then $0 = x_n - x_{n-1} - x_{n-2} = r^n - r^{n-1} - r^{n-2}$

Thus $r^{n-2}(r^2 - r - 1) = 0$.

Thus either $r = 0$ or $r = \frac{1 \pm \sqrt{1-4(1)(-1)}}{2} = \frac{1 \pm \sqrt{5}}{2}$

Thus $x_n = 0$, $x_n = \left(\frac{1+\sqrt{5}}{2}\right)^n$ and $f_n = \left(\frac{1-\sqrt{5}}{2}\right)^n$

are 3 different sequences that satisfy the

homog linear recurrence relation: $x_n - x_{n-1} - x_{n-2} = 0$.

Hence $x_n = c_1 \left(\frac{1+\sqrt{5}}{2}\right)^n + c_2 \left(\frac{1-\sqrt{5}}{2}\right)^n$ also satisfies this

homogeneous linear recurrence relation.

Suppose the initial conditions are $x_1 = 1$ and $x_2 = 1$

Then for $n = 1$: $x_1 = 1$ implies $c_1 + c_2 = 1$

For $n = 2$: $x_2 = 1$ implies $c_1 \left(\frac{1+\sqrt{5}}{2}\right) + c_2 \left(\frac{1-\sqrt{5}}{2}\right) = 1$

We can solve this for c_1 and c_2 to determine that

$$x_n = \frac{1}{\sqrt{5}} \left(\frac{1+\sqrt{5}}{2}\right)^n - \frac{1}{\sqrt{5}} \left(\frac{1-\sqrt{5}}{2}\right)^n$$

Existence and Uniqueness for LINEAR DEs.

Homogeneous:

$$y^{(n)} + p_1(t)y^{(n-1)} + \dots p_{n-1}(t)y' + p_n(t)y = 0$$

Non-homogeneous: $g(t) \neq 0$

$$y^{(n)} + p_1(t)y^{(n-1)} + \dots p_{n-1}(t)y' + p_n(t)y = g(t)$$

1st order LINEAR differential equation:

Thm 2.4.1: If $p : (a, b) \rightarrow R$ and $g : (a, b) \rightarrow R$ are continuous and $a < t_0 < b$, then there exists a unique function $y = \phi(t)$, $\phi : (a, b) \rightarrow R$ that satisfies the

$$\text{IVP: } y' + p(t)y = g(t), \quad y(t_0) = y_0$$

Thm: If $y = \phi_1(t)$ is a solution to homogeneous equation, $y' + p(t)y = 0$, then $y = c\phi_1(t)$ is the general solution to this equation.

If in addition $y = \psi(t)$ is a solution to non-homogeneous equation, $y' + p(t)y = g(t)$, then $y = c\phi_1(t) + \psi(t)$ is the general solution to this equation.

Partial proof: $y = \phi_1(t)$ is a solution to $y' + p(t)y = 0$ implies

Thus $y = c\phi_1(t)$ is a solution to $y' + p(t)y = 0$ since

$y = \psi(t)$ is a solution to $y' + p(t)y = g(t)$ implies

Thus $y = c\phi_1(t) + \psi(t)$ is a solution to $y' + p(t)y = g(t)$ since

2nd order LINEAR differential equation:

Thm 3.2.1: If $p : (a, b) \rightarrow R$, $q : (a, b) \rightarrow R$, and $g : (a, b) \rightarrow R$ are continuous and $a < t_0 < b$, then there exists a unique function $y = \phi(t)$, $\phi : (a, b) \rightarrow R$ that satisfies the initial value problem

$$\begin{aligned}y'' + p(t)y' + q(t)y &= g(t), \\y(t_0) &= y_0, \\y'(t_0) &= y'_0\end{aligned}$$

Thm 3.2.2: If ϕ_1 and ϕ_2 are two solutions to a homogeneous linear differential equation, then $c_1\phi_1 + c_2\phi_2$ is also a solution to this linear differential equation.

Proof of thm 3.2.2:

Since $y(t) = \phi_i(t)$ is a solution to the linear homogeneous differential equation $y'' + py' + qy = 0$ where p and q are functions of t (note this includes the case with constant coefficients), then

Claim: $y(t) = c_1\phi_1(t) + c_2\phi_2(t)$ is also a solution to $y'' + py' + qy = 0$

Pf of claim:

Second order differential equation:

Linear equation with constant coefficients:

If the second order differential equation is

$$ay'' + by' + cy = 0,$$

then $y = e^{rt}$ is a solution

Need to have two independent solutions.

Solve the following IVPs:

1.) $y'' - 6y' + 9y = 0$ $y(0) = 1, y'(0) = 2$

2.) $4y'' - y' + 2y = 0$ $y(0) = 3, y'(0) = 4$

3.) $4y'' + 4y' + y = 0$ $y(0) = 6, y'(0) = 7$

4.) $2y'' - 2y = 0$ $y(0) = 5, y'(0) = 9$

Summary of sections 3.1, 3, 4: Solve linear homogeneous 2nd order DE with constant coefficients.

Solve $ay'' + by' + cy = 0$. Educated guess $y = e^{rt}$, then

$$ar^2e^{rt} + bre^{rt} + ce^{rt} = 0 \text{ implies } ar^2 + br + c = 0,$$

Suppose $r = r_1, r_2$ are solutions to $ar^2 + br + c = 0$

$$r_1, r_2 = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

If $r_1 \neq r_2$, then $b^2 - 4ac \neq 0$. Hence a general solution is $y = c_1e^{r_1t} + c_2e^{r_2t}$

If $b^2 - 4ac > 0$, general solution is $y = c_1e^{r_1t} + c_2e^{r_2t}$.

If $b^2 - 4ac < 0$, change format to linear combination of real-valued functions instead of complex valued functions by using Euler's formula.

general solution is $y = c_1e^{dt}\cos(nt) + c_2e^{dt}\sin(nt)$ where $r = d \pm in$

If $b^2 - 4ac = 0$, $r_1 = r_2$, so need 2nd (independent) solution: te^{r_1t}

Hence general solution is $y = c_1e^{r_1t} + c_2te^{r_1t}$.

Initial value problem: use $y(t_0) = y_0$, $y'(t_0) = y'_0$ to solve for c_1, c_2 to find unique solution.

Derivation of general solutions:

If $b^2 - 4ac > 0$ we guessed e^{rt} is a solution and noted that any linear combination of solutions is a solution to a homogeneous linear differential equation.

Section 3.3: If $b^2 - 4ac < 0$, :

Changed format of $y = c_1 e^{r_1 t} + c_2 e^{r_2 t}$ to linear combination of real-valued functions instead of complex valued functions by using Euler's formula:

$$e^{it} = \cos(t) + i\sin(t)$$

Hence $e^{(d+in)t} = e^{dt} e^{int} = e^{dt} [\cos(nt) + i\sin(nt)]$

Let $r_1 = d + in$, $r_2 = d - in$

$$\begin{aligned} y &= c_1 e^{r_1 t} + c_2 e^{r_2 t} \\ &= c_1 e^{dt} [\cos(nt) + i\sin(nt)] + c_2 e^{dt} [\cos(-nt) + i\sin(-nt)] \\ &= c_1 e^{dt} \cos(nt) + ic_1 e^{dt} \sin(nt) + c_2 e^{dt} \cos(nt) - ic_2 e^{dt} \sin(nt) \\ &= (c_1 + c_2) e^{dt} \cos(nt) + i(c_1 - c_2) e^{dt} \sin(nt) \\ &= k_1 e^{dt} \cos(nt) + k_2 e^{dt} \sin(nt) \end{aligned}$$

Section 3.4: If $b^2 - 4ac = 0$, then $r_1 = r_2$.

Hence one solution is $y = e^{r_1 t}$ Need second solution.

If $y = e^{rt}$ is a solution, $y = ce^{rt}$ is a solution.

How about $y = v(t)e^{rt}$?

$$y' = v'(t)e^{rt} + v(t)re^{rt}$$

$$\begin{aligned}y'' &= v''(t)e^{rt} + v'(t)re^{rt} + v'(t)re^{rt} + v(t)r^2e^{rt} \\ &= v''(t)e^{rt} + 2v'(t)re^{rt} + v(t)r^2e^{rt}\end{aligned}$$

$$ay'' + by' + cy = 0$$

$$a(v''e^{rt} + 2v're^{rt} + vr^2e^{rt}) + b(v'e^{rt} + vre^{rt}) + cve^{rt} = 0$$

$$a(v''(t) + 2v'(t)r + v(t)r^2) + b(v'(t) + v(t)r) + cv(t) = 0$$

$$av''(t) + 2av'(t)r + av(t)r^2 + bv'(t) + bv(t)r + cv(t) = 0$$

$$av''(t) + (2ar + b)v'(t) + (ar^2 + br + c)v(t) = 0$$

$$av''(t) + (2a(\frac{-b}{2a}) + b)v'(t) + 0 = 0$$

$$\text{since } ar^2 + br + c = 0 \text{ and } r = \frac{-b}{2a}$$

$$av''(t) + (-b + b)v'(t) = 0. \quad \text{Thus } av''(t) = 0.$$

Hence $v''(t) = 0$ and $v'(t) = k_1$ and $v(t) = k_1 t + k_2$

Hence $v(t)e^{r_1 t} = (k_1 t + k_2)e^{r_1 t}$ is a soln

Thus $te^{r_1 t}$ is a nice second solution.

Hence general solution is $y = c_1 e^{r_1 t} + c_2 t e^{r_1 t}$

Solve: $y'' + y = 0$, $y(0) = -1$, $y'(0) = -3$

$r^2 + 1 = 0$ implies $r^2 = -1$. Thus $r = \pm i$.

Since $r = 0 \pm 1i$, $y = k_1 \cos(t) + k_2 \sin(t)$.

Then $y' = -k_1 \sin(t) + k_2 \cos(t)$

$y(0) = -1$: $-1 = k_1 \cos(0) + k_2 \sin(0)$ implies $-1 = k_1$

$y'(0) = -3$: $-3 = -k_1 \sin(0) + k_2 \cos(0)$ implies $-3 = k_2$

Thus IVP solution: $y = -\cos(t) - 3\sin(t)$

When does the following IVP have unique sol'n:

IVP: $ay'' + by' + cy = 0$, $y(t_0) = y_0$, $y'(t_0) = y_1$.

Suppose $y = c_1 \phi_1(t) + c_2 \phi_2(t)$ is a solution to

$$ay'' + by' + cy = 0. \text{ Then } y' = c_1 \phi_1'(t) + c_2 \phi_2'(t)$$

$$y(t_0) = y_0: y_0 = c_1 \phi_1(t_0) + c_2 \phi_2(t_0)$$

$$y'(t_0) = y_1: y_1 = c_1 \phi_1'(t_0) + c_2 \phi_2'(t_0)$$

To find IVP solution, need to solve above system of two equations for the unknowns c_1 and c_2 .

Note the IVP has a unique solution if and only if the above system of two equations has a unique solution for c_1 and c_2 .

Note that in these equations c_1 and c_2 are the unknowns and $y_0, \phi_1(t_0), \phi_2(t_0), y_1, \phi_1'(t_0), \phi_2'(t_0)$ are the constants. We can translate this linear system of equations into matrix form:

$$\begin{aligned} c_1\phi_1(t_0) + c_2\phi_2(t_0) &= y_0 \\ c_1\phi_1'(t_0) + c_2\phi_2'(t_0) &= y_1 \end{aligned} \Rightarrow \begin{bmatrix} \phi_1(t_0) & \phi_2(t_0) \\ \phi_1'(t_0) & \phi_2'(t_0) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \end{bmatrix}$$

Note this equation has a unique solution if and only if

$$\det \begin{bmatrix} \phi_1(t_0) & \phi_2(t_0) \\ \phi_1'(t_0) & \phi_2'(t_0) \end{bmatrix} = \begin{vmatrix} \phi_1 & \phi_2 \\ \phi_1' & \phi_2' \end{vmatrix} = \phi_1\phi_2' - \phi_1'\phi_2 \neq 0$$

Definition: The Wronskian of two differential functions, ϕ_1 and ϕ_2 is

$$W(\phi_1, \phi_2) = \phi_1\phi_2' - \phi_1'\phi_2 = \begin{vmatrix} \phi_1 & \phi_2 \\ \phi_1' & \phi_2' \end{vmatrix}$$

Examples:

$$\begin{aligned} 1.) \quad W(\cos(t), \sin(t)) &= \begin{vmatrix} \cos(t) & \sin(t) \\ -\sin(t) & \cos(t) \end{vmatrix} \\ &= \cos^2(t) + \sin^2(t) = 1 > 0. \end{aligned}$$

$$2.) \quad W(e^{dt}\cos(nt), e^{dt}\sin(nt)) =$$

$$\begin{aligned} &\begin{vmatrix} e^{dt}\cos(nt) & e^{dt}\sin(nt) \\ de^{dt}\cos(nt) - ne^{dt}\sin(nt) & de^{dt}\sin(nt) + ne^{dt}\cos(nt) \end{vmatrix} \\ &= e^{dt}\cos(nt)(de^{dt}\sin(nt) + ne^{dt}\cos(nt)) - e^{dt}\sin(nt)(de^{dt}\cos(nt) - ne^{dt}\sin(nt)) \\ &= e^{2dt}[\cos(nt)(d\sin(nt) + n\cos(nt)) - \sin(nt)(d\cos(nt) - n\sin(nt))] \\ &= e^{2dt}[d\cos(nt)\sin(nt) + n\cos^2(nt) - d\sin(nt)\cos(nt) + n\sin^2(nt)] \\ &= e^{2dt}[n\cos^2(nt) + n\sin^2(nt)] \\ &= ne^{2dt}[\cos^2(nt) + \sin^2(nt)] = ne^{2dt} > 0 \text{ for all } t. \end{aligned}$$

Definition: The Wronskian of two differential functions, f and g is

$$W(f, g) = fg' - f'g = \begin{vmatrix} f & g \\ f' & g' \end{vmatrix}$$

Thm 3.2.3: Suppose that

ϕ_1 and ϕ_2 are two solutions to $y'' + p(t)y' + q(t)y = 0$.

If $W(\phi_1, \phi_2)(t_0) = \phi_1(t_0)\phi_2'(t_0) - \phi_1'(t_0)\phi_2(t_0) \neq 0$, then

there is a unique choice of constants c_1 and c_2 such that $c_1\phi_1 + c_2\phi_2$ satisfies this homogeneous linear differential equation and initial conditions, $y(t_0) = y_0$, $y'(t_0) = y_0'$.

Thm 3.2.4: Given the hypothesis of thm 3.2.1, suppose that ϕ_1 and ϕ_2 are two solutions to

$$y'' + p(t)y' + q(t)y = 0.$$

If $W(\phi_1, \phi_2)(t_0) \neq 0$, for some $t_0 \in (a, b)$, then any solution to this homogeneous linear differential equation can be written as $y = c_1\phi_1 + c_2\phi_2$ for some c_1 and c_2 .

Defn If ϕ_1 and ϕ_2 satisfy the conditions in thm 3.2.4, then ϕ_1 and ϕ_2 form a fundamental set of solutions to $y'' + p(t)y' + q(t)y = 0$.

Thm 3.2.5: Given any second order homogeneous linear differential equation, there exist a pair of functions which form a fundamental set of solutions.

3.3: Linear Independence and the Wronskian

Defn: f and g are linearly dependent if there exists constants c_1, c_2 such that $c_1 \neq 0$ or $c_2 \neq 0$ and

$$c_1 f(t) + c_2 g(t) = 0 \text{ for all } t \in (a, b)$$

Thm 3.3.1: If $f : (a, b) \rightarrow R$ and $g : (a, b) \rightarrow R$ are differentiable functions on (a, b) and if $W(f, g)(t_0) \neq 0$ for some $t_0 \in (a, b)$, then f and g are linearly independent on (a, b) . Moreover, if f and g are linearly dependent on (a, b) , then $W(f, g)(t) = 0$ for all $t \in (a, b)$

If $c_1 f(t) + c_2 g(t) = 0$ for all t , then $c_1 f'(t) + c_2 g'(t) = 0$

Solve the following linear system of equations for c_1, c_2

$$\begin{aligned} c_1 f(t_0) + c_2 g(t_0) &= 0 \\ c_1 f'(t_0) + c_2 g'(t_0) &= 0 \end{aligned}$$

$$\begin{bmatrix} f(t_0) & g(t_0) \\ f'(t_0) & g'(t_0) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Thm: Suppose $c_1\phi_1(t) + c_2\phi_2(t)$ is a general solution to

$$ay'' + by' + cy = 0,$$

If ψ is a solution to

$$ay'' + by' + cy = g(t) \text{ [*]},$$

Then $\psi + c_1\phi_1(t) + c_2\phi_2(t)$ is also a solution to [*].

Moreover if γ is also a solution to [*], then there exist constants c_1, c_2 such that

$$\gamma = \psi + c_1\phi_1(t) + c_2\phi_2(t)$$

Or in other words, $\psi + c_1\phi_1(t) + c_2\phi_2(t)$ is a general solution to [*].

Proof:

Define $L(f) = af'' + bf' + cf$.

Recall L is a linear function.

Let $h = c_1\phi_1(t) + c_2\phi_2(t)$. Since h is a solution to the differential equation, $ay'' + by' + cy = 0$,

Since ψ is a solution to $ay'' + by' + cy = g(t)$,

We will now show that $\psi + c_1\phi_1(t) + c_2\phi_2(t) = \psi + h$ is also a solution to [*].

Since γ a solution to $ay'' + by' + cy = g(t)$,

We will first show that $\gamma - \psi$ is a solution to the differential equation $ay'' + by' + cy = 0$.

Since $\gamma - \psi$ is a solution to $ay'' + by' + cy = 0$ and

$c_1\phi_1(t) + c_2\phi_2(t)$ is a general solution to

$$ay'' + by' + cy = 0,$$

there exist constants c_1, c_2 such that

$$\gamma - \psi = \underline{\hspace{15em}}$$

Thus $\gamma = \psi + c_1\phi_1(t) + c_2\phi_2(t)$.

Thm:

Suppose f_1 is a solution to $ay'' + by' + cy = g_1(t)$ and f_2 is a solution to $ay'' + by' + cy = g_2(t)$, then $f_1 + f_2$ is a solution to $ay'' + by' + cy = g_1(t) + g_2(t)$

Proof: Let $L(f) = af'' + bf' + cf$.

Since f_1 is a solution to $ay'' + by' + cy = g_1(t)$,

Since f_2 is a solution to $ay'' + by' + cy = g_2(t)$,

We will now show that $f_1 + f_2$ is a solution to $ay'' + by' + cy = g_1(t) + g_2(t)$.

Sidenote: The proofs above work even if a, b, c are functions of t instead of constants.

Examples: Find a suitable form for ψ for the following differential equations:

1.) $y'' - 4y' - 5y = 4e^{2t}$

2.) $y'' - 4y' - 5y = t^2 - 2t + 1$

3.) $y'' - 4y' - 5y = 4\sin(3t)$

4.) $y'' - 5y = 4\sin(3t)$

5.) $y'' - 4y' = t^2 - 2t + 1$

6.) $y'' - 4y' - 5y = 4(t^2 - 2t - 1)e^{2t}$

$$7.) y'' - 4y' - 5y = 4\sin(3t)e^{2t}$$

$$8.) y'' - 4y' - 5y = 4(t^2 - 2t - 1)\sin(3t)e^{2t}$$

$$9.) y'' - 4y' - 5y = 4\sin(3t) + 4\sin(3t)e^{2t}$$

$$10.) y'' - 4y' - 5y = 4\sin(3t)e^{2t} + 4(t^2 - 2t - 1)e^{2t} + t^2 - 2t - 1$$

$$11.) y'' - 4y' - 5y = 4\sin(3t) + 5\cos(3t)$$

$$12.) y'' - 4y' - 5y = 4e^{-t}$$

To solve $ay'' + by' + cy = g_1(t) + g_2(t) + \dots g_n(t)$ [**]

1.) Find the general solution to $ay'' + by' + cy = 0$:
$$c_1\phi_1 + c_2\phi_2$$

2.) For each g_i , find a solution to $ay'' + by' + cy = g_i$:
$$\psi_i$$

This includes plugging guessed solution ψ_i into $ay'' + by' + cy = g_i$.

The general solution to [**] is

$$c_1\phi_1 + c_2\phi_2 + \psi_1 + \psi_2 + \dots\psi_n$$

3.) If initial value problem:

Once general solution is known, can solve initial value problem (i.e., use initial conditions to find c_1, c_2).

Solve $y'' - 4y' - 5y = 4\sin(3t)$, $y(0) = 6$, $y'(0) = 7$.

1.) **First solve homogeneous equation:**

Find the general solution to $y'' - 4y' - 5y = 0$:

Guess $y = e^{rt}$ for HOMOGENEOUS equation:

$$y' = re^{rt}, y'' = r^2e^{rt}$$

$$y'' - 4y' - 5y = 0$$

$$r^2e^{rt} - 4re^{rt} - 5e^{rt} = 0$$

$$e^{rt}(r^2 - 4r - 5) = 0$$

$e^{rt} \neq 0$, thus can divide both sides by e^{rt} :

$$r^2 - 4r - 5 = 0$$

$(r + 1)(r - 5) = 0$. Thus $r = -1, 5$.

Thus $y = e^{-t}$ and $y = e^{5t}$ are both solutions to LINEAR HOMOGENEOUS equation.

Thus the general solution to the 2nd order LINEAR HOMOGENEOUS equation is

$$y = c_1e^{-t} + c_2e^{5t}$$

2.) Find one solution to non-homogeneous eq'n:

Find a solution to $ay'' + by' + cy = 4\sin(3t)$:

Guess $y = A\sin(3t) + B\cos(3t)$

$$y' = 3A\cos(3t) - 3B\sin(3t)$$

$$y'' = -9A\sin(3t) - 9B\cos(3t)$$

$$y'' - 4y' - 5y = 4\sin(3t)$$

$$\begin{array}{rcl} -9A\sin(3t) & - & 9B\cos(3t) \\ 12B\sin(3t) & - & 12A\cos(3t) \\ -5A\sin(3t) & - & 5\cos(3t) \end{array}$$

$$(12B - 14A)\sin(3t) - (-14B - 12A)\cos(3t) = 4\sin(3t)$$

Since $\{\sin(3t), \cos(3t)\}$ is a linearly independent set:

$$12B - 14A = 4 \text{ and } -14B - 12A = 0$$

Thus $A = -\frac{14}{12}B = -\frac{7}{6}B$ and

$$12B - 14\left(-\frac{7}{6}B\right) = 12B + 7\left(\frac{7}{3}B\right) = \frac{36+49}{3}B = \frac{85}{3}B = 4$$

$$\text{Thus } B = 4\left(\frac{3}{85}\right) = \frac{12}{85} \text{ and } A = -\frac{7}{6}B = -\frac{7}{6}\left(\frac{12}{85}\right) = -\frac{14}{85}$$

Thus $y = \left(-\frac{14}{85}\right)\sin(3t) + \frac{12}{85}\cos(3t)$ is one solution to the nonhomogeneous equation.

Thus the general solution to the 2nd order linear non-homogeneous equation is

$$y = c_1e^{-t} + c_2e^{5t} - \left(\frac{14}{85}\right)\sin(3t) + \frac{12}{85}\cos(3t)$$

3.) If initial value problem:

Once general solution is known, can solve initial value problem (i.e., use initial conditions to find c_1, c_2).

NOTE: you must know the GENERAL solution to the ODE BEFORE you can solve for the initial values. The homogeneous solution and the one nonhomogeneous solution found in steps 1 and 2 above do NOT need to separately satisfy the initial values.

Solve $y'' - 4y' - 5y = 4\sin(3t)$, $y(0) = 6$, $y'(0) = 7$.

General solution: $y = c_1e^{-t} + c_2e^{5t} - (\frac{14}{85})\sin(3t) + \frac{12}{85}\cos(3t)$

Thus $y' = -c_1e^{-t} + 5c_2e^{5t} - (\frac{42}{85})\cos(3t) - \frac{36}{85}\sin(3t)$

$$y(0) = 6: \quad 6 = c_1 + c_2 + \frac{12}{85} \quad \frac{498}{85} = c_1 + c_2$$

$$y'(0) = 7: \quad 7 = -c_1 + 5c_2 - \frac{42}{85} \quad \frac{637}{85} = -c_1 + 5c_2$$

$$6c_2 = \frac{498+637}{85} = \frac{1135}{85} = \frac{227}{17}. \text{ Thus } c_2 = \frac{227}{102}.$$

$$c_1 = \frac{498}{85} - c_2 = \frac{498}{85} - \frac{227}{102} = \frac{2988-1135}{510} = \frac{1853}{510} = \frac{109}{30}$$

Thus $y = (\frac{109}{30})e^{-t} + (\frac{227}{102})e^{5t} - (\frac{14}{85})\sin(3t) + \frac{12}{85}\cos(3t)$.

Partial Check: $y(0) = (\frac{109}{30}) + (\frac{227}{102}) + \frac{12}{85} = 6$.

$$y'(0) = -\frac{109}{30} + 5(\frac{227}{102}) - \frac{42}{85} = 7.$$

$(e^{-t})'' - 4(e^{-t})' - 5(e^{-t}) = 0$ and $(e^{5t})'' - 4(e^{5t})' - 5(e^{5t}) = 0$

Potential proofs for exam 1:

Proof by (counter) example:

1. Prove a function is not 1:1, not onto, not a bijection, not linear.
 2. Prove that a differential equation can have multiple solutions.
-

Prove convergence of a series using ratio test.

Induction proof.

Prove a function is linear.

Theorem 3.2.2: If $y = \phi_1(t)$ and $y = \phi_2(t)$ are solutions to the 2nd order linear ODE, $ay'' + by' + cy = 0$, then their linear combination $y = c_1\phi_1(t) + c_2\phi_2(t)$ is also a solution for constants c_1 and c_2 .

Note you may use what you know from both pre-calculus and calculus (e.g., integration and derivatives are linear).