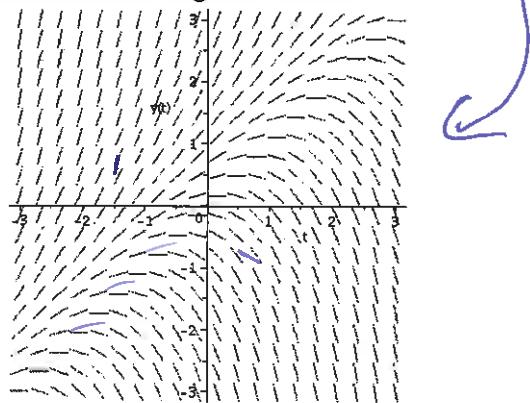


$$y' = f(t, y)$$

4.) Circle the general solution to the differential equation whose direction field is given below:

- | | |
|----------------------|-----------------------|
| A) $y = t + C$ | B) $y = t^2 + C$ |
| C) $y = e^t + C$ | D) $y = Ce^t + t + 1$ |
| E) $y = Ce^t$ | F) $y = e^t + t + C$ |
| G) $y = \ln(t) + C$ | H) $y = C$ |
| I) $y = \sin(t) + C$ | J) $y = \cos(t) + C$ |



5.) Which of the following could be the general solution to the differential equation whose direction field is given below:

- | | |
|-------------------------|--------------------------------|
| A) $y = t + C$ | B) $y = t^2 + C$ |
| C) $y = e^t + C$ | D) $y = \frac{(t-1)^3}{3} + C$ |
| E) $y = Ce^t$ | F) $y = \frac{t^3}{3} + C$ |
| G) $y = \ln(t) + C$ | H) $y = C$ |
| I) $y = \frac{Ct^3}{3}$ | J) $y = \frac{C(t-1)^3}{3}$ |

$$y' = f(t)$$

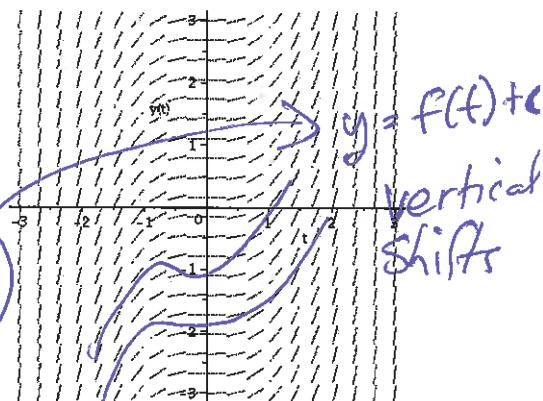
$$D) y = \frac{(t-1)^3}{3} + C$$

$$F) y = \frac{t^3}{3} + C$$

$$H) y = C$$

$$J) y = \frac{C(t-1)^3}{3}$$

*Calc 1
problem*



6.) Circle the differential equation whose direction field is given below:

- | | |
|--|--|
| A) $y' = t^2$ | B) $y' = y + 3$ |
| C) $y' = e^t$ | D) $y' = t + 1$ |
| E) $y' = t - y$ | F) $y' = y - t$ |
| G) $y' = (1+y)(1-y)$ | H) $y' = y(1+y)$ |
| I) $y' = t(1-t)$ | J) $y' = y(1-y)$ |

y = 1 stable

y = 0 unstable

~~$B) y' = y + 3$~~

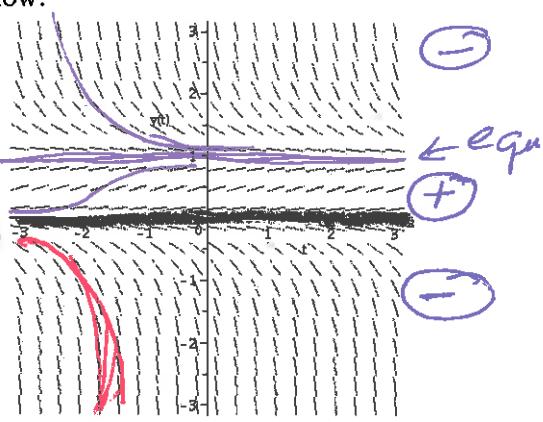
~~$D) y' = t + 1$~~

~~$F) y' = y - t$~~

~~$H) y' = y(1+y)$~~

~~$I) y' = t(1-t)$~~

$$J) y' = y(1-y)$$



$$y' = f(y)$$

2.5 * Autonomus DE

2.8

~~initial value will be $y(0) = 0$~~

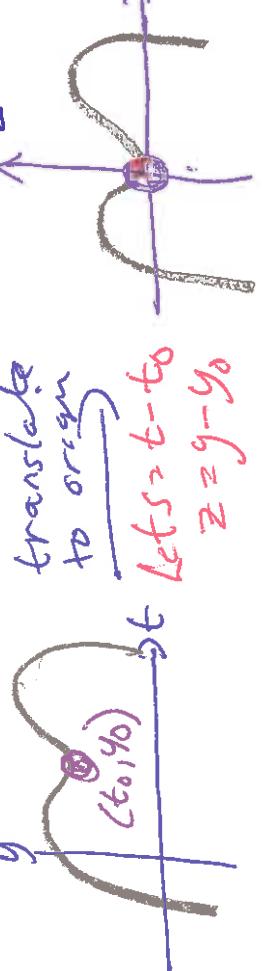
2.8: Approximating solution using

Method of Successive Approximation

(also called Picard's iteration method).

$$\text{IVP: } y' = f(t, y), y(t_0) = y_0.$$

Note: Can always translate IVP to move initial value to the origin and translate back after solving:



Hence for simplicity in section 2.8, we will assume initial value is at the origin: $y' = f(t, y), y(0) = 0$.

Theorem 2.4.2: Suppose the functions

$z = f(t, y)$ and $z = \frac{\partial f}{\partial y}(t, y)$ are continuous on $(a, b) \times (c, d)$ and the point $(t_0, y_0) \in (a, b) \times (c, d)$, then there exists an interval $(t_0 - h, t_0 + h) \subset (a, b)$ such that there exists a unique function $y = \phi(t)$ defined on $(t_0 - h, t_0 + h)$ that satisfies the following initial value problem:

$$y' = f(t, y), y(t_0) = y_0.$$

1

Theorem 2.8.1 is translated to origin version of Thm 2.4.2:

Theorem 2.8.1: Suppose the functions

$z = f(t, y)$ and $z = \frac{\partial f}{\partial y}(t, y)$ are continuous for all t in $(-a, a) \times (-c, c)$,

then there exists an interval $(-h, h) \subset (-a, a)$ such that there exists a unique function $y = \phi(t)$ defined on $(-h, h)$ that satisfies the following initial value problem:

$$y' = f(t, y), y(0) = 0.$$

Given: $y' = f(t, y), y(0) = 0$ Eqn (*)

$f, \frac{\partial f}{\partial y}$ continuous $\forall (t, y) \in (-a, a) \times (-b, b)$.

Then $y = \phi(t)$ is a solution to (*) iff

$$\begin{aligned} \phi'(t) &= f(t, \phi(t)), \quad \phi(0) = 0 & \text{Eqn (*)} \\ \int_0^t \phi'(s) ds &= \int_0^t f(s, \phi(s)) ds, \quad \phi(0) = 0 \end{aligned}$$

$$\phi(t) = \phi(t) - \phi(0) = \int_0^t f(s, \phi(s)) ds$$

Thus $y = \phi(t)$ is a solution to (*)

$$\text{iff } \phi(t) = \int_0^t f(s, \phi(s)) ds$$

2

Sequence of functions that approaches $\sin t$

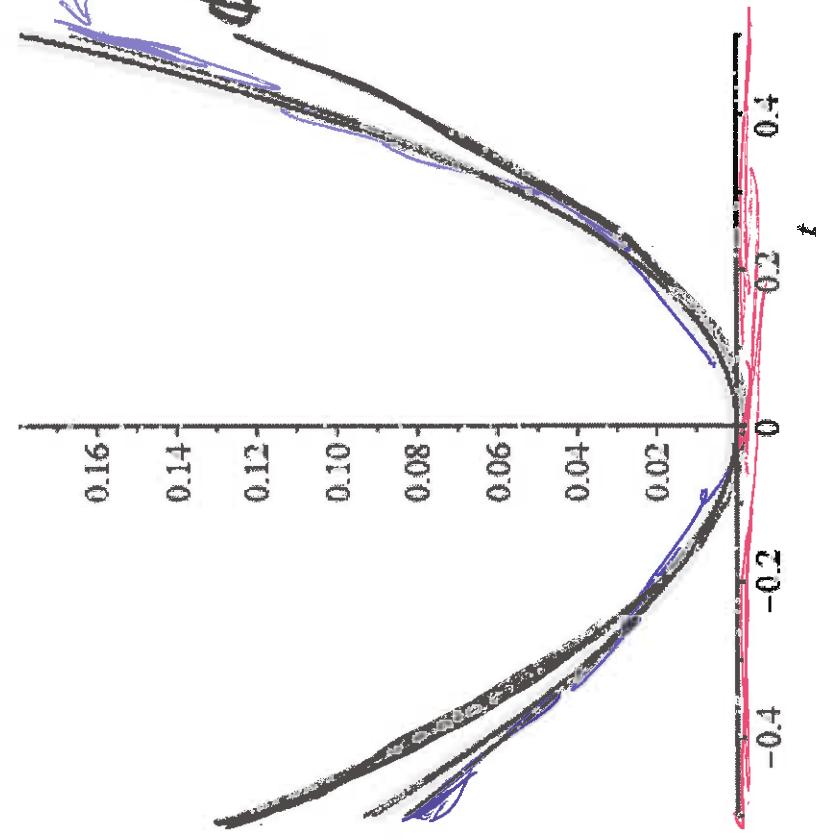
2.8: Approximating soln to IVP using seq of fns.

$$\phi_0(t) = 0, \quad \phi_1(t) = \frac{t^2}{2}, \quad \phi_2(t) = \frac{t^2}{2} + \frac{t^3}{3},$$

$$\phi_3(t) = \frac{t^2}{2} + \frac{t^3}{3} + \frac{t^4}{6}, \quad \phi_4(t) = \frac{t^2}{2} + \frac{t^3}{3} + \frac{t^4}{6} + \frac{t^5}{15}$$

2.7: Approximating soln to IVP using multiple tangent lines.

$$y(t) = \begin{cases} 0 & 0 \leq t \leq 0.1 \\ 0.1t - 0.01 & 0.1 \leq t \leq 0.2 \\ 0.22t - 0.034 & 0.2 \leq t \leq 0.3 \\ 0.364t - 0.0772 & 0.3 \leq t \leq 0.4 \\ 0.5328t - 0.14672 & 0.4 \leq t \leq 0.5 \end{cases}$$



7

8

Solve
of
first
order
equations

$$y' = f(x, y)$$

Construct ϕ using method of successive approximation – also called Picard's iteration method.

Let $\phi_0(t) = 0$ (or the function of your choice)

$$\text{Let } \phi_1(t) = \int_0^t f(s, \phi_0(s)) ds$$

$$\text{Let } \phi_2(t) = \int_0^t f(s, \phi_1(s)) ds$$

$$\vdots$$

$$\text{Let } \phi_{n+1}(t) = \int_0^t f(s, \phi_n(s)) ds$$

$$\text{Let } \phi(t) = \lim_{n \rightarrow \infty} \phi_n(t)$$

To finish the proof, need to answer the following questions (see book or more advanced class):

- 1.) Does $\phi_n(t)$ exist for all n ?
- 2.) Does sequence ϕ_n converge? *use ratio test for this*
- 3.) Is $\phi(t) = \lim_{n \rightarrow \infty} \phi_n(t)$ a solution to (*).
- 4.) Is the solution unique?

Example: $y' = t + 2y$. That is $f(t, y) = t + 2y$

$$\text{Let } \phi_0(t) = 0$$

$$\text{Let } \phi_1(t) = \int_0^t f(s, 0) ds = \int_0^t (s + 2(0)) ds$$

$$= \int_0^t s ds = \frac{s^2}{2} \Big|_0^t = \frac{t^2}{2}$$

$$\text{Let } \phi_2(t) = \int_0^t f(s, \phi_1(s)) ds = \int_0^t f(s, \frac{s^2}{2}) ds$$

$$= \int_0^t (s + 2(\frac{s^2}{2})) ds = \frac{t^2}{2} + \frac{t^3}{3}$$

$$\text{Let } \phi_3(t) = \int_0^t f(s, \phi_2(s)) ds = \int_0^t f(s, \frac{s^2}{2} + \frac{s^3}{3}) ds$$

$$= \int_0^t (s + 2(\frac{s^2}{2} + \frac{s^3}{3})) ds = \frac{t^2}{2} + \frac{t^3}{3} + \frac{t^4}{6}$$

$$\text{Let } \phi_4(t) = \int_0^t f(s, \phi_3(s)) ds$$

$$= \int_0^t f(s, \frac{s^2}{2} + \frac{s^3}{3} + \frac{s^4}{6}) ds$$

$$= \int_0^t (s + 2(\frac{s^2}{2} + \frac{s^3}{3} + \frac{s^4}{6})) ds$$

$$= \frac{t^2}{2} + \frac{t^3}{3} + \frac{t^4}{6} + \frac{t^5}{15}$$

:

*claim the step by step
is true in
just one*

$$\phi_n(t) =$$

Take limit as $n \rightarrow \infty$ for arbitrary t