

Give that the solution to $x' = \begin{bmatrix} -2 & 0 \\ 21 & 5 \end{bmatrix} x$ is $x = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$

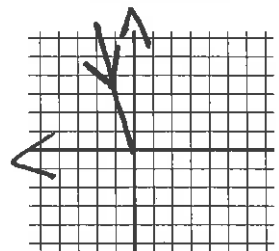
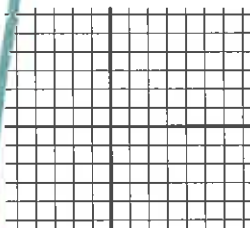
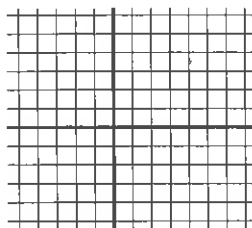
$$\frac{x_2}{x_1} = \frac{3e^{-2t}}{-1e^{-2t}} = x_2 = \frac{3}{-1} x_1$$

Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ in the $\Rightarrow c_1 = 0$ & $c_2 = 1$

t, x_1 -plane $x_1 = -1e^{-2t}$

t, x_2 -plane $x_2 = 3e^{-2t}$

x_1, x_2 -plane

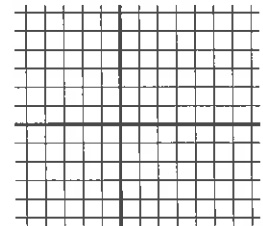
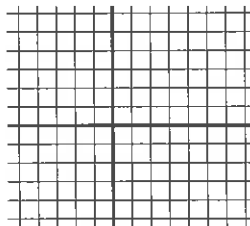
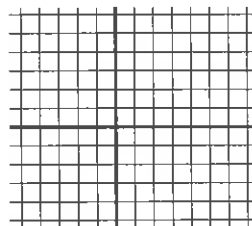


Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in the

t, x_1 -plane

t, x_2 -plane

x_1, x_2 -plane



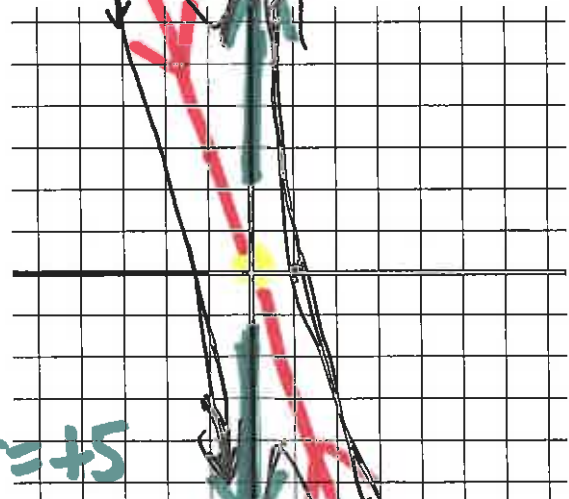
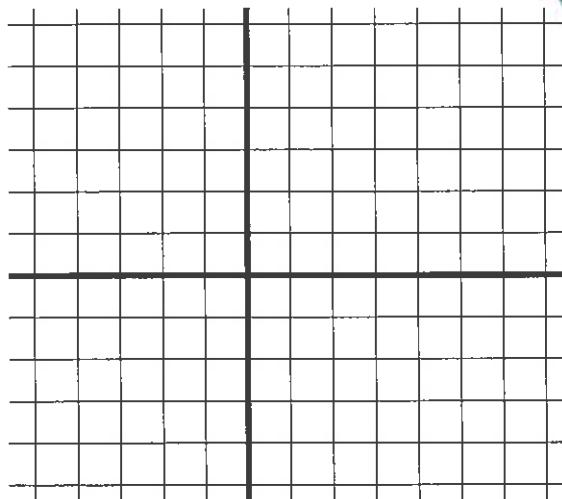
The equilibrium solution for this system of equations is $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$

$\frac{dx_2}{dx_1} =$ _____

$\begin{bmatrix} -1 \\ 3 \end{bmatrix} \rightarrow$ slope $3/-1$
 $r = -2$

Plot several direction vectors where the slope is 0 and where slope is vertical.

Graph several trajectories.



Saddle

$r = +5$

$\begin{bmatrix} 0 \\ 1 \end{bmatrix} \rightarrow$ slope $1/0$

$c_1 = c_2 = 0 \Rightarrow \vec{x} = 0$

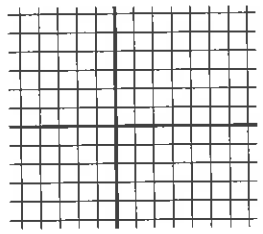
Give that the solution to $\mathbf{x}' = \begin{bmatrix} -2 & 0 \\ 21 & 5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$

$\frac{x_2}{x_1} = \frac{1}{0} \Rightarrow x_2 = \frac{1}{0} x_1$

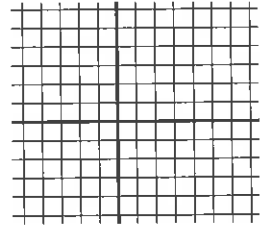
$\frac{x_2}{x_1} = \frac{3}{-1} \Rightarrow x_2 = \frac{3}{-1} x_1$

Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ in the

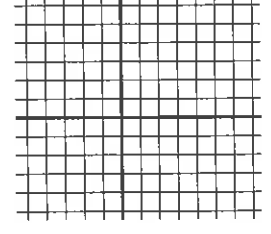
t, x_1 -plane



t, x_2 -plane

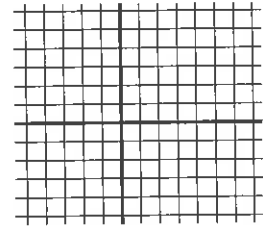


x_1, x_2 -plane

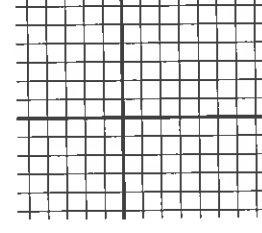


Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in the

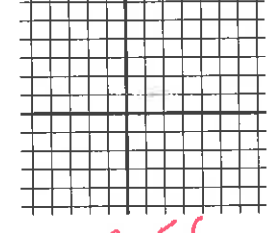
t, x_1 -plane



t, x_2 -plane



x_1, x_2 -plane

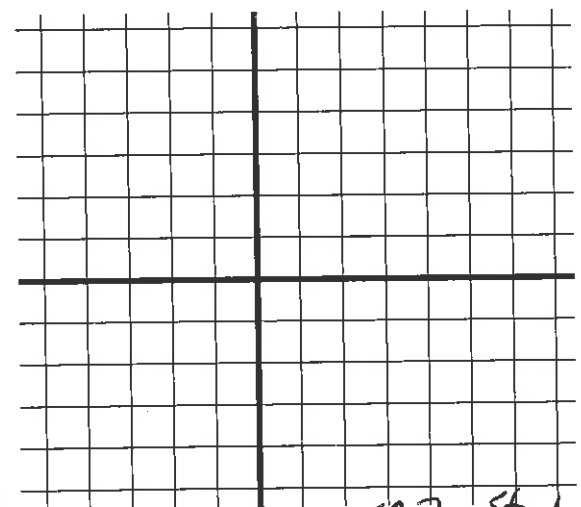


The equilibrium solution for this system of equations is $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

$\frac{dx_2}{dx_1} = \underline{\hspace{2cm}}$

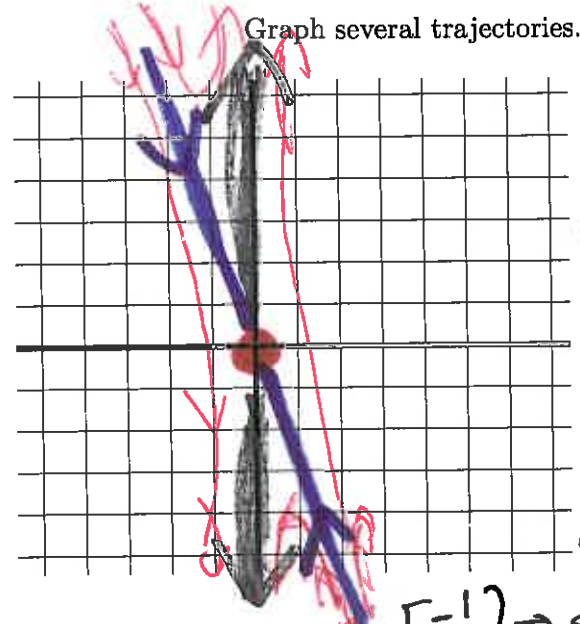
$\begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} \leftarrow$ positive e-value goes always from
 $\begin{bmatrix} 0 \\ 1 \end{bmatrix} \rightarrow$ slope $\frac{1}{0}$

Plot several direction vectors where the slope is 0 and where slope is vertical.



$t \rightarrow \infty \Rightarrow \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t}$ dominates
 $t \rightarrow -\infty \Rightarrow \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$ dominates

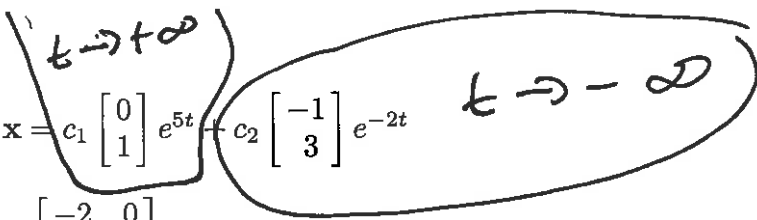
Graph several trajectories.



Saddle
 $\begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t} \rightarrow$ slope $\frac{3}{-1}$
 negative e-value \Rightarrow goes to 0

Case

The solution to $\mathbf{x}' = \begin{bmatrix} -2 & 0 \\ 21 & 5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$



Answer the following questions for $A = \begin{bmatrix} -2 & 0 \\ 21 & 5 \end{bmatrix}$:

The smaller eigenvalue of A is $r_1 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_1 is $\mathbf{v} =$

The larger eigenvalue of A is $r_2 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_2 is $\mathbf{w} =$

The general solution to $\mathbf{x}' = A\mathbf{x}$ is

case: $c_1 \neq 0$ and $c_2 \neq 0$

$t \rightarrow +\infty$

For large **positive** values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{5t} > e^{-2t}$ as $t \rightarrow +\infty$

For the following problems, consider the case when $c_1 \neq 0$ and $c_2 \neq 0$ where the general solution is

$\mathbf{x} = c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t} + c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$,

For large **positive** values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large **positive** values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

* moves away from the origin. $t \rightarrow +\infty$

* moves toward the origin.

* approaches the line $y = mx$ with slope $m = \underline{1/0}$

* approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + \text{tiny}$
dominate as $t \rightarrow +\infty$

$t \rightarrow -\infty$

For large **negative** values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{5t} < e^{-2t}$ as $t \rightarrow -\infty$

For large **negative** values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large **negative** values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

* moves away from the origin. $t \rightarrow -\infty$

* moves toward the origin. $t \rightarrow +\infty$

* approaches the line $y = mx$ with slope $m = \underline{3/4}$

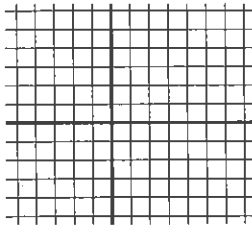
* approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

tiny + $c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$

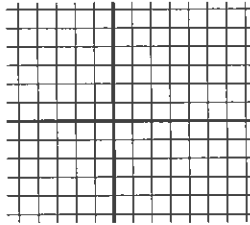
Give that the solution to $\mathbf{x}' = \begin{bmatrix} -2 & 0 \\ -9 & -5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{-5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$

Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ in the

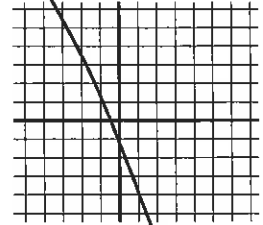
t, x_1 -plane



t, x_2 -plane

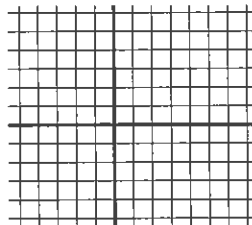


x_1, x_2 -plane

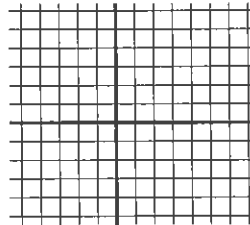


Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in the

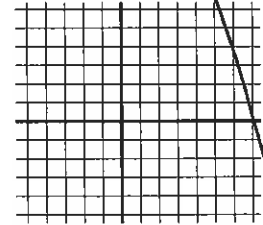
t, x_1 -plane



t, x_2 -plane



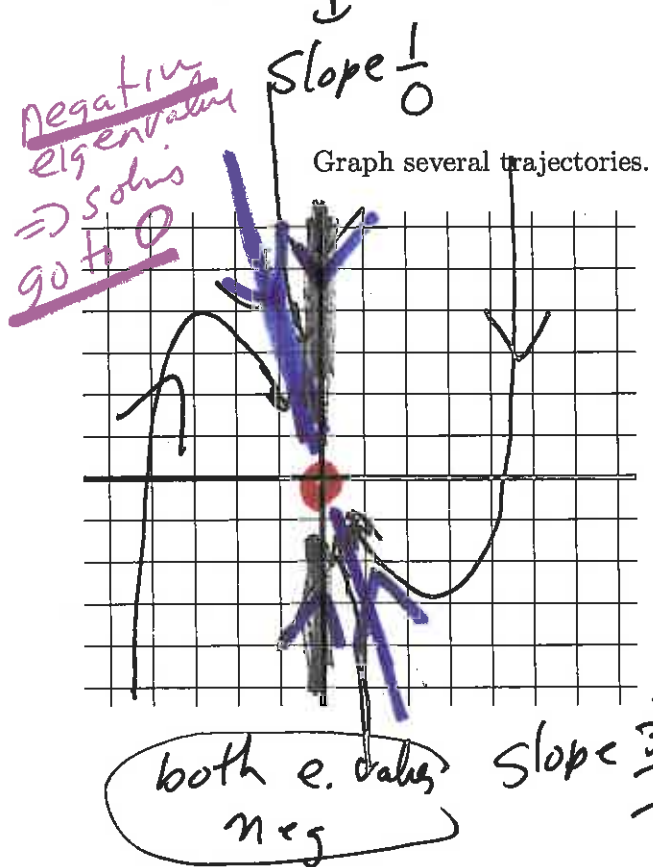
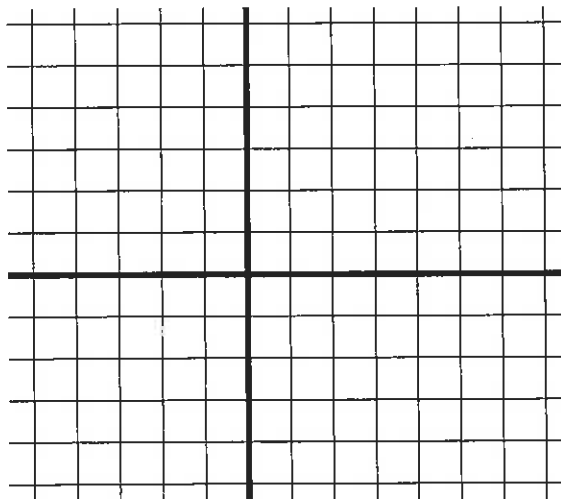
x_1, x_2 -plane



The equilibrium solution for this system of equations is $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

$\frac{dx_2}{dx_1} = \underline{\hspace{2cm}}$

Plot several direction vectors where the slope is 0 and where slope is vertical.



the solution to $\mathbf{x}' = \begin{bmatrix} -2 & 0 \\ -9 & -5 \end{bmatrix} \mathbf{x}$ is

$\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{-5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$ *dominant as $t \rightarrow +\infty$*

Answer the following questions for $A = \begin{bmatrix} -2 & 0 \\ -9 & -5 \end{bmatrix}$:

The smaller eigenvalue of A is $r_1 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_1 is $\mathbf{v} = \underline{\hspace{2cm}}$

The larger eigenvalue of A is $r_2 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_2 is $\mathbf{w} = \underline{\hspace{2cm}}$

The general solution to $\mathbf{x}' = A\mathbf{x}$ is

Case for when $c_1 \neq 0, c_2 \neq 0$

$t \rightarrow +\infty$

For large positive values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{-5t} < e^{-2t}$ as $t \rightarrow +\infty$

For the following problems, consider the case when $c_1 \neq 0$ and $c_2 \neq 0$ where the general solution is

$\mathbf{x} = c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t} + c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$,

For large positive values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large positive values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

- * moves away from the origin.
- * moves toward the origin. $t \rightarrow +\infty$
- * approaches the line $y = mx$ with slope $m = \underline{3/-1}$
- * approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{NA}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$\text{tiny} + c_1 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$
 \swarrow no displacement

$t \rightarrow -\infty$

For large negative values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{-5t} > e^{-2t}$ as $t \rightarrow -\infty$

For large negative values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large negative values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

- * moves away from the origin.
- * moves toward the origin. $t \rightarrow -\infty$
- * approaches the line $y = mx$ with slope $m = \underline{NA}$
- * approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{-5t} + \text{big}$
 \swarrow 1/0 displacement

$as t \rightarrow -\infty$

the solution to $\mathbf{x}' = \begin{bmatrix} -2 & 0 \\ -9 & -5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{-5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t}$ $as t \rightarrow +\infty$

Answer the following questions for $A = \begin{bmatrix} -2 & 0 \\ -9 & -5 \end{bmatrix}$:

The smaller eigenvalue of A is $r_1 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_1 is $\mathbf{v} =$

The larger eigenvalue of A is $r_2 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_2 is $\mathbf{w} =$

The general solution to $\mathbf{x}' = A\mathbf{x}$ is

Case for when $c_1 \neq 0, c_2 \neq 0$

$as t \rightarrow +\infty$

For large positive values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{-5t} < e^{-2t}$ ← but both small

For the following problems, consider the case when $c_1 \neq 0$ and $c_2 \neq 0$ where the general solution is

$\mathbf{x} = c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t} + c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$

For large positive values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large positive values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

- * moves away from the origin.
- * moves toward the origin. $as t \rightarrow +\infty$
- * approaches the line $y = mx$ with slope $m = \underline{3/-1}$
- * approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{NA}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$tiny + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{-2t} + \text{circle}$

$as t \rightarrow -\infty$

For large negative values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{-5t} \gg e^{-2t}$ ← but both large

For large negative values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large negative values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

* moves away from the origin. $as t \rightarrow -\infty$

* ~~moves toward the origin $as t \rightarrow +\infty$~~

* approaches the line $y = mx$ with slope $m = \underline{NA}$

* approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{1/0}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

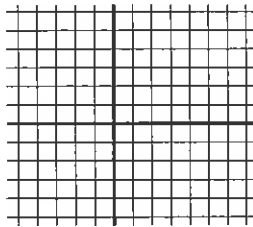
$c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{-5t} + \text{big}$

will be "parallel" to $\frac{1}{0}$

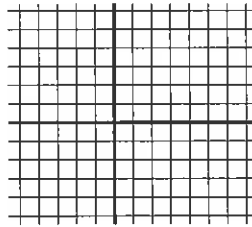
Give that the solution to $\mathbf{x}' = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$

Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ in the

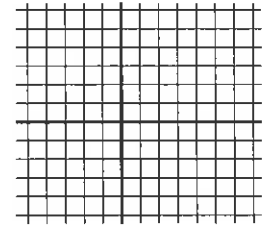
t, x_1 -plane



t, x_2 -plane

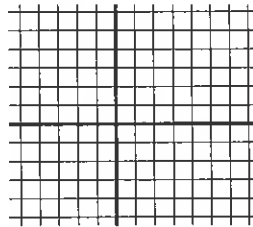


x_1, x_2 -plane

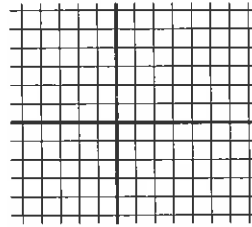


Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in the

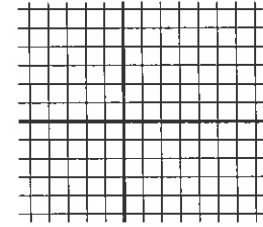
t, x_1 -plane



t, x_2 -plane



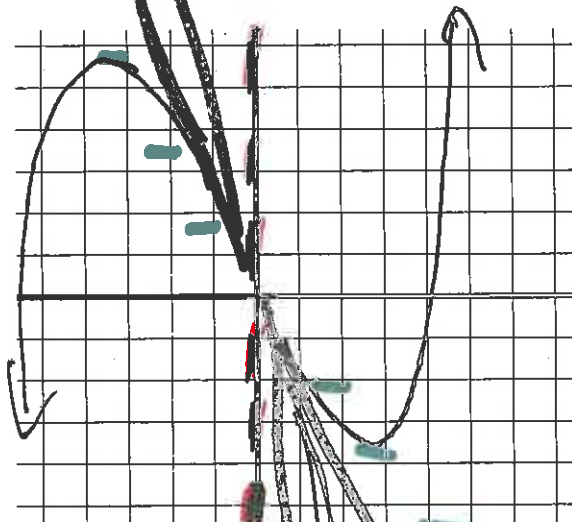
x_1, x_2 -plane



The equilibrium solution for this system of equations is $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

$$\frac{dx_2}{dx_1} = \frac{9x_1 + 5x_2}{2x_1}$$

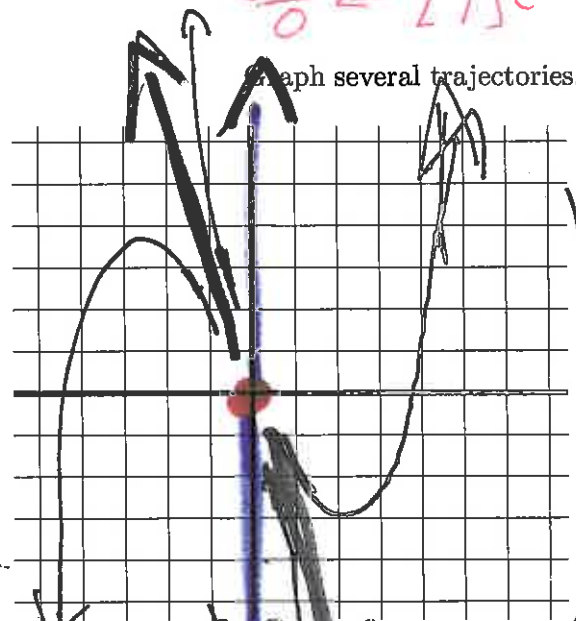
Plot several direction vectors where the slope is 0 and where slope is vertical.



slope 0
 $x_2 = -\frac{9x_1}{5}$

slope ∞
 $x_1 = 0$

Graph several trajectories.



positive exp

$\frac{3}{-1} \leftarrow \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$

$\frac{1}{0} \leftarrow \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t}$

both e. values

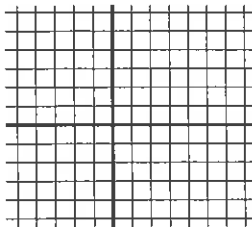
Give that the solution to $\mathbf{x}' = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$

$$x_2 = \frac{1}{0} x_1$$

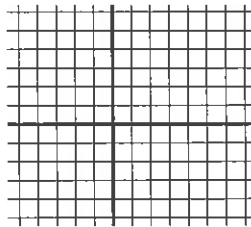
$$x_2 = \frac{3}{-1} x_1$$

Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ in the

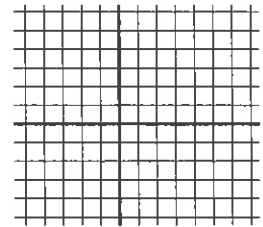
t, x_1 -plane



t, x_2 -plane

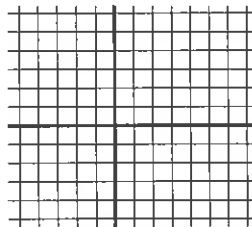


x_1, x_2 -plane

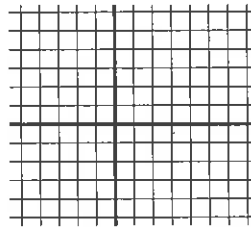


Graph the solution to the IVP $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in the

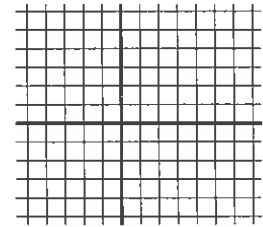
t, x_1 -plane



t, x_2 -plane



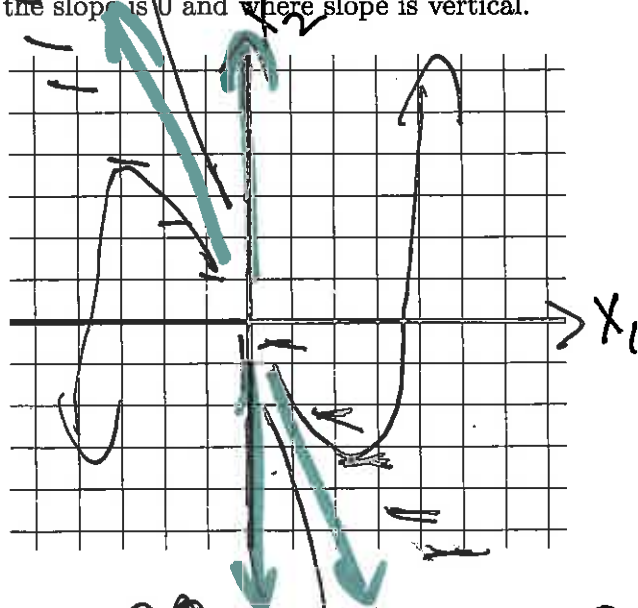
x_1, x_2 -plane



The equilibrium solution for this system of equations is $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\frac{dx_2}{dx_1} = \frac{9x_1 + 5x_2}{2x_1}$$

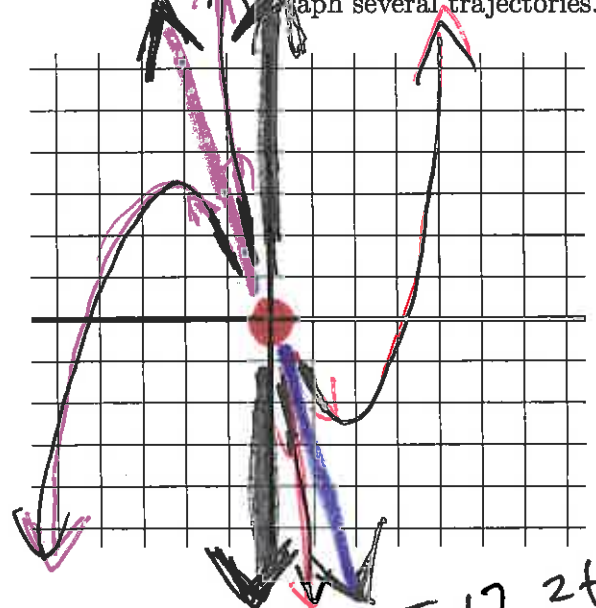
Plot several direction vectors where the slope is 0 and where slope is vertical.



$$\text{slope } 0: -\frac{9x_1}{5x_2}$$

$$\text{slope } \infty: x_2 = 0$$

e^{2t} dominant as $t \rightarrow -\infty$
 $\begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t}$
 $r = +5$
 Graph several trajectories.



$$\begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$$

$$r = +2$$

the solution to $\mathbf{x}' = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$ as $t \rightarrow -\infty$

$t \rightarrow +\infty$
 $\begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t}$ dominates
 $\begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$ dominates

Answer the following questions for $A = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix}$:

The smaller eigenvalue of A is $r_1 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_1 is $\mathbf{v} =$

The larger eigenvalue of A is $r_2 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_2 is $\mathbf{w} =$

The general solution to $\mathbf{x}' = A\mathbf{x}$ is

case: $c_1 \neq 0$ and $c_2 \neq 0$

$t \rightarrow +\infty$

For large positive values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{5t} > e^{2t}$ as $t \rightarrow +\infty$

For the following problems, consider the case when $c_1 \neq 0$ and $c_2 \neq 0$ where the general solution is

$$\mathbf{x} = c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t} + c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t},$$

For large positive values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large positive values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

* moves away from the origin. $t \rightarrow +\infty$

* moves toward the origin.

* approaches the line $y = mx$ with slope $m = \underline{\hspace{2cm}}$

* approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + \text{big}$
 \swarrow NA
 \searrow 1/0
 displaced from $c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t}$ but exhibit similar behavior

$t \rightarrow -\infty$

For large negative values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$?

$e^{5t} < e^{2t}$ as $t \rightarrow -\infty$

For large negative values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large negative values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

* moves away from the origin.

* moves toward the origin. $t \rightarrow -\infty$

* approaches the line $y = mx$ with slope $m = \underline{\hspace{2cm}}$

* approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

tiny + $c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$
 \swarrow 3/-1
 NA

the solution to $\mathbf{x}' = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix} \mathbf{x}$ is $\mathbf{x} = c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$ $t \rightarrow -\infty$

Answer the following questions for $A = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix}$:

The smaller eigenvalue of A is $r_1 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_1 is $\mathbf{v} =$

The larger eigenvalue of A is $r_2 = \underline{\hspace{2cm}}$. An eigenvector corresponding to r_2 is $\mathbf{w} =$

The general solution to $\mathbf{x}' = A\mathbf{x}$ is

case: $c_1 \neq 0$ and $c_2 \neq 0$

$t \rightarrow +\infty$
For large **positive** values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$? $e^{5t} > e^{2t}$

For the following problems, consider the case when $c_1 \neq 0$ and $c_2 \neq 0$ where the general solution is $\mathbf{x} = c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t} + c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$,

For large **positive** values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$?

Thus for large **positive** values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

- * moves away from the origin. $t \rightarrow +\infty$
- * moves toward the origin.
- * approaches the line $y = mx$ with slope $m = \underline{\hspace{2cm}}$
- * approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$c_1 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{5t} + \text{big}$
huge
displaced by big
"parallel" to $y = \frac{1}{3}x$

$t \rightarrow -\infty$
For large **negative** values of t which is larger: $e^{r_1 t}$ or $e^{r_2 t}$? $e^{5t} < e^{2t}$ for negative value

For large **negative** values of t , which term dominates: $c_1 \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} e^{r_1 t}$ or $c_2 \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} e^{r_2 t}$? $t \rightarrow -\infty$

Thus for large **negative** values of t , such trajectories (where $c_1 c_2 \neq 0$) when projected into the x_1, x_2 plane exhibit the following behavior (select all that apply):

- * moves away from the origin. $t \rightarrow +\infty$
- * moves toward the origin. $t \rightarrow -\infty$
- * approaches the line $y = mx$ with slope $m = \underline{\hspace{2cm}}$
- * approaches a line $y = mx + b$ for $b \neq 0$ with slope $m = \underline{\hspace{2cm}}$. Note this case corresponds to where both $\|c_1 \mathbf{v}\| e^{r_1 t}$ and $\|c_2 \mathbf{w}\| e^{r_2 t}$ are large, but one is significantly larger than the other.

$c_1 (1, 1) + c_2 \begin{bmatrix} -1 \\ 3 \end{bmatrix} e^{2t}$
 $\lim_{t \rightarrow -\infty} e^{2t} = 0$

Slope field

$$\begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 9 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 9x_1 + 5x_2 \end{bmatrix}$$

$$x_1' = \frac{dx_1}{dt} = 2x_1$$

$$x_2' = \frac{dx_2}{dt} = 9x_1 + 5x_2$$

$$\frac{dx_2}{dx_1} = \frac{dx_2}{dt} \cdot \frac{dt}{dx_1} = \frac{dx_2/dt}{dx_1/dt}$$

$$\frac{dx_2}{dx_1} = \frac{9x_1 + 5x_2}{2x_1}$$

slope 0

$$9x_1 + 5x_2 = 0$$

$$x_2 = -\frac{9x_1}{5}$$

slope ∞

$$2x_1 = 0$$

$$x_1 = 0$$